Automation and Motion Control

PROGRAMMABLE AUTOMATION SOLUTIONS

KOLLMORGEN®

Because Motion Matters™

Kollmorgen: Your partner. In Motion.

Every solution comes from a real understanding of the challenges facing machine designers and users.

Innovators consistently rate Kollmorgen as one of their best motion systems manufacturing partners. Whether you are looking for classic servo motors, direct-drive servo motors, stepper motors, drives & amplifiers, gearing, actuation, or multi-axis motion controllers, Kollmorgen is one of the few companies in the world who actually designs and manufactures all of these products.

Our customers are leaders in many industries such as Aerospace & Defense, Printing, Packaging & Converting, Food & Beverage Processing, Medical Imaging, In Vitro Diagnostics & Laboratory Automation, Pharmaceutical Manufacturing, Material Forming and Cutting, Oil & Gas, and Robotics. Kollmorgen is also a leader in Warehouse Automation, including complete AGV systems, software, awareness and autonomy.

Our Automation Solutions can be found on Mars and in space, ships and submarines, O&G drilling and metrology, surgical robots and laser eye surgery, even inside artificial hearts. These are just a few applications that demand high-performance and high-quality while satisfying their specific needs.

Because motion matters, it's our focus: Motion can distinctly differentiate a machine and deliver a marketplace advantage by increasing its performance and dramatically improving overall equipment effectiveness (OEE).

High-performance motion can make your customer's machine more reliable and energy-efficient, enhance accuracy and improve operator safety. Motion also represents endless possibilities for innovation.

We've always understood this potential, and thus have kept motion at our core and in our Vision, Mission & Values, relentlessly developing products that offer precise control of torque, velocity and position accuracy in machines that rely on complex motion.

Removing the Barriers of Design, Sourcing, and Time

At Kollmorgen, we know that OEM engineers can achieve a lot more when obstacles aren't in the way. So, we clear obstacles in three important ways:

Integrating Standard and Custom Products

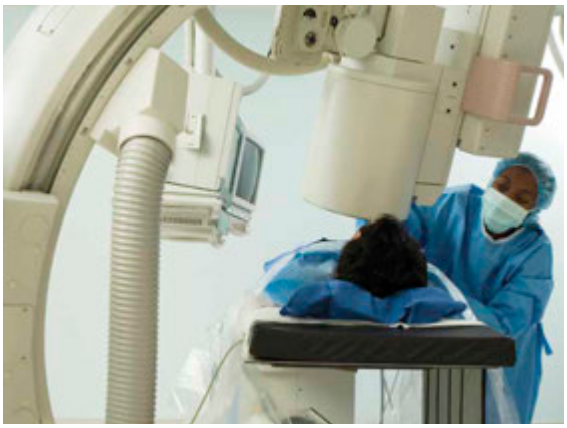
The optimal solution is often not clear-cut. Our application expertise allows us to modify standard products or develop totally custom solutions across our whole product portfolio so that designs can take flight.

Providing Motion Solutions, Not Just Components

As companies reduce their supplier base and have less engineering manpower, they need a total system supplier with a wide range of integrated solutions. Kollmorgen offers complete solutions as well as motion subsystems that combine programming software, engineering services and best-in-class motion components.

Global Footprint

With direct sales, engineering support, manufacturing facilities, and distributors spanning the Americas, Europe, the Middle East, and Asia, we're close to OEMs worldwide. Our proximity helps speed delivery and lend support where and when they're needed.



Financial and Operational Stability

Kollmorgen is part of Altra Industrial Motion. A key driver in the growth of all Altra divisions is the Altra Business System, which relies on the principle of "kaizen" – or continuous improvement. Using world-class tools, cross-disciplinary teams of exceptional people evaluate processes and develop plans that result in superior performance.

Kollmorgen: Your partner. In Motion.

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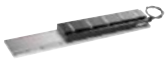

Capture, or click, any QR code throughout this catalog to access detailed product-specific selection guides, installation manuals, information, self-help tools, and support.

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Because Motion Matters™

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Automation and Motion Control

Comprehensive Line of Products Offering Complete System Solutions

Kollmorgen's comprehensive line of control software and hardware, drives and motors enables you to complete your solutions with one supplier:

Whether you want a stand-alone controller or drive-resident, Kollmorgen's Automation Suite can coordinate up to 128 axes, and synchronize the path of up to 32 axes per control engine. We offer standard languages according to IEC61131 -3, as well as C, C+, C++, C#, .NET, and our industry-leading graphical programming language, Pipe Network.

Our broad range of motor- and drive technologies and gearing and actuation products interface seamlessly with our KAS.

AKI touch panels operate and display

System programming with the Pipe-Network™ or PLCopen

PROGRAMMABLE CONTROL

Control of motors with AKD® PDMM programmable multi-axis master

The AKD® PDMM multi-axis motion controller is equipped with an AKD servo drive for direct connection to a motor. Additional axes each with their own AKD servo drive are controlled by the AKD PDMM via the system bus with the EtherCAT® protocol; extremely precise with cycle times of 250 µs. Optionally, an AKI control panel with one of the standard communication protocols can be connected for operating the machine. The AKD PDMM supports all leading bus systems and thus opens up limitless control system options. The PDMM motion controller functionality is also available in a stand-alone package, the PCMM, for machine designers that prefer traditional, independent controller hardware.

Flexible single or multi-axis drive solutions in decentralized and central architectures with AKD-PDMM and the Kollmorgen Automation Suite

AKD-C Power Supply Module

EtherCAT®

DECENTRALIZED SERVO DRIVES

AKD-N Decentralized Servo Drive

SERVO MOTORS

AKMH™ Servo Motor

Cartridge DDR® Motor

AKM® Servo Motor

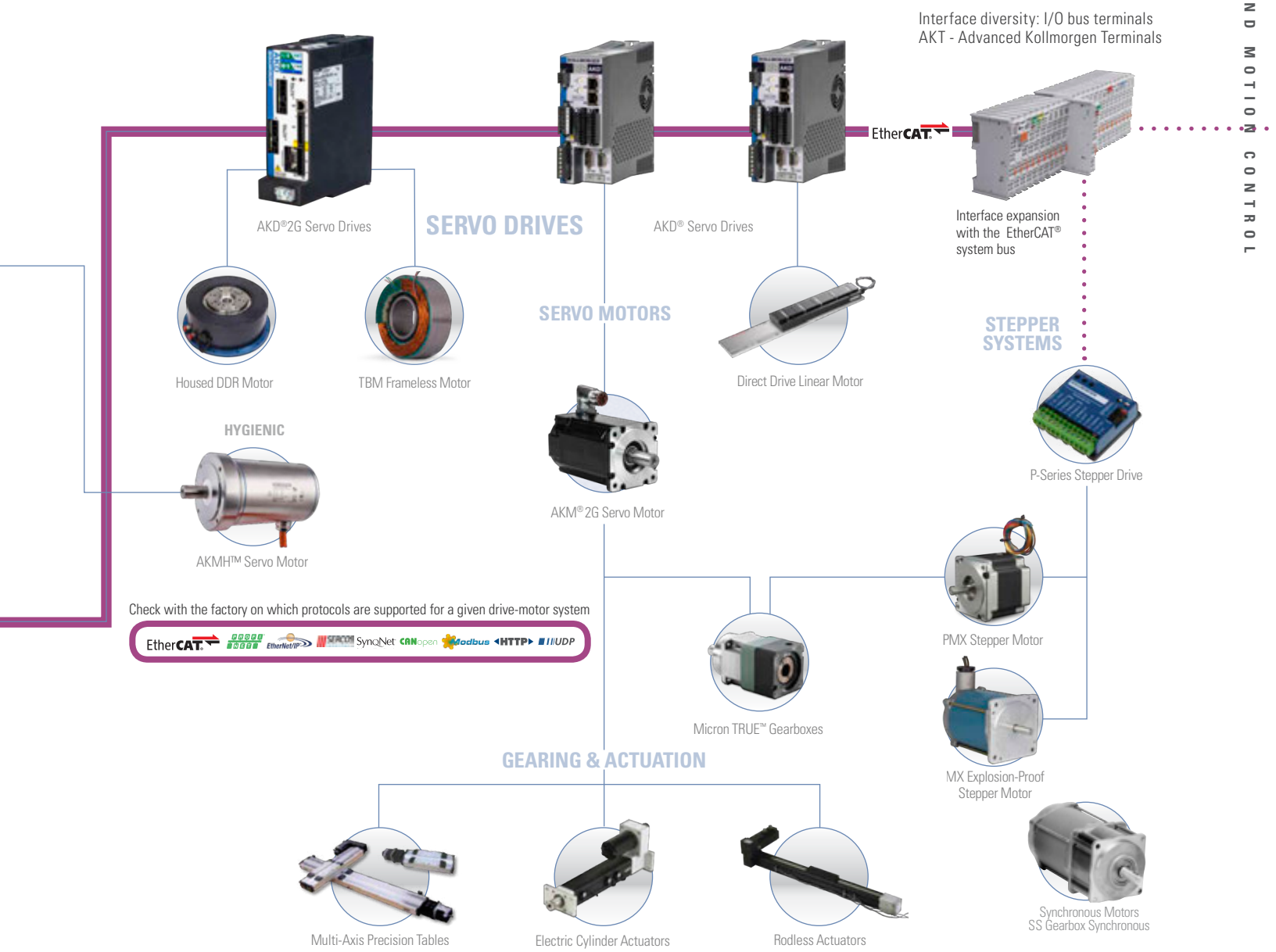
KBM Frameless Motor

Diverse and Scalable Drive Solutions

Need more axes? Different motor types? Linear direct drives here, direct drives with no housing there? No problem! With the EtherCAT® system bus you can connect more AKD servo drives and add motors of all performance classes from the Kollmorgen product range.

Interfaces are frequently the bottleneck in system design, but not so with the Kollmorgen Automation Suite (KAS). With the IO Advanced Kollmorgen Terminals (AKT) and the EtherCAT® bus coupler, you possess a flexible interface system which meets all of your requirements.

Control and monitor the processes on the machine with the AKI series touch panels. With the Kollmorgen Visualization Builder (KVB), you can program ergonomic user interfaces which guarantee safe handling and which display machine data clearly.



Kollmorgen Automation Suite™

Kollmorgen's machine automation platform dramatically simplifies how you approach the many complex automation challenges of today's machines. We have created an integrated development environment (IDE) that greatly simplifies programming and system configuration and combines multiple tools into one intuitive platform, we have global support and experienced engineering services to solve your biggest challenges, and our best-in-class automation and motion components deliver unparalleled motion performance; all of which combine to help you create a differentiated machine, get to market faster, and have the comfort and ease of collaborating with just one vendor.

Integrated Development Environment – Quickly and easily design, refine and troubleshoot all of a machine's automated solutions in this highly intuitive application featuring a single programming environment that provides great flexibility and control.

Engineering Services – A Kollmorgen representative establishes a collaborative, consultative relationship from the beginning by assessing needs and objectives. Field engineers and application engineers constantly support the design and build phase as well as the factory installation phase to ensure that your needs are met from concept to production. Additional services are available that include development, on-site deployment, and training.

Best-in-Class Automation and Motion Components – With Kollmorgen, there's security in knowing the necessary components that form the building blocks of a machine are always available. No one offers a wider range of standard, modified standard and custom products. Motion is at the core of our Automation Suite, where others in the industry consider it an add-on.

Kollmorgen Co-engineering – More than a solutions provider, we co-engineer a better fit with your company using both products and services. From a wide breadth of product modifications, over 500,000 standard options with 5-day delivery on our AKM® line, to aftermarket revenue protection and training programs, Kollmorgen co-engineering helps you differentiate your machine and business.

We accept your challenges as our own. That's the Kollmorgen co-engineering difference.

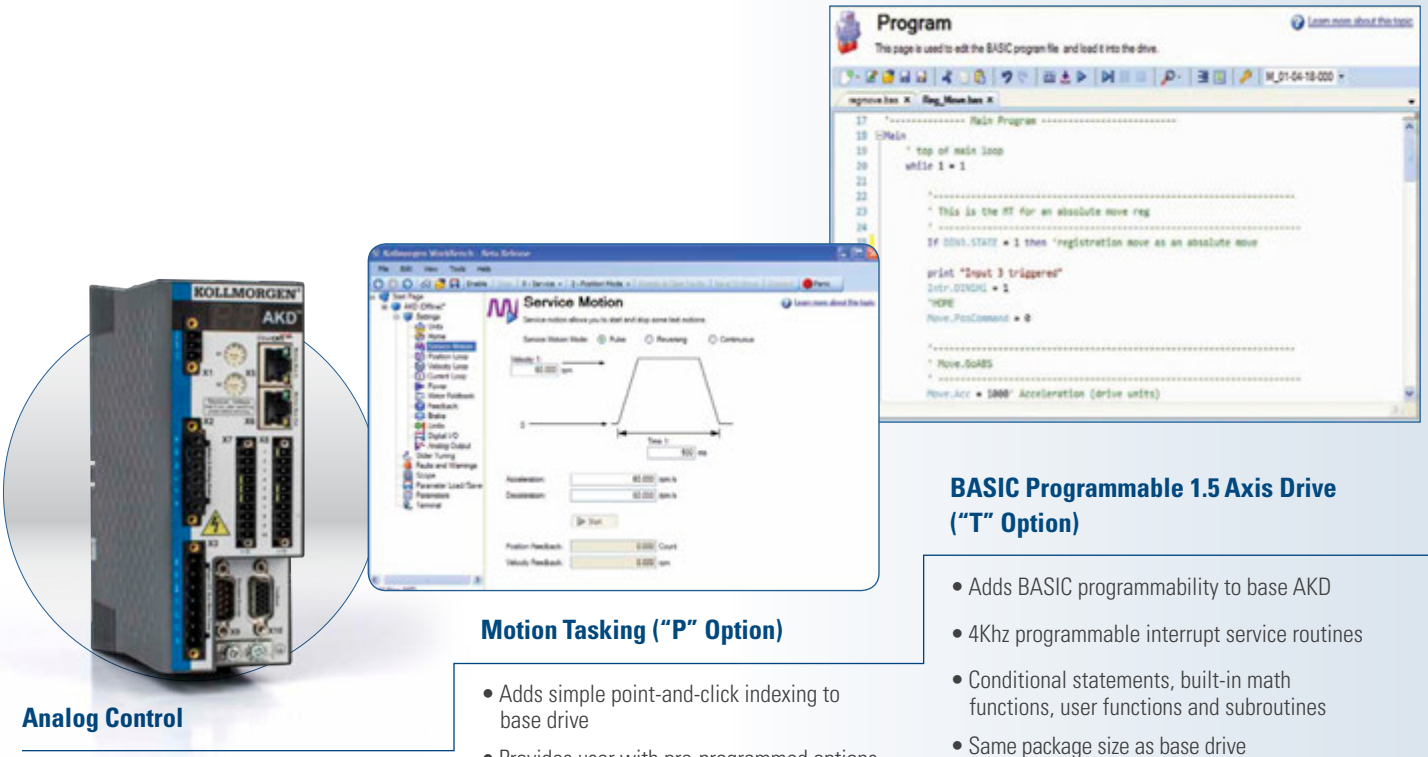
The Advantages of Kollmorgen Automation Suite™

• High machine performance	• Up to 25% greater throughput • Up to 50% scrap reduction • Improved accuracy • Advanced drive technology for machines with outstanding performance
• Fast to market	• Up to 30% reduction in development time • Services available for program development, training, start-up, and support • Industry standard programming environment and industrial networks
• Enhanced ease-of-use and integration	• Single integrated programming environment for automation, drive technology, and all hardware • Drag-and-drop motion programming • Certified components that are tested to work together • Seamless integration and configuration of amplifiers for optimal set-up
• A demonstrated solution	• The result of over 25 years of permanent optimization of programming and implementing automation and drive solutions • Provides the diverse experience of a great number of suppliers and platforms that form today's Kollmorgen • Used successfully for more than 6 years

Scalable Programmability

Kollmorgen delivers cutting-edge technology and performance with the AKD® servo drive and KAS controls platform. Whether your application requires a single axis or over 100 fully synchronized axes, Kollmorgen's intuitive software and tools scale to meet your needs. From simple analog torque control to the latest high-performance automation network, the AKD servo drive packs power and flexibility for virtually any application into one of the most compact footprints of any digital servo drive in the industry.

- Patented auto-tuning delivers optimized performance in seconds.
- 1.5MHz current loop and 16KHz velocity loops offers greater bandwidth and performance Optimized performance in seconds
- Greater throughput and accuracy
- Easy-to-use Graphical User Interface (GUI) for faster commissioning and troubleshooting
- Flexible and scalable to meet any application



Analog Control

- Controlled by analog torque-and-velocity commands
- Includes electronic gearing via X9 connector

Motion Tasking ("P" Option)

- Adds simple point-and-click indexing to base drive
- Provides user with pre-programmed options
- Guides novice user through simplified steps to create indexing moves
- Network connectivity to EtherCAT®, CANopen®, Profinet® RT, Ethernet/IP™, TCP/IP, SynqNet® and others
- MODBUS port for communication with HMI

BASIC Programmable 1.5 Axis Drive ("T" Option)

- Adds BASIC programmability to base AKD
- 4Khz programmable interrupt service routines
- Conditional statements, built-in math functions, user functions and subroutines
- Same package size as base drive
- Optional integrated SD card for easy backup and drive cloning
- Includes electronic camming functionality

RANGE OF KOLLMORGEN AUTOMATION SUITE CAPABILITIES

AKD2G Multi-Axis Drive

- Adds dual axis capability with analog, electronic gearing, step-and-direction, motion tasking and motionbus operation modes
- Adds dual channel STO for each axis
- Option to add 4 Safe Inputs and integrated SafeMotion including FSoE, SS1, SDB, SBC/SBT,etc.
- Optimized for single cable technology
- Modular design offers quicker customization means
- Improved graphical display (160x128-pixel)
- One axis variant is available

Programmable Drive Multi-Axis Master PDMM ("M" Option)

- Scalable solution for use as a single and dual-axis drives with integrated programmable automation controller
- Choose from all five IEC 61131-3 languages for soft PLC process programming
- Program motion using your choice of PLCopen for motion or our innovative Pipe Network™
- 4KHz PLC scan rate and EtherCAT® updates
- Complete line of HMI panels with integrated software to simplify GUI development
- Exclusive function blocks, such as "wait," enable your program to act as a scanning or sequential language
- Connects to AKT™ network I/O for nearly unlimited expandability

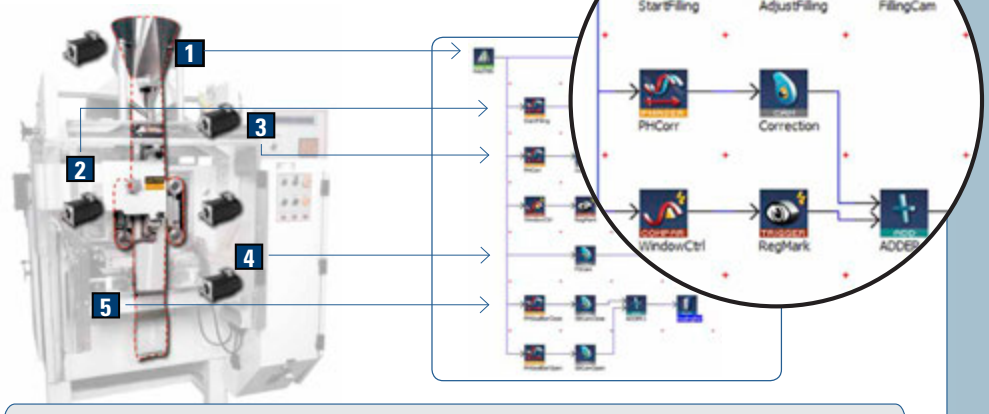
Seamlessly add additional axes and AKD PDMM serves as a high-performance multi-axis machine controller

- SD card for easy backup and system updates
- IoT-enabled integrated webserver for diagnostics and troubleshooting from any computer or mobile device
- Provide true synchronized-path control of up to 32 axes
- Reduce cabinet size and wiring requirements with a single, compact package
- Easily manage remote I/O and the I/O of all attached drives via EtherCAT®
- Use industry standard PLCopen for motion, or step up to Kollmorgen's Pipe Network™ to program sophisticated camming and gearing applications in a matter of minutes

Pipe Network™

Kollmorgen Visual Motion Programming

- Accelerate development by programming tasks in hours that would otherwise take weeks
- Improved coding quality through visual programming and by using pre-built modules that have been thoroughly tested and optimized
- Easy knowledge transfer, replacing pages of complex code with easily understood graphical representations
- Available on PDMM controllers



Pipe Network provides a one-to-one translation of a mechanical system into a logical world as shown in the Vertical Form Fill and Seal machine above. Click and build your motion program in minutes, or contact Kollmorgen for examples of common machine architectures to further accelerate your development.

Dual-Axis Programming

Multi-Axis Programming

Development

A fully integrated development environment (IDE) provides the tools you need to develop everything from PLC and motion programs to HMI and device setup – all in one place. It's easier to learn and use, eliminates the need for multiple programs and data stores, and helps you bring a higher-quality machine to market faster.

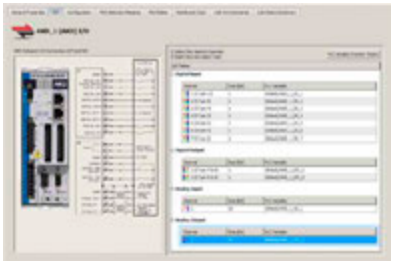
Integrated Development Environment (IDE)

· Our fully integrated programming environment incorporates standard IEC61131-3 compliant tools.
· Use our network configurator and predefined user blocks to streamline development and ensure programming quality.

Our IDE offers two powerful programming methods and a complete set of tools for simulating, testing and optimizing motion.

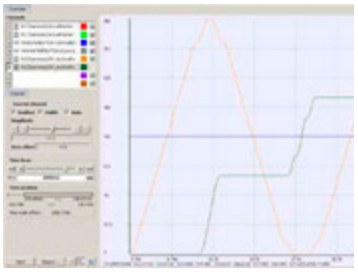
Embedded Motion

· Choose PLCopen for motion if you already use this industry standard in your existing products, and want to continue using it within the Kollmorgen Automation Suite programming environment.

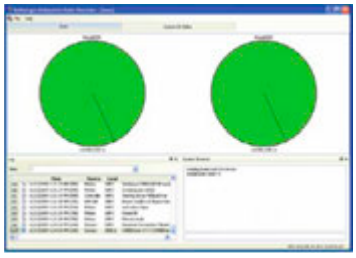


Embedded wiring diagrams and one-click IO variable mapping makes drive integration easy.

Integrated Tools



Scope motion parameters to fine-tune performance and synchronization, portrayed with up to eight channels and flexible mapping of variables.



One-click motion simulation using virtual axes alongside real axes for quick development and implementation.

Complete motion system configuration from one location with embedded AKD Workbench allows configuration of all servo drives over EtherCat®.

Pipe Network™

Kollmorgen Visual Motion Programming

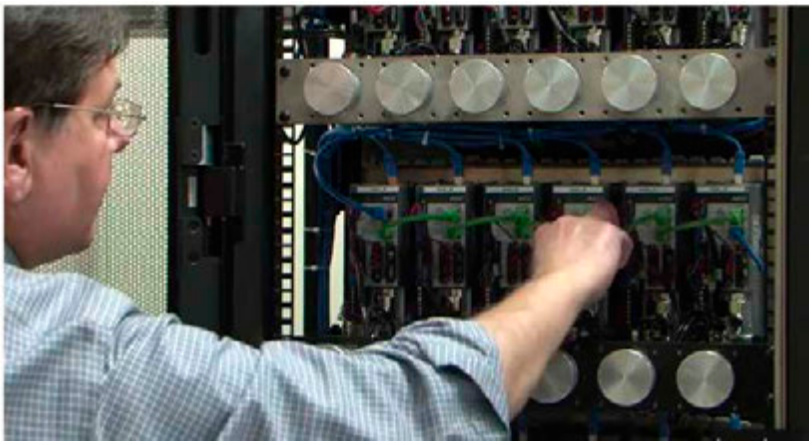
· Choose Kollmorgen's exclusive Pipe Network™ for the quickest, easiest way to represent mechanical systems in software – using drag-and-drop tools to create an intuitive visual representation.

Lifecycle

Kollmorgen is committed to helping you maximize the productivity and profitability of your machine across an extended lifecycle. Design and build today, with confidence for a full return on investment for years to come.

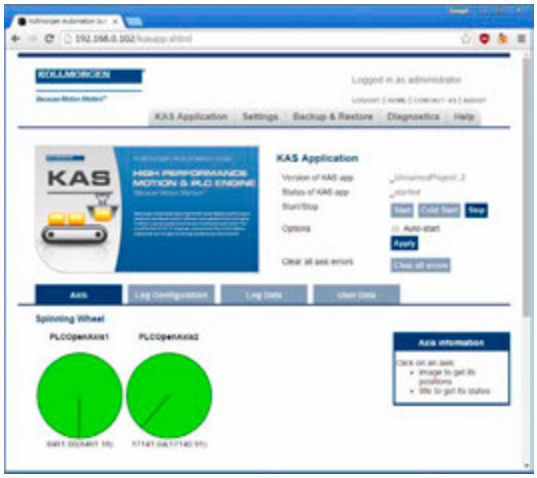
Continual Development Testing

Kollmorgen develops, tests, and continually validates all new products to ensure compatibility and performance, in the Kollmorgen ecosystem.



Maintenance Support Tools

Our tools give end-users the ability to remotely verify continuous operation and communicate issues effectively.



Built-in, mobile-ready webserver provides performance information with no software required

Software and Hardware Security

Password protection for source code and hardware connectivity provides security for both OEMs and end-users.

✓ **Protect source code**
✓ **Protect network access**

Software PLC

Easy-to-Use, Auto-Discover, Auto-Recognize, Auto-Configure, Scope, CAM, IEC 61131-3 PLC

- Kollmorgen Automation Suite™ offers a set of tools that is familiar to automation programs, but has enhancements like predefined motion blocks and visual diagnostics tools.

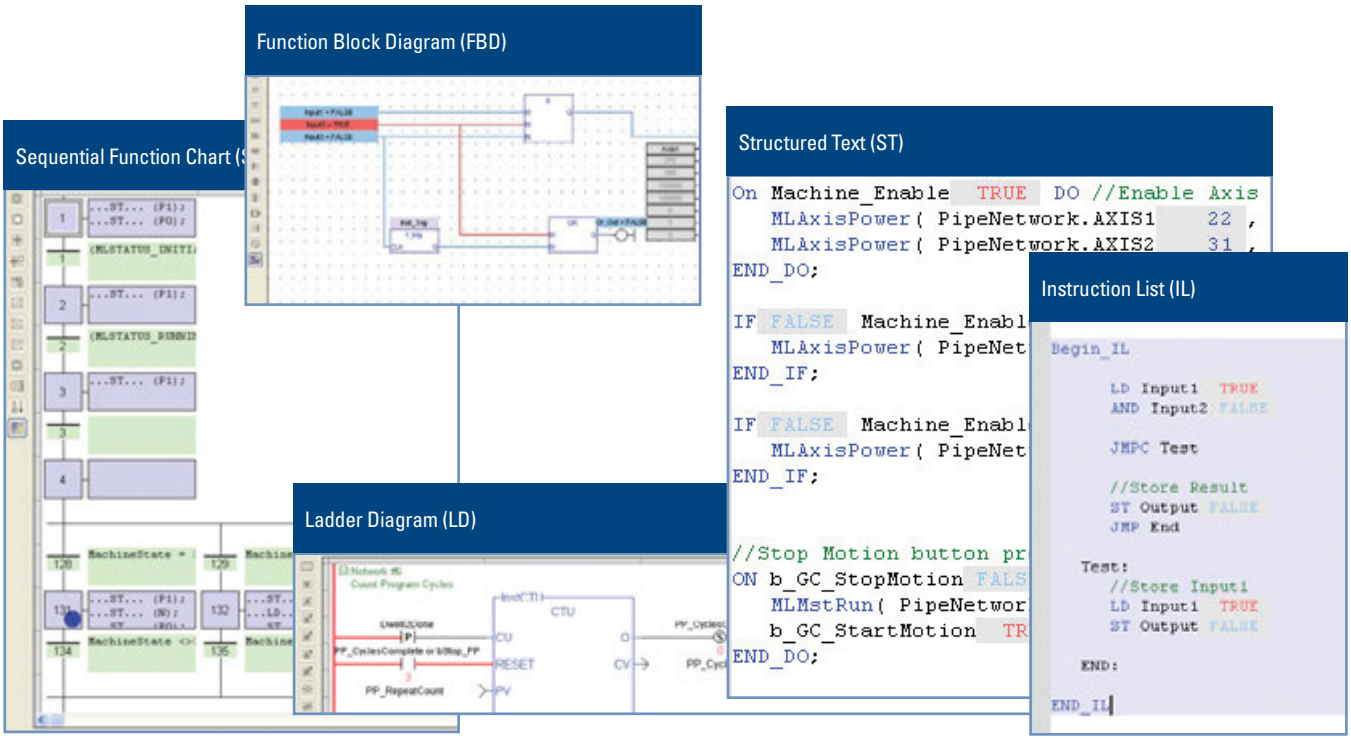
IEC 61131-3 Toolkit Features

- IEC-61131-3 engine
- Re-compile while running animated variables
- Industry and application Specific Function Blocks
- PID temperature control block
- Debugger Tools with Watch window
- 8-channel Real-Time Oscilliscope

- The environment for developing PLC programs has been created with an emphasis on speed. Recognize and configure motion control components to accelerate systems development. With auto-recognize and auto-configure features, testing efforts are reduced.

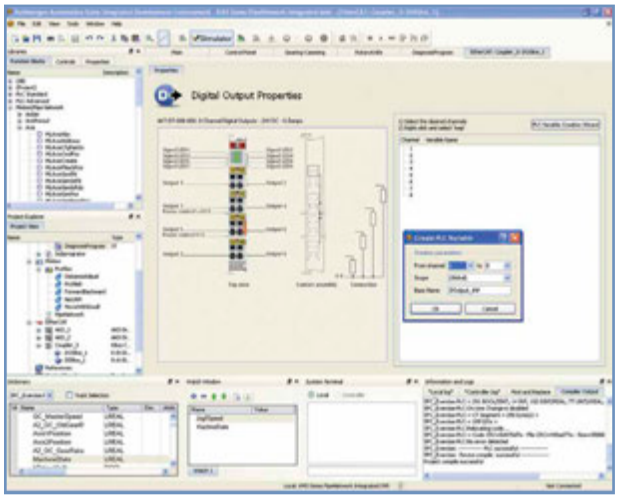
- Once an application or a function block has been created for a given application, the user can store this as a "user-defined function block" to promote reuse of tested software in subsequent projects to save time.

- Maintain your standards in corporate programming languages by using any of the IEC 61131-3 languages. In fact, enhance it further by mixing and matching languages to deliver the best solution for the application.



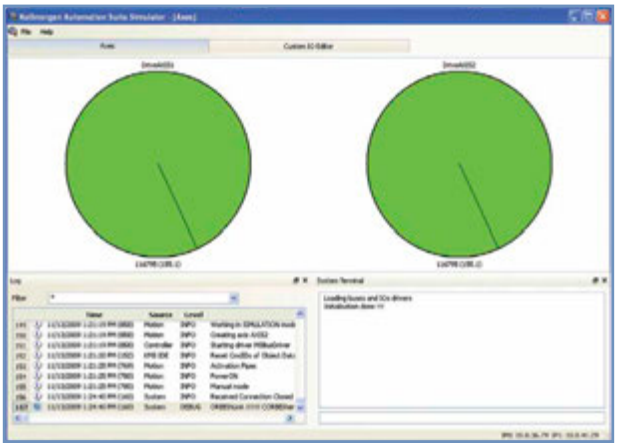
All five IEC 61131-3 PLC languages are supported

- Kollmorgen Automation Suite's integrated development environment (IDE) allows the developer to create solutions without having to connect a single device by using the offline simulator. Start creating systems before the first hardware component is delivered. Simply configure your system network in "offline development" mode and change the status of the devices one-by-one when you actually connect them.



Automatic I/O variable creation with scope definitions

Adding bus couplers with I/Os onto a motion network topology

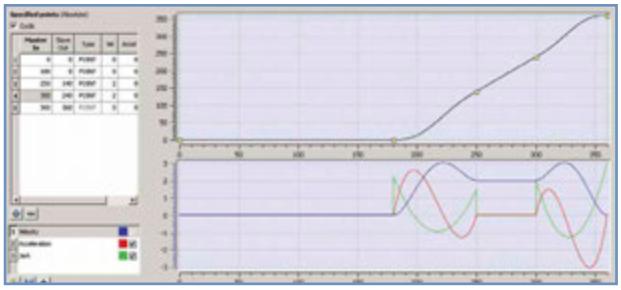


Simulator with PLC simulation and motion

- Standard debugging features like "step into", "step over", etc. are available to troubleshoot programs. In addition, debug your code using the softoscilloscope and continuously plot up to 8 variables at network update rates – the display can also be configured to suit the scale that the developer desires.

- Our CAM editor lets you create complex CAM profiles using a graphical interface. When converting, it is also possible to import existing CAM profile points into the CAM editor to allow you to seamlessly reuse your existing profiles.

- CAM-on-the-Fly lets you change CAM profiles based on network inputs or changes in machine conditions.



Graphical environment for creating CAMs

Motion Programming

Our motion control solutions are backed by Kollmorgen's vast experience solving application-specific problems for the many industries we serve. Kollmorgen Automation Suite™ offers several advantages that have helped our customers accelerate the development of more precise, high-performance motion. For example:

Superior machine synchronization, with motion-optimized runtime engine and deterministic EtherCAT® network:

· IEEE1588 distributed clock correction

· Hardware-based synchronization

· PLC code execution at EtherCAT® update rate, eliminating process delay

· Low hardware latency

Flexible profile generation, allowing problem-solving through multiple methods branching out of standard pre-packaged tools:

· Pre-loaded and user-defined motion blocks optimized for specific industries and applications

· Configurable through Pipe Network™ and PLCopen for motion

Motion Capabilities

· Absolute and incremental moves

· Jerk-limited moves (S-curve)

· CAM profiles (static or with "on-the-fly" profile changes)

· Gearing (EtherCAT® synchronized)

· Multiple high-speed registration methods (FPGA-based capture engine)

· Homing

· Tension control based motion

· Motion-based functional safety

· Superimposed moves

· Phase adjust

· Multi-axis interpolated motion

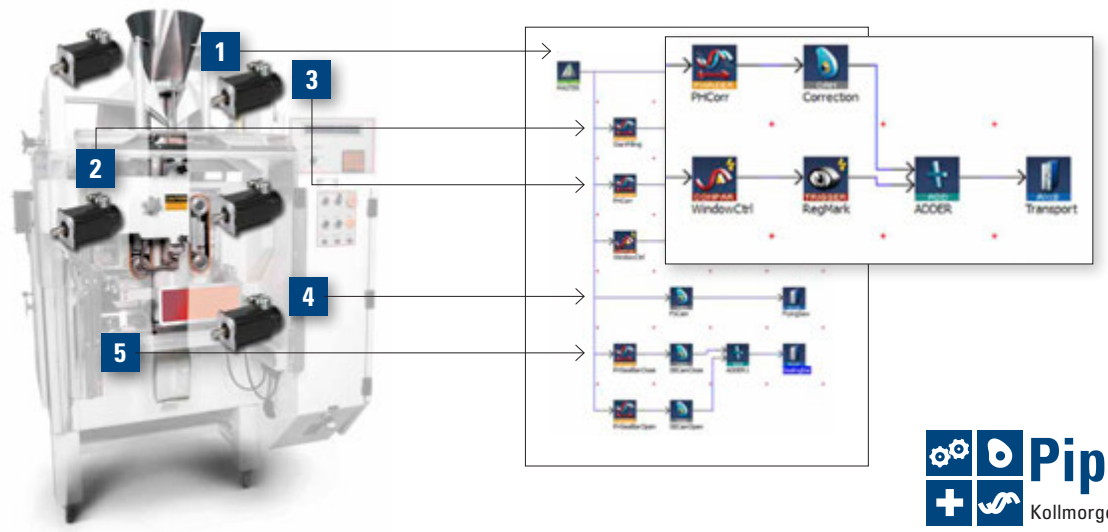
Program motion quickly and intuitively with our Pipe Network™ graphical programming language. Or choose the industry-standard PLCopen for motion to easily reuse your existing programming resources.

Pipe Network™ Visual Programming Environment

Our innovative Pipe Network™ programming environment provides a visual, drag-and-drop model of your machine's motion, including complex axis and cam relationships.

Program Tasks in Hours Instead of Weeks:

- Intuitive visual programming with a library of prebuilt modules.
- Easy knowledge transfer, replacing pages of complex code with easily understood graphical representations



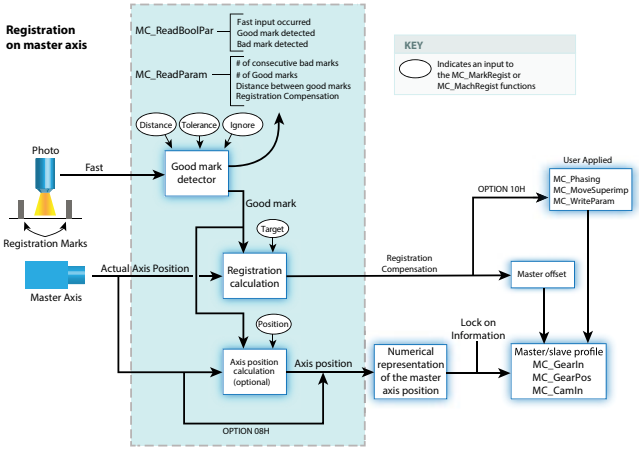
Pipe Network™ provides a one-to-one translation of mechanical systems into a logical world, so you can click and build your motion program in minutes – as shown in this example of a vertical form-fill-seal machine.

Pipe Network™
Kollmorgen Visual Motion Programming

PLCopen for Motion

The Kollmorgen Automation Suite™ IDE incorporates PLCopen for motion, a widely accepted open industry standard.

In the example shown here, PLCopen for motion is used within the Kollmorgen Automation Suite IDE to precisely control axis position based on registration marks:



AKD® PDMM Drive-Resident Controller

Build Simpler and Better with Drive-Resident Machine and Motion Control

Extend your design options. Control as many as eight axes or more without the need for a PLC or PAC. Reduce cabinet space and wiring requirements. Program perfect machine and motion control for any project using a single, fully integrated programming environment. Build a better machine at a lower cost.

Our new addition to the AKD® drive family combines one servo axis, a master controller that supports multiple additional axes, and the full automation capability of Kollmorgen Automation Suite™—all in a single, compact package.

Welcome to the AKD® PDMM programmable drive, multi-axis master.

Performance Specifications

120/240 Vac 1- and 3-Phase*	Continuous Current (Arms)	Peak Current (Arms)	H (mm/inches)	W (mm/inches)	D (mm/inches)
AKD-M00306-MxEC-0000	3	9	168 / 6.61	89 / 3.50	156 / 6.14
AKD-M00606-MxEC-0000	6	18	168 / 6.61	89 / 3.50	156 / 6.14
AKD-M01206-MxEC-0000	12	30	196 / 7.72	107 / 4.21	187 / 7.36
AKD-M02406-MxEC-0000	24	48	248 / 9.76	96 / 3.78	228 / 8.98

240/400/480 Vac 3-Phase*	Continuous Current (Arms)	Peak Current (Arms)	H (mm/inches)	W (mm/inches)	D (mm/inches)
AKD-M00307-MxEC-0000	3	9	256 / 10.08	99 / 3.90	185 / 7.28
AKD-M00607-MxEC-0000	6	18	256 / 10.08	99 / 3.90	185 / 7.28
AKD-M01207-MxEC-0000	12	30	256 / 10.08	99 / 3.90	185 / 7.28
AKD-M02407-MxEC-0000	24	48	306 / 12.05	99 / 3.90	228 / 8.98
AKD-M04807-MxEC-0000	48	96	385 / 15.16	185 / 7.28	225 / 8.85

*Where"x" = C is for the standard 800 MHz CPU and "x" = 1 is for the high performance v1.2 GHz CPU.

Features

- Kollmorgen Automation Suite™ provides fully integrated programming, testing, setup and commissioning
- Embedded web server utility simplifies service
- Control 32 axes or more* while reducing machine footprint
  - EtherCAT® multi-axis master motion controller integrated with a standard AKD® drive axis
  - Full IEC61131-3 soft PLC for machine control, with support for all 5 programming languages
  - Choice of PLCopen for motion or Pipe Network™ for programming motion control
  - 32 KB non-volatile memory stores machine data to eliminate scrap upon restart after power failure
  - SD Card slot simplifies backup and commissioning, with no PC required
  - On-board I/O includes 13 digital inputs, 4 digital outputs, 1 analog input, 1 analog output (expandable with AKT series of remote I/O)
- Works with Kollmorgen Visualization Builder for programming AKI2G human-machine interface panels

*Maximum axis count depends on motion/automation complexity and performance (8 axes nominal based on medium complexity at 4 kHz network update rate)

A Single, Scalable Development Suite

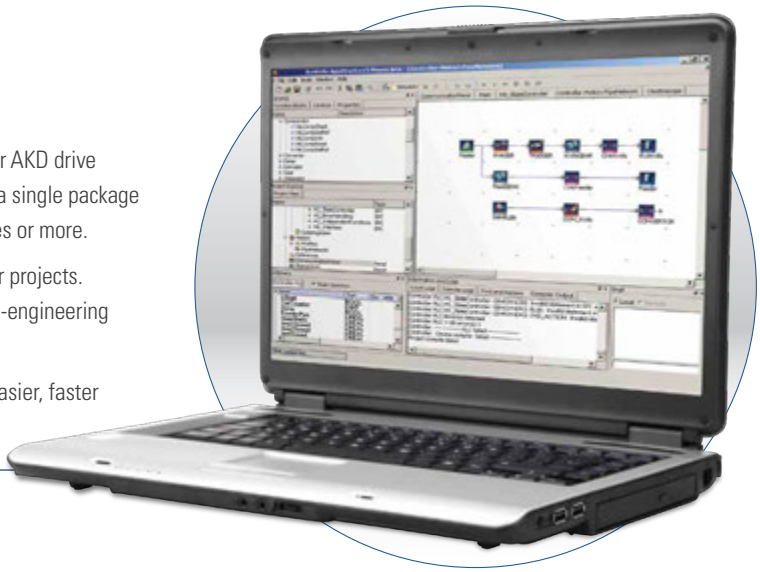
Kollmorgen Automation Suite™ simplifies and accelerates development through a unified system of software, hardware, and collaborative co-engineering. This scalable solution provides a fully integrated development environment for any application, whether you're programming a single axis of motion, a multi-axis AKD® PDMM system, or a PCMM-based system up to 64 axes or more. Kollmorgen Automation Suite has been proven to:

- Improve product throughput by up to 25% with industry-leading motion bandwidth
- Reduce scrap by up to 50% with world-class servo accuracy, seamless power-failure recovery and highly dynamic changeovers
- Increase precision for better quality, reduced waste and less downtime using EtherCAT®—the field bus with motion bus performance
- Enable more adaptable, sustainable and innovative machines that measurably improve marketability and profitability

A Single Family of Servo Drives

Kollmorgen AKD® servo drives deliver cutting-edge performance in a compact footprint. From basic torque-and-velocity applications, to indexing, to multi-axis programmable motion, these feature-rich drives offer:

- Plug-and-play compatibility with your servo motor
- All the advantages of Kollmorgen´s breadth of motor platforms including AKM®, CDDR®, and other direct-drive technologies
- The fastest velocity and position loop updates
- Full-frequency auto-tuning for perfect motion across the performance spectrum
- Real-time feedback from a wide variety of devices



Our Best Drive and Automation Solution in a Single Package

The AKD PDMM programmable drive, multi-axis master combines our AKD drive platform with the full feature set of Kollmorgen Automation Suite in a single package —providing complete machine and motion control for up to eight axes or more.

You need only one development suite and one drive family for all your projects. And you can rely on one source for all the motion components and co-engineering expertise you need to build a better machine.

With AKD PDMM, the best in machine engineering has never been easier, faster or more cost-effective.

PCMM™ Stand-Alone Controller

Powerful Motion Controller in Small and Simple Package

The PCMM programmable motion controller delivers the same features as the drive-integrate AKD®-PDMM controller, but in a stand-alone package that offers flexibility when used with AKD®-N/C decentralized drives and for machines where the benefits of an integrated drive and controller are not required.

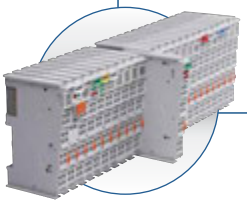
Ideal for OEMs that want to reduce cabinet space and machine complexity without sacrificing performance, the PCMM delivers full PLC functionality, a high-performance motion control and EtherCAT® master in one small package that easily installs in any electrical panel. Plus, programming is made easy using KAS IDE which includes PipeNetwork™ visual programming, one-click simulation, and integrated configuration and diagnostic tools simplify machine development and help you get to market faster.

General Features and Specifications

Processor	Available with 1.2GHz or 800MHz CPU
Internal Memory	64 MB Flash memory for program storage
External Memory	Removable SD card (not included)
Input Power	24 Vdc @ 1.25 A
Operating Temperature	0 °C - 40 °C
Sealing	IP20
Local I/O	6 digital inputs, 2 digital outputs
Motion Network	EtherCAT®, max 4kHz update rate
PLC Programming	IEC-61131-3, support for all 5 languages
Motion Programming	PLCopen or PipeNetwork®
HMI Programming	KVB programming for AKI panels
Dimensions	174mm (H) x 46.6mm (W) x 111.5mm (D)
Certifications	CE / UL

Part Number	Processor	Code	Axes Capacity	Synchronized Axes
AKC-PCM-MC-080-00N-00-000	800 MHz Standard Multi-axis Controller	MC	8+	4+
AKC-PCM-M1-120-00N-00-000	1.2 GHz High Performance Multi-axis Controller	M1	32+	16+
AKC-PCM-M2-120-00N-00-000	1.2 GHz Dual-core High Performance Multi-axis Controller	M2	64+	32+

Note: these are axis count estimates which are impacted by cycle update rate and motion complexity.



I/O

PCMM™ Hardware Features

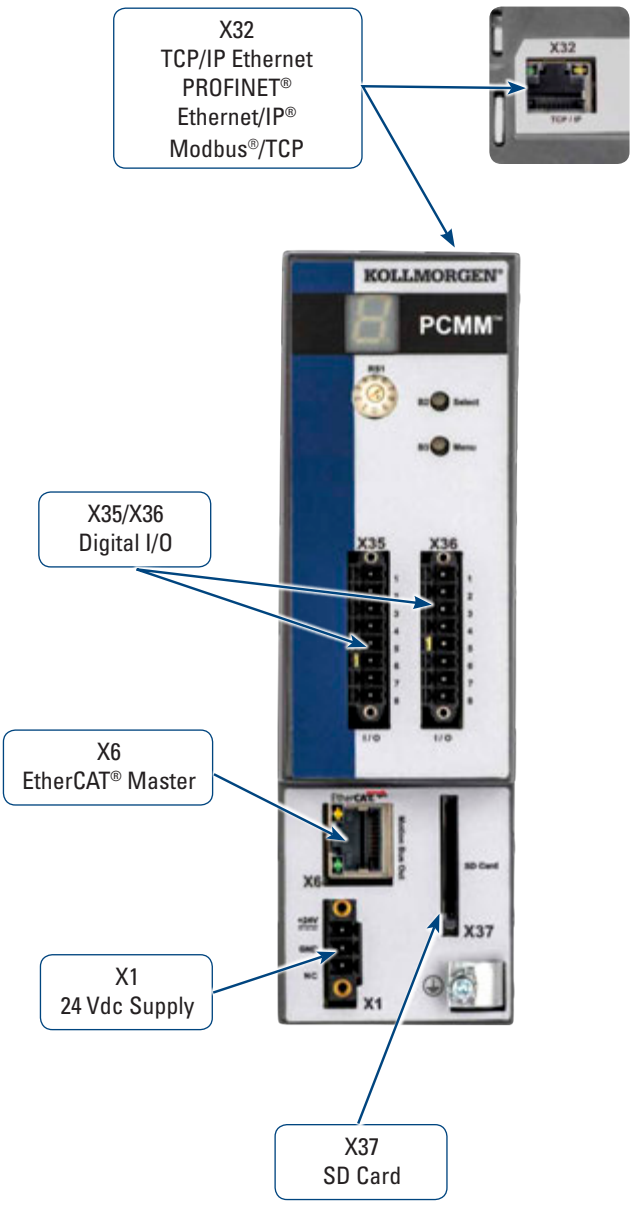
- Up to 1.2GHz CPU meets the performance requirements for a broad range of machines
- Control 1 to 30 or more axes with a single controller
- 100BaseT connection supporting TCP/IP, MODBUS®, EthernetIP®, Profinet® to host PLC, computer, or network to easily interface with most manufacturing systems
- Cycle times as low as 250 µs
- Alphanumeric display for fast diagnostics and system troubleshooting
- Removable SD memory card for simple backup/restore and file storage
- On-board digital I/O with support for expansion I/O via EtherCAT®
- Compact size reduces cabinet space and cost

PCMM™ Software Features

- IEC 61131-3 programmable automation and motion controller
- EtherCAT® master for high-performance motion and device synchronization
- PipeNetwork™ motion engine for visual programming
- Embedded RTOS for guaranteed performance and stability
- Integrated webserver for remote diagnostics and status checking
- Ideal design for modular machines and flexible manufacturing systems

PCMM™ System Integration

- Seamless integration with Kollmorgen's AKD® servo drives, AKM® rotary servo motors , AKI HMIs, and AKT fieldbus I/O modules for complete automation solution
- Network communication via OPC, MODBUS®, TCP/IP, UDP, and common fieldbus for fast integration into your machine or factory
- Intuitive EtherCAT® configuration tools built into KAS IDE simplifies network configuration
- Integrated Kollmorgen Workbench for rapid servo tuning and machine optimization




AKM® 2G Servo Motor


AKD®-N Servo Drive


AKD®2G Servo Drive


HMI

Real-time Motion Bus

EtherCAT®

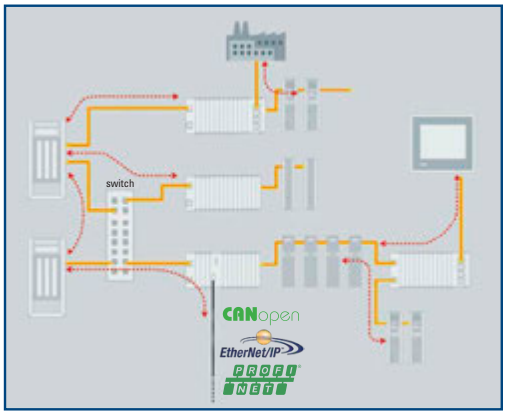
EtherCAT® Real-time Bus for Motion and I/O Connectivity

- Auto-recognition of Kollmorgen Automation Suite-compatible components
- Guaranteed real-time update cycle down to 250 microseconds.
- Supported by 2000+ member companies
- Standard Ethernet cabling = lower implementation cost
- Interoperability with other buses
- Wide availability of devices

Transparent for all Ethernet protocols

EtherCAT® Performance Overview

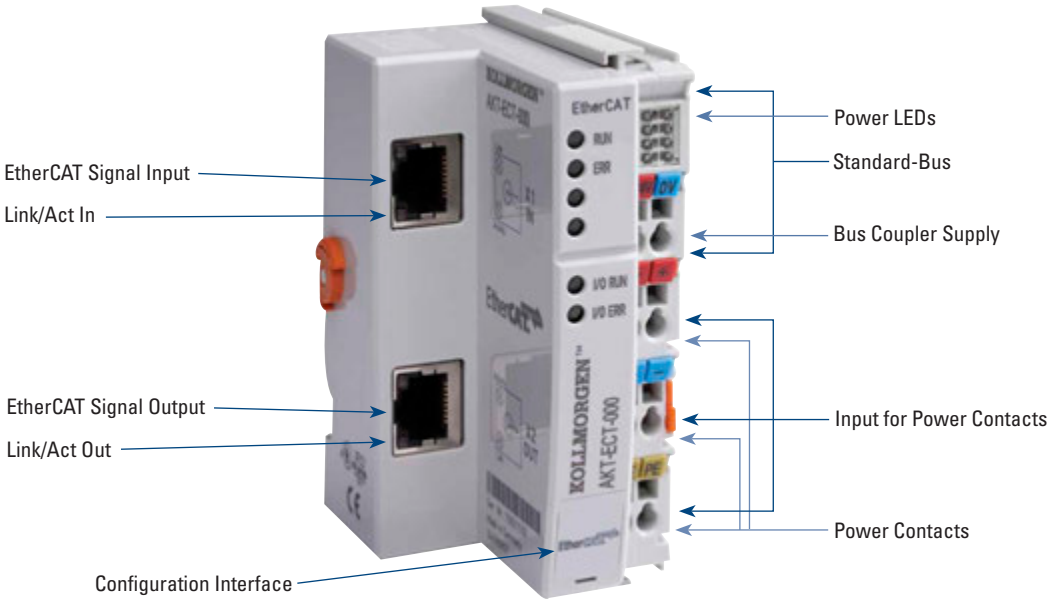
Process Data	Update Time
256 distributed digital I/O	11 µs = 0.01 ms
1000 distributed digital I/O	30µs
200 analog I/O (16 bit)	50 µs – 20 kHz
100 Servo Axis, with 8 Bytes input and output data each	100 µs
1 Fieldbus Master-Gateway (1486 Bytes Input and 1486 Bytes Output Data)	150 µs



Versatile network architecture

Kollmorgen EtherCAT® Bus Coupler

See page 26 for models and configurations



Human Machine Interface (HMI)

Kollmorgen HMI Panels

With Kollmorgen HMI's visualization projects can be scaled for different size screens and performance demands without having to re-write code or learn different tools.

- Choose from 5", 7", and 12" displays
- IP65 protection class screen for easy cleaning
- Rugged Plastic or Aluminum Housing

AKI2G-CDA 5" and 7"

AKI2G-CDB 7" and 12"

AKI2G-CDA Series

5", 7" Touchscreen HMI

Our basic industrial HMI offers a high resolution touch-screen and modern design. The panel combine IP65 corrosion resistant plastic housing with the full version of Kollmorgen Visualization Builder, providing a cost-effective yet advanced HMI solution for small to medium applications. The basic AKI2G model is the obvious choice when requiring a cost-efficient, high value, reliable HMI panel.

AKI2G-CDB Series

7", 12" Touchscreen HMI

Our advanced AKI2G series HMIs offers a range of high performance industrial panels designed for demanding applications. All with high performance ARM Cortex-A9 processors, the latest screen technology and a wide range of connectivity options to cover all your automation needs. We recommend our advanced HMI with high-performance for all applications.

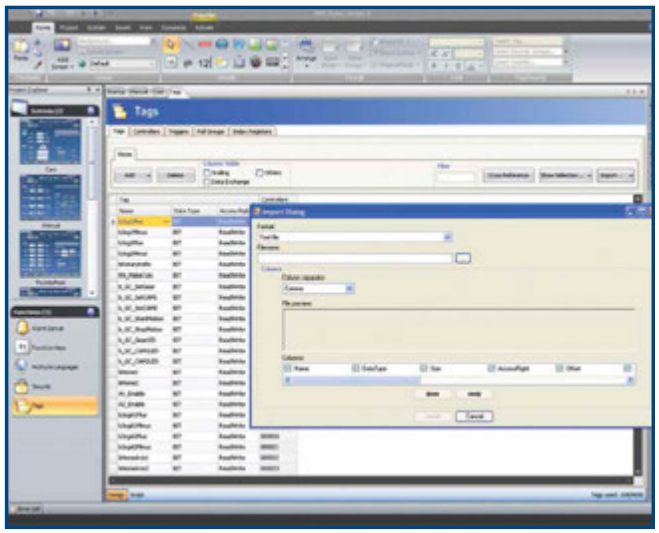
HMI Software Tools

Kollmorgen Automation Suite Visualization Builder™ HMI Software

Kollmorgen Automation Suite Visualization Builder operates from within the Kollmorgen Automation Suite integrated development environment making it quick and easy to create your HMI program and transfer it to the panel.

Features include

- Automatic mapping transfers PLC variables to HMI tags avoiding mistakes and saving time.
- Multi-screen navigation
- Trending/Data Logging
- Recipes
- Alarm management
- Drag and Drop programming
- Password Protection



HMI developer environment

Human Machine Interface (HMI)

AKI2G-CDA Series

Specifications	5 inch AKI2G-CDA-MOD-05T-000	7 inch AKI2G-CDA-MOD-07T-000
General Description		
Part number	AKI2G-CDA-MOD-05T-000	AKI2G-CDA-MOD-07T-000
Certifications		
General	CE, FCC, KCC	
Marine	–	
UL	UL 61010-2-201	
Mechanical		
Mechanical size	170 × 107 × 49 mm	196 × 146 × 52 mm
Touch type	Resistive	
Cut-out size	161 × 93 mm	186 × 136 mm
Weight	0.5 kg	0.7 kg
Housing material	Plastic (PC+ABS), Gray	
Power		
Input voltage	24 V DC (18 to 32 VDC) CE: The power supply must conform with the requirements according to IEC 60950 and IEC 61558-2-4. UL and cUL: The power supply must conform with the requirements for class II power supplies.	
Power consumption	6W	9.6W
Input fuse	Internal DC fuse	
System		
CPU	ARM9 400 MHz	
RAM	128 MB	
FLASH	256 MB, 200 MB free for application storage	
Display		
Size diagonal	5" diagonal	7" diagonal
Resolution	800 × 480 pixels	
Backlight	LED Backlight	
Backlight life time	20 000 hours	
Backlight brightness	300 cd/m²	400 cd/m²
Backlight dimming	Industrial Dimming	
Display type	TFT-LCD with LED backlight	
Display pixel error	Class I (ISO9241-307)	
Communication Serial		
Number of serial ports	2 Port 9pin DSUB	
Serial port 1	RS 232 (RTS/CTS)	
Serial port 2	RS422/485	
Serial port 3	RS 232	
Serial port 4	RS 485	
Ethernet Communication		
Number of ethernet ports	1	
Ethernet port 1	1 × 10/100 Base-T (shielded RJ45)	
Ethernet port 2	–	
Expansion interface		
Expansion port	No	
SD card	No	
USB	1 × USB 2.0 500mA	
Environmental		
Operating temperature	-10°C to +50°C	
Storage temperature	-20° to +60°C	
Shock	15g, half-sine, 11ms according to IEC60068-2-27	
Vibration	1g, according to IEC 60068-2-6, Test Fc	
Sealing front	IP65	
Sealing back	IP20	
Humidity	5% – 85% non-condensed	

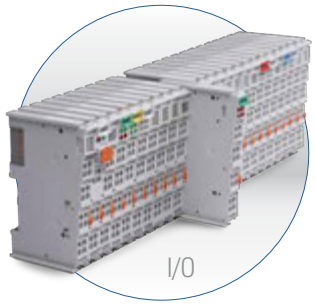
AKI2G-CDB Series

Specifications	7 inch AKI2G-CDB-MOD-07T-000	12 inch AKI2G-CDB-MOD-12T-000
General Description		
Part number	AKI2G-CDB-MOD-07T-000	AKI2G-CDB-MOD-12T-000
Certifications		
General	CE, FCC, KCC	
Marine	DNV, KR, GL, LR, ABS, CCS	
UL	UL 61010-2-201	
Mechanical		
Mechanical size	204 × 143 × 50 mm	340 × 242 × 57 mm
Touch type	Resistive	
Cut-out size	189 × 128mm	324 × 226mm
Weight	0.8 kg	2.6 kg
Housing material	Powder-coated aluminum, Gray	
Power		
Input voltage	24 V DC (18 to 32 VDC) CE: The power supply must conform with the requirements according to IEC 60950 and IEC 61558-2-4. UL and cUL: The power supply must conform with the requirements for class II power supplies.	
Power consumption	14.4W	28.8W
Input fuse	Internal DC fuse	
System		
CPU	i.MX6Solo Single Cortex-A9 1.0GHz 512kBL2cache	i.MX6DualLite, Dual Cortex-A9 1.0GHz 512kBL2cache
RAM	512 MB	1 GB
FLASH	2GB SSD(eMMC), 1.5GB free for application storage	
Display		
Size diagonal	7" diagonal	12.1" diagonal
Resolution	800 × 480 pixels	
Backlight	LED Backlight	
Backlight life time	20 000 hours	50 000 hours
Backlight brightness	350 cd/m²	400 cd/m²
Backlight dimming	Industrial Dimming	
Display type	TFT-LCD with LED backlight	
Display pixel error	Class I (ISO9241-307)	
Communication Serial		
Number of serial ports	1 Port 9pin DSUB	
Serial port 1	RS 232 (RTS/CTS)	
Serial port 2	RS422/485	
Serial port 3	RS485 (only if COM 2 is RS485)	
Ethernet Communication		
Number of ethernet ports	1	2
Ethernet port 1	1 × 10/100 Base-T (shielded RJ45)	
Ethernet port 2	–	1 × 10/100 Base-T (shielded RJ45)
Expansion interface		
Expansion port	Yes, ciX expansion module	
SD card	SD and SDHC	
USB	1 × USB 2.0 500mA	2 × USB 2.0 500mA
Environmental		
Operating temperature	-10°C to +60°C	
Storage temperature	-20° to +70°C	
Shock	15g, half-sine, 11ms according to IEC60068-2-27	
Vibration	1g, according to IEC 60068-2-6, Test Fc	
Sealing front	IP65, NEMA 4X/12 and UL Type 4X/12	
Sealing back	IP20	
Humidity	5% – 85% non-condensed	

I/O Terminals

Advanced Kollmorgen Terminal (AKT)

The Kollmorgen Automation Suite™ includes an array of I/O options for applications that need more I/O than can be provided by the onboard I/O of the drives or for applications that need specialized functionality such as thermocouple management through I/O. The DIN rail mount IP20 terminals simply slide together and connect to the system's EtherCAT® bus where they are auto-recognized for easy configuration.



Typical Bus Coupler

EtherCAT® bus coupler

Typical I/O Terminal

Front wiring view

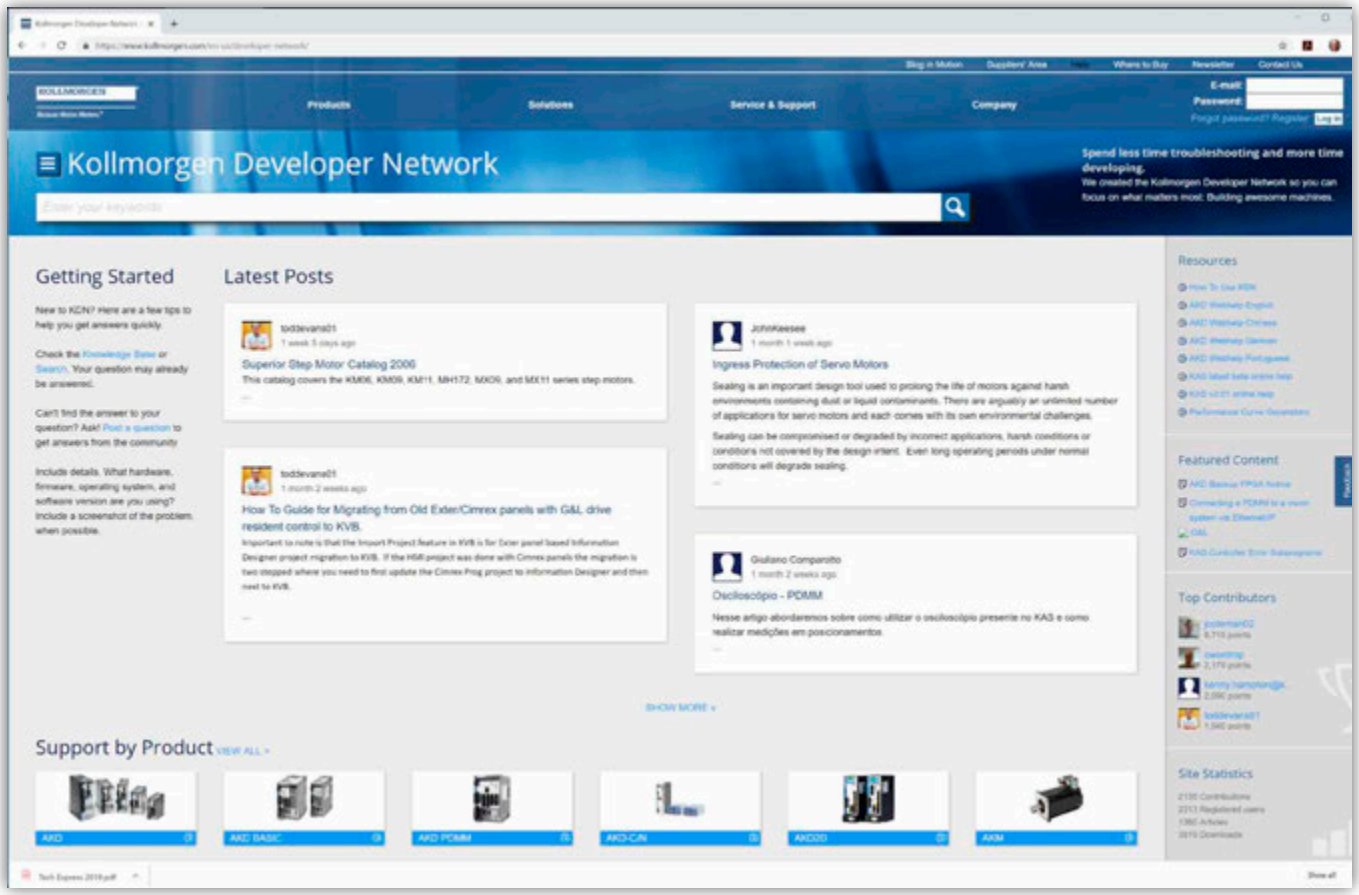
Side label view

Available Motion Bus Coupler Model	
AKT-ECT-000-000	EtherCAT® Bus Coupler
Available Analog Input Terminal Models	
AKT-AN-410-000	4 channel analog input module, 0-10 Vdc
AKT-AN-420-000	4 channel analog input module, 0-20 ma
AKT-AN-810-000	8 channel analog input module, 0-10 Vdc
AKT-AN-820-000	8 channel analog input module, 0-20 ma
AKT-AN-200-000	2 channel thermocouple input module
AKT-AN-400-000	4 channel thermocouple input module
Available Analog Output Terminal Models	
AKT-AT-220-000	2 channel analog output module, 0-20 ma
AKT-AT-410-000	4 channel analog output module, 0-10 Vdc
AKT-AT-420-000	4 channel analog output module, 0-20 ma
AKT-AT-810-000	8 channel analog output module, 0-10 Vdc
AKT-AT-820-000	8 channel analog output module, 0-20 ma
Available Digital Output Terminal Models	
AKT-DT-004-000	4 channel digital output module, 0.5A
AKT-DT-008-000	8 channel digital output module, 0.5A
AKT-DT-2RT-000	2 channel relay output module, 2.0A, N/O

Available Digital Input Terminal Models	
AKT-DN-004-000	4 channel digital input module, 3ms
AKT-DNH-004-000	4 channel digital input module, .2ms
AKT-DN-008-000	8 channel digital input module, 3ms
AKT-DNH-008-000	8 channel digital input module, .2ms
Available Specialty Terminal Models	
AKT-EM-000-000	End module
AKT-IM-000-000	Isolation module
AKT-PS-024-000	Bus feed terminal, 24 Vdc
AKT-PSF-024-000	Bus feed terminal, 24 Vdc, fused
Available Field Bus Coupler Models	
AKT-PRB-000-000	Profibus Bus Coupler
AKT-ENP-000-000	Ethernet/IP Bus Coupler
Stepper Driver	
AKT-SM-L15-000	Stepper Module, 24 Vdc, 1.5 A
AKT-SM-L50-000	Stepper Module, 50 Vdc, 5 A

Kollmorgen Developer Network

Kollmorgen Developer Network (KDN) is the central location for engineers to quickly get support on all Kollmorgen products, interact with and learn from the larger Kollmorgen user community, and receive expert instruction from Kollmorgen Applications Engineers and staff.



Ask a Question

Ask a question, or search and respond to existing questions. Provide an answer, or vote on the best answer. Leverage the global scope of Kollmorgen to get up to speed quickly.

Start a Discussion

Want to share a best practice, get feedback, or understand how others are solving similar problems? Start a new discussion, or join an active one, to share in the collabrative experience and knowledge of Kollmorgen product developers.

Propose a Feature

Have an idea for a new product, or feature? Submit it here. Customers speak and we listen. We know one size does not fit all. Our product is flexible, but sometimes differentiation requires a collaborative approach.

Latest Downloads

Keep up with our continually improving product, with access to the latest downloads.

Kollmorgen Servo Drive Overview

AKD® Product Family

Kollmorgen offers an extensive range of servo drives, designed to provide precise control, optimum torque and a rich feature set to complement our wide range of our rotary servo motors and linear positioning systems. The AKD product family of servo drives offer the broadest connectivity with the most advanced control technology, simplified commissioning and compact packaging available in the global marketplace.

Kollmorgen servo drives are commonly paired with our broad lineup of Kollmorgen servo motors offering plug-and-play compatibility. They are also well suited to run with most servo motors on the market due to flexible setup software and support for the most popular feedback devices (including resolvers, incremental encoders, BiSS, EnDat®, HIPERFACE®, sine encoders).

The AKD product family offers a range of drive-resident safety functions increasing machine safety, while improving operator ergonomics and machine throughput.

The AKD product family offers several variants supporting centralized control panel architecture including single and dual axis drives, programmable and drive-resident controllers, minimizing panel space requirements and maximizing performance. For those applications that need IP67 drives outside a control panel, or have extensive cabling lengths from the machine to the control panel, the AKD-N is great decentralized option for machine builders to design the optimal cost effective machine.

Our premier KAS machine automation solution brings together a highly integrated and intuitive software programming environment, best-in-class motion components and exceptional co-engineering services to help you build highly differentiated machines. Kollmorgen Automation Suite™ (KAS) has proven to dramatically accelerate development time, increase machine throughput, reduce scrap and increase overall equipment effectiveness (OEE). AKD product family drives can connect to Kollmorgen's PCMM, an EtherCAT® master controller, which is programmed through KAS using industry-standard IEC 61131-3 PLC programming toolkit controlling up to 128 axes.

AKD® Product Family





Parameter	AKD2G	AKD	AKD BASIC	AKD PDMM	AKD-N/AKD-C
Base I/O	12 digital 2 analog	11 digital 2 analog	11 digital 2 analog	17 digital 2 analog	5 digital
Expansion I/O[1]	8 digital 2 analog *Drive size is the same	No	20 digital 2 analog *adds 30 mm to the drive width for drives up to 12A	Up to 1000+ remote I/O via EtherCAT	No
Safe I/O	2 digital inputs, expandable to 4	No	No	No	No
SafeMotion[2]	Yes	STO only	STO only	STO only	STO only
Optimized for single cable[3]	Yes	No	No	No	Yes
Continuous current limit[4]	12A	48A	48A	48A	12A
Connectivity[5]	Analog, EtherCAT, CANopen	Analog, EtherCAT, CANopen, Profinet RT, Ethernet/IP, TCP/IP, Modbus/TCP	Analog	EtherCAT, CANopen, Profinet RT, Ethernet/IP, TCP/IP, Modbus/TCP	EtherCAT
Axis Configuration	single or dual	single	single	single	single
Drive-resident controller	No	No	No	Yes	No
Programmability	parameterized, 2 axes control loops, actlon table	parameterized	parameterized, BASIC programmable	parameterized, IEC 61131-3 via PLCopen or Pipe Network	parameterized
Graphical Display	160x128-pixel display	2 digit LED	2 digit LED	3 digit LED	Status LED
Removeable Memory[6]	Yes	No	Yes	Yes	No
System Architecture	Centralized	Centralized	Centralized	Centralized	Decentralized
IP Rating	IP20	IP20	IP20	IP20	IP67

Notes:
1: Add EtherCAT multi-axis master, PCMM, to the AKD drive family to enable remote I/O expansion via EtherCAT. PCMM controller functionality is built into the PDMM
2: SafeMotion includes FSoE, SS1, SDB, SBC/SBT, etc. Consult factory on availability of the latest drive-resident SafeMotion functions
3: Single cable optimized means one single cable for power & motor feedback with 1 connector at motor end and 1 connector at drive end
4: Consult factory on drive current limitations for AKD2G. 24A is planned for 2020 and 48A is planned for 2021
5: Consult factory on connectivity options for AKD2G. Profinet and Ethernet/IP will be added in 2020
6: Optional integrated SD card for easy backup and drive cloning

AKD®2G Servo Drive

The newest member of the AKD family is our most powerful yet. Along with increased power, the AKD2G is simplified and includes integrated Safe Motion that increases Ease-of-Use

The new AKD2G servo drive introduces the Kollmorgen Servo-on-a-Chip: A powerful compute engine that can control 2 axes simultaneously and up to 28 I/O. While we were at it, we streamlined the design by optimizing the AKD2G for single-cable motors.

The Benefits of AKD®2G Servo Drive

• Flexible	• One and two axis variants available
	• Modular design allows the user to specify only the features needed
	• Supports a variety of feedback devices—SFD & HIPERFACE® DSL standard;
	  • optional feedbacks include EnDat, BiSS, Analog Sine/Cos encoder, incremental encoder, resolver and more
	• Multiple bus choices for system optimization, including EtherCAT® & FSoE, and CANopen®
	• Over-voltage, current, and temperature detection provided for added dependability
	• Optional Safe Motion Monitor (SMM), SIL3/PLe
	• Dual-channel STO for each axis (up to SIL3/PLe)*
	• Industry-leading power density for greater flexibility in mounting
	  • Fits into a 10 inch [25.4 cm] deep control panel

• Easy to Use	• Plug-and-play compatibility with Kollmorgen controls and motors • WorkBench GUI, acclaimed for customer experience and usability • Hybrid Motor-Power connector is optimized for single-cable motors: • No adaptors, no D-subs, no splitters • Cage-clamp spring terminal connectors on I/O allow for fast and easy installation • Optically-isolated I/O reduces noise, and eliminates need for additional hardware

• Fast	• Accommodates changing load conditions immediately:
	  • Current loop updates in 1.28 µs, nearly 50x the speed of our nearest competitors
	  • Velocity and position loops lead the market at 62.5 µs and 125 µs, respectively
	• Servo on a Chip™ includes dual-core ARM™ A9, 800 MHz µP, 1.5 M gates
	• AI-based auto-tuning with a click of a button gets you started quickly
	• Wizard-based tuning uses advanced Bode Plot tool to help you efficiently manual-tune when desired
	• Fast data acquisition with TCP/IP Ethernet service channel

*Consult factory on certification status for AKD2G drives.

AKD®2G Servo Drive

AKD® 2G Means Unparalleled Connectivity

Base Model:

The base model of Kollmorgen's AKD2G includes all of the performance described previously, and is optimized to interface to a single-connector motor with Kollmorgen's Smart Feedback or HIPERFACE® DSL. It also offers 16 I/O, 160x128-pixel graphical display, removable SD card, and your choice of motionbusses.

Extended I/O Variant

The extended I/O variant offers everything on the base model, plus I/O expansion.

This I/O expansion includes the 15-pin D-sub for legacy feedbacks or dual-loop operation; it also includes an additional 12 I/O for a total of 28 I/O. The options fit in the same package as the base model.

Safe Motion Monitor (SMM)

The Extended I/O model is offered with the optional SMM. The SMM converts some of the I/O into "Safe" I/O, and allows the drive to interface safely to an FSoE master. Again, these options fit in the same package as the base model.

Dual-Axis AKD2G 480 Vac (shown with optional feedback and I/O expansion)

Dual-Axis AKD2G 240 Vac (shown with optional SMM, feedback and I/O expansion)

Safety over EtherCAT. EtherCAT. Conformance tested

CANopen®

UL LISTED CE ISO RoHS EAC

General Specifications

120/240 Vac	Continuous Current	Peak Current	Typical Shaft Power	Internal Regen		Height	Width	Depth	Depth w/ cable bend radius
	(Arms)	(Arms)	(kW)	(W)	(Ω)	mm (in)	mm (in)	mm (in)	mm (in)
AKD2G-SPx-6V03S	3	9	1	100	15	233 (9.15)	75 (2.95)	180 (7.09)	225 (8.86)
AKD2G-SPx-6V06S	6	18	2						
AKD2G-SPx-6V12S	12	30	4						
AKD2G-SPx-6V03D	3 & 3	9 & 9	1 & 1						
AKD2G-SPx-6V06D	6 & 6	18 & 18	2 & 2						

240/480 Vac	Continuous Current	Peak Current	Typical Shaft Power	Internal Regen		Height	Width	Depth	Depth w/ cable bend radius
	(Arms)	(Arms)	(kW)	(W)	(Ω)	mm (in)	mm (in)	mm (in)	mm (in)
AKD2G-SPx-7V03S	3	9	2	100	33	270 (10.6)	75 (2.95)	180 (7.09)	225 (8.86)
AKD2G-SPx-7V06S	6	18	4						
AKD2G-SPx-7V12S	12	30	8						
AKD2G-SPx-7V03D	3 & 3	9 & 9	2 & 2						
AKD2G-SPx-7V06D	6 & 6	18 & 18	4 & 4						

Note: For complete AKD2G model nomenclature, refer to page 193.

AKD® 2G Drive Connector Layout

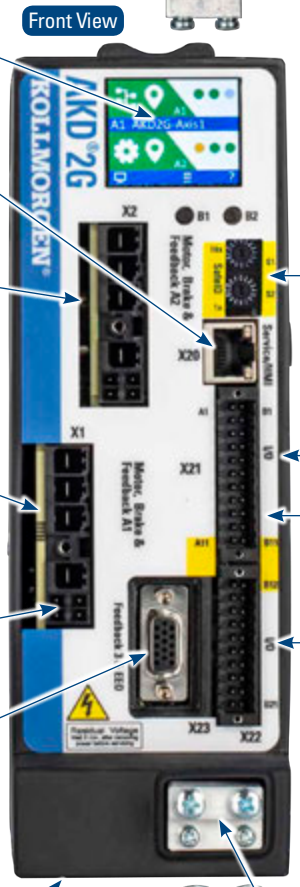
24Vdc logic supply input

Optional Motionbus:
- EtherCAT®
- FSoE
- CANopen®

Removable memory (Standard SD card)

Safe Address Setting (included with SMM option)

Full color (RGB) backlit LCD display, 160 x 128 pixels



Service Port

Second motor (with dual-axis option)
- Motor power
- Brake
- Feedback

Optimized for single hybrid cable interface:
- Motor power
- Brake
- Feedback

SIL3 Safe Options
- Safe Brake
- Safe Feedback

Optional feedback port (15-pin "D-sub"):
- Dual-loop Feedback
- Legacy Feedbacks
  - Resolver
  - A-QUAD-B
  - EnDAT
  - BiSS
  - sin/cos, etc.
- EEO (encoder emulation)

AC Mains (in and out): 120 Vac, 240 Vac, 480 Vac

Inputs and Outputs (I/O):

Base drive will offer:
1 x Analog Input
1 x Analog Output
8 x Digital Inputs (sinking), of which two (2) are high-speed
4 x Digital Outputs (sourcing)
1 x Relay Output, 24V @ 2A
1 x Two-channel STO

Optional I/O Expansion:

Drive with I/O expansion will offer:
2 x Analog Inputs
2 x Analog Outputs
12 x Digital Inputs (sinking), of which two (2) are high-speed
2 x "Open" Digital Outputs as volt-free pairs (sink/source 5V-24V), high speed
6 x Digital Outputs (sourcing)
2 x RS485-style Selectable Inputs or Outputs, 5V
1 x Relay Output, 24V @ 2A
1 x One-channel or Two-channel STO

Drive with SMM* & I/O Expansion Will Offer:**
2 x Analog Inputs
2 x Analog Outputs
8 x Digital Inputs (sinking), of which two (2) are high-speed
4 x "Safe" Digital Inputs (sinking), can be configured instead as "normal" inputs or STO
2 x "Open" Digital Outputs (sink/source 5V-24V), high speed
2 x Digital Outputs (sourcing)
4 x "Safe" Outputs (sourcing)
2 x RS485-style Selectable Inputs or Outputs, 5V high-speed
1 x Relay Output, 24V @ 2A
1 x One-channel or Two-channel STO

Physical Earth (PE)
Also where shield/screens are mounted

*SMM = Optional Safe Motion Monitor
**I/O count shows the net sum of standard I/O + the expansion I/O

SafeMotion

Why should a whole production line be brought to a standstill during user interventions when only one part of it is affected? Kollmorgen has put the idea of building drives with SafeMotion that integrates the safety logic and monitoring within the drive. Without compromising on safety, SafeMotion can achieve considerably higher productivity and offer more flexibility when adjusting to new requirements.

Make the Most of the Advantages of the Kollmorgen Motion Safety Strategy

• Higher productivity	• Motion Safety enables user interventions in running processes • Safe motion instead of safe deactivation • Risk-dependent triggering of safety functions
• Low system costs	• Optimal adjustment to requirements due to modular structure • Wide range of standard products • Safety control and drive monitoring in one device
• Flexible	• Modular concept and simple upgrade of existing drives • Seamless transition from hardwired to configurable safety logic
• Simple and fast implementation	• Important motion-related safety functions are integrated • Predefined safety function blocks • Intuitive tools for programming and parameterization in the field by the customer

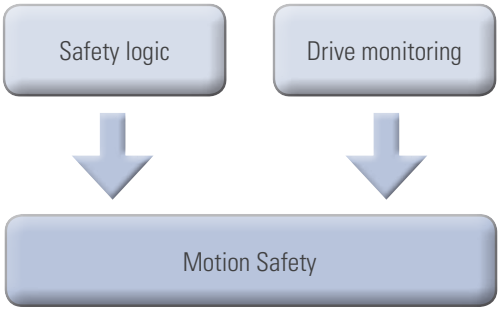
Safe Motion

Safety Logic and Drive Monitoring Integrated within the Drive

Quickly Integrate AKD2G Into Your Automation System

Easy to Use

- Workbench or FSoE master tool:
  - Easy configuration and troubleshooting
  - Simplified commissioning & troubleshooting
  - Simple field drive replacement



Flexible & Seamless Integration

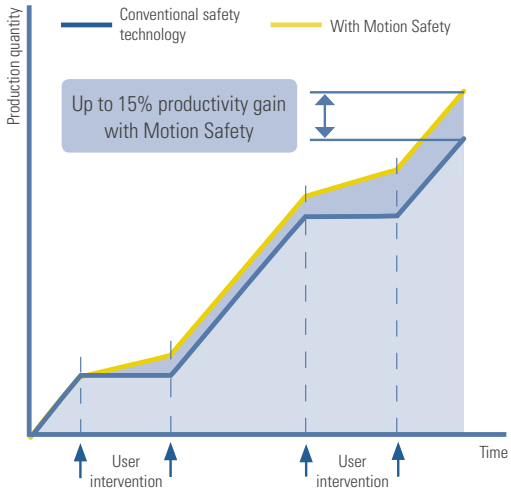
- Easy connectivity to simple safety relays or to FSoE master
- Standalone safety without additional safety control
- Central SafeMotion parameter storage in the PLC

Innovative SafeMotion

- Single cable technology with optional safe encoder
- Optional Safe EnDAT 2.2 high-accuracy e.g. with linear feedback
- Quick (~ms) response to critical events
- Extended safety funtions like Safe Dynamic Brake (SDB) and Safe Brake Test (SBT)

Productivity Gains with Motion Safety

Safety functions for areas with dangerous motion are activated when intervening in a running process. With intelligent safety functions, motion sequences are controlled so that each motion is safe. For example, this is performed through position monitoring and restricting the range of motion or by increasing the cycle times. Parts of the machine that do not constitute a risk to the user are not affected. The graph clearly shows the productivity gains when using Kollmorgen's Motion Safety technology.

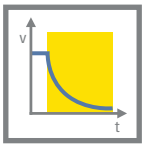


Kollmorgen – your Competent Partner for Safe Drive Solutions

As the leading manufacturer of electrical drive technology, Kollmorgen boasts extensive expertise gained from thousands of drive projects around the world. Safety logic, servo drives, motors, through to complete automation solutions – Kollmorgen supplies co-ordinated components for safe drive solutions, all from one source. Whether it is a standard implementation or a new development as part of a co-engineering project, make use of Kollmorgen's innovative capacity and experience for developing your safe drive.

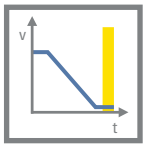
Extensive Safety Functions for Safe Motion

STO[3] (Safe Torque Off)



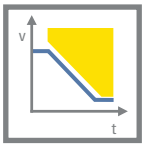
STO safely interrupts the power supply to the motor in the servo drive. The motor becomes torque-free.

SS1[2] (Safe Stop 1)



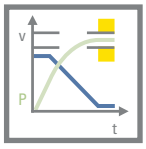
The drive is brought to a standstill by controlled braking. Then the power supply to the motor is safely interrupted and the motor becomes torque-free.

SS2[1] (Safe Stop 2)



The drive is brought to a standstill by controlled braking and subsequently remains in controlled standstill. The control functions of the drive are maintained.

SOS (Safe Operating Stop)

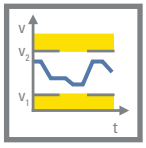


Monitors the stop position reached and triggers SS1 in the event of deviations beyond the specified limits. The control functions of the drive remain active.

SDI[1] (Safe Direction)

The SDI function ensures that the drive can only move in a defined direction. In the event of an error, SS1 is triggered.

SSR[1] (Safe Speed Range)

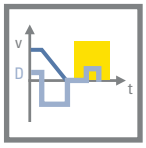


Monitors that the drive observes a defined speed limit. In the event of an error, SS1 is triggered.

SLS[1] (Safe Limited Speed)

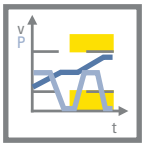
Monitors that the drive observes a defined speed limit. In the event of an error, SS1 is triggered.

SBC (Safe Brake Control), SBT



SBT (Safe Brake Test) (non-standardized)
Test function for external brakes and the internal motor holding brake

SLP[1] (Safe Limited Position)



Monitors the absolute position of the drive. If the limit value is reached or the brake torque is too low to keep the drive within the limit value, SS1 is triggered.

SLI[1,3] (Safe Limited Increments[3])

Monitors the relative position of the drive with respect to the current position when activating the SLI function. SS1 is triggered when the prescribed limit value is reached.

[1]Requires "Safe" feedback devices; function available Q4, 2019
[2]SS1 if faulted is the default setting. Users can easily configure this or other actions in WorkBench.
[3]STO SIL 2/PLd to be completed in Q4 2019 and all SIL 3/PLe certifications to be completed in Q1 2020

AKD® Servo Drive

Our AKD series is a complete range of Ethernet-based servo drives that are fast, feature-rich, flexible and integrate quickly and easily into any application. AKD ensures plug-and-play commissioning for instant, seamless access to everything in your machine. And, no matter what your application demands, AKD offers industry-leading servo performance, communication options, and power levels, all in a smaller footprint.

This robust, technologically advanced family of drives delivers optimized performance when paired with our best-in-class components, producing higher quality results at greater speeds and more uptime. With Kollmorgen servo components, we can help you increase your machine's overall equipment effectiveness (OEE) by 50%.

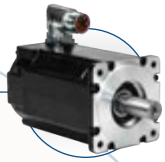
The Benefits of AKD Servo Drive

• Optimized Performance in Seconds	• Auto-tuning is one of the best and fastest in the industry • Automatically adjusts all gains, including observers • Immediate and adaptive response to dynamic loads • Precise control of all motor types • Compensation for stiff and compliant transmission and couplings
• Greater Throughput and Accuracy	• Up to 27-bit-resolution feedback yields unmatched precision and excellent repeatability • Very fast settling times result from a powerful dual processor system that executes industry-leading and patent pending servo algorithms with high resolution • Advanced servo techniques such as high-order observer and bi-quad filters yield industry-leading machine performance • Highest bandwidth torque-and-velocity loops. Fastest digital current loop in the market
• Easy-to-use Graphical User Interface (GUI) for Faster Commissioning and Troubleshooting	• Six-channel real-time software oscilloscope commissions and diagnoses quickly • Multi-function Bode Plot allows users to quickly evaluate performance • Auto-complete of programmable commands saves looking up parameter names • One-click capture and sharing of program plots and parameter settings allow you to send machine performance data instantly • Widest range of programming options in the industry
• Flexible and Scalable to Meet any Application	• 3 to 48 Arms continuous current; 9 to 96 Arms peak • Very high power density enables an extremely small package • True plug-and-play with all standard Kollmorgen servo motors and actuators • Supports a variety of single and multi-turn feedback devices – Smart Feedback Device (SFD/SFD3), EnDat 2.2, EnDat 2.1, BiSS, analog Sine/Cos encoder, incremental encoder, HIPERFACE®, and resolver • Tightly integrated Ethernet motion buses without the need to add large hardware: EtherCAT®, SynqNet®, Modbus® TCP, EtherNet/IP™, PROFINET® RT, SERCOS® III, and CANopen® • Scalable programmability from base torque-and-velocity through multi-axis master

AKD® Servo Drive

The AKD servo drive delivers cutting-edge technology and performance with one of the most compact footprints in the industry. These feature-rich drives provide a solution for nearly any application, from basic torque-and-velocity applications, to indexing, to multi-axis programmable motion with embedded Kollmorgen Automation Suite™. The versatile AKD sets the standard for power density and performance.

AKMH™ Hygienic Stainless Steel Motors



AKM & AKM® 2G Servo Motors

Frameless Brushless Direct Drive Motors

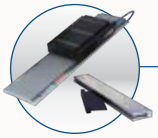
AKD®-N Decentralized Servo Drive

Control of motors with AKD® PDMM programmable multi-axis master

Cartridge DDR® Motors

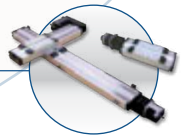
AKD® Servo Drive

Housed DDR® Motors



Direct Drive Linear Motors

Linear Actuators



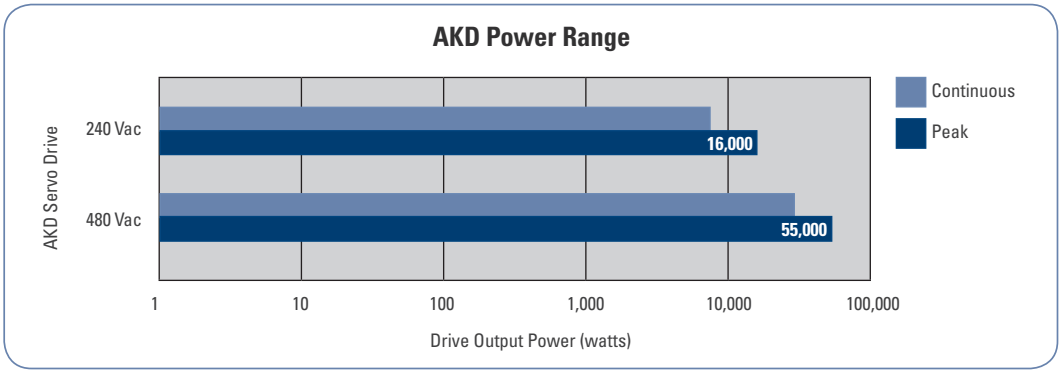
Multi-Axis Precision Tables

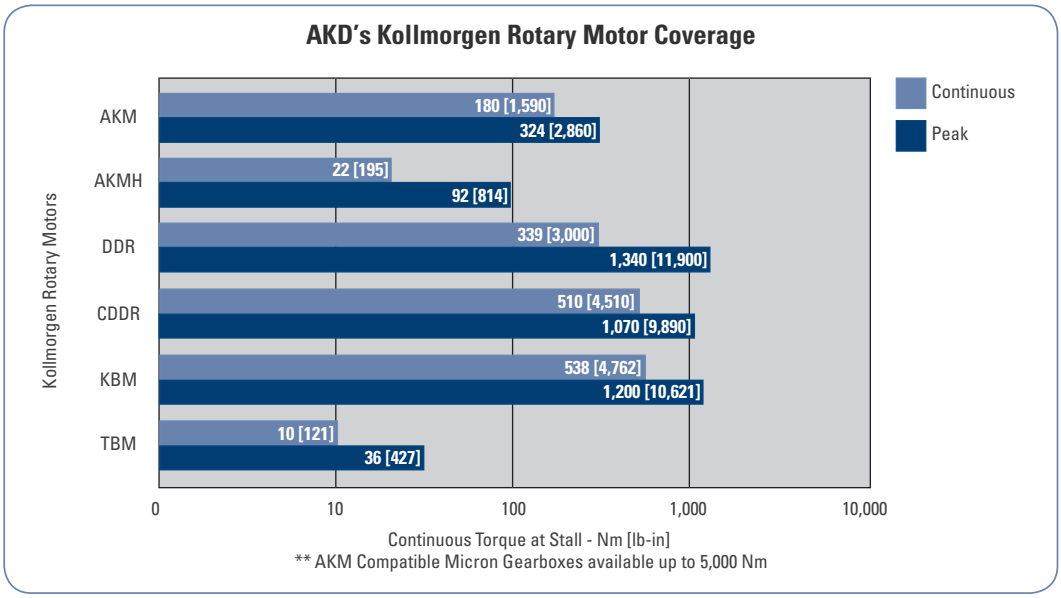
Best-in-Class Components

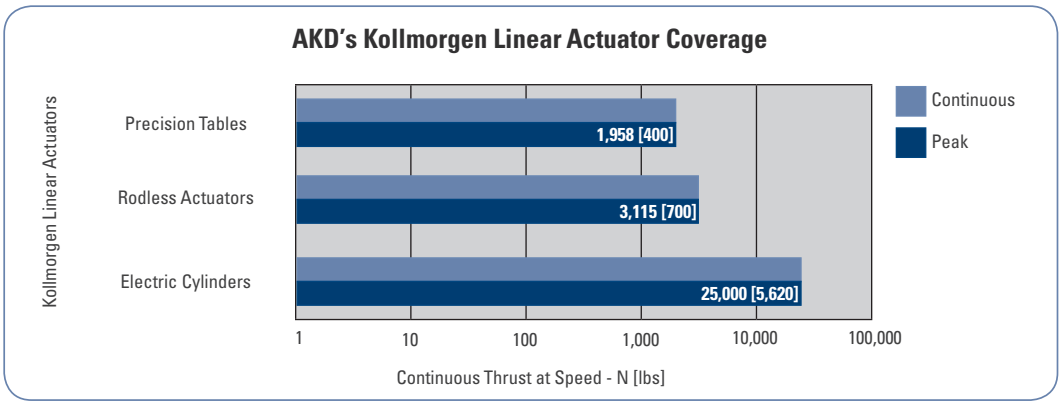
AKD works seamlessly with Kollmorgen motors and actuators–well-known for quality, reliability, and performance.

Range of Coverage

When you pair the AKD servo drive with any of our Kollmorgen motors or linear actuators, you'll achieve optimized performance. From 3 to 48 Arms continuous current and 9 to 96 Arms peak current, the feature-rich AKD provides a solution for nearly any application.







AKD® BASIC Drives

High Performance Capabilities in an Integrated Drive/Control Solution

Add co-engineering to your toolbox. Save money, simplify your machine and customize performance to meet the specific needs of each customer or application – as needed, today or tomorrow.

Our new Kollmorgen AKD® BASIC drives add BASIC-programmable machine and motion control to the superior performance of our AKD drive platform. So engineers can quickly customize performance at the drive level without touching the PLC. In fact, for many applications you can avoid the expense, wiring and cabinet space of a PLC altogether.

Whether you rely on your own engineering expertise or Kollmorgen's, the base and Expanded I/O versions of our AKD BASIC drive give you the unprecedented machine and motion control flexibility in a compact, fully integrated drive package. It's one more example of our co-engineering mission to help you deliver exactly what your customers want – when they want it – in solutions that are more cost-effective to build, simpler in design and faster to market.

AKD BASIC Language Programmable Drive

In addition to the wide selection and key features of our proven AKD, the standard version of our AKD BASIC drive offers:

- **Programmable machine control built into the drive,** so you can engineer perfect axis-level performance without touching the machine controller. In fact, AKD BASIC can eliminate the need for a PLC in single and 1.5 axis applications – reducing wiring requirements, panel space, design complexity and cost.
- **High performance motion control built into the drive,** enabling increased speed for more complex moves in a simpler design with reduced wiring.
- **BASIC Language programming,** providing simple program flow control in a solution that's easy to learn, quick to master and universally accepted.
- **An integrated development environment,** allowing single-point programming, de-bugging, commissioning, tuning and management of your AKD BASIC drive from within AKD WorkBench. Our BASIC editor provides innovative features that speed development time and reduce coding errors.
- **Source code lockout with password protection,** freeing you to differentiate your product with drive-level control while safeguarding your intellectual property.

I/O Capabilities	Base Version	Expanded I/O Version
Digital Inputs	8	20
Digital Outputs	3	13
Analog Inputs	1	2
Analog Outputs	1	2

Expanded I/O AKD BASIC Programmable Drive

Building on the features of the AKD BASIC drive, we also offer an expanded I/O version that adds:

- **A total of 20 digital inputs, 13 digital outputs, 2 analog inputs and 2 analog outputs,** reducing or eliminating the need for remote I/O and its associated installation and wiring costs.
- **An SD memory card slot** for loading, and restoring programs and parameters, without the need for a PC.

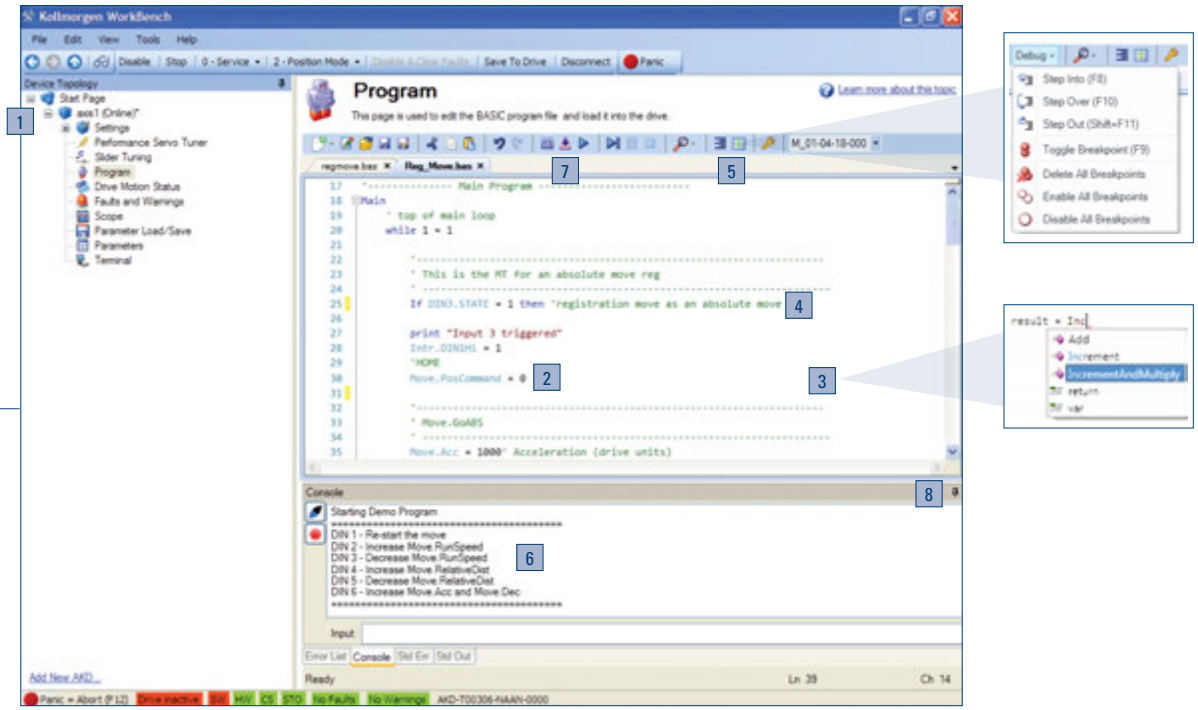
Development Tools that Speed Programming and Improve Quality

Co-engineering is a powerful tool. To make it easy for you to provide better solutions for your customers, we provide an innovative BASIC programming environment within Kollmorgen WorkBench. So there's only one software package to use for all of your drive setup, configuration, tuning and management tasks in addition to motion and machine control programming.

Pre-built code templates give your application a head-start, while automatic formatting, highlighting and other ease-of-use features increase programming speed and accuracy. Complete access to all programming capabilities and drive features within a single environment helps speed your development of complete, optimally engineered solutions.

Novice users will enjoy a short ramp-up time to productive coding, while experienced users will discover well-designed tools that take their programming skills to new levels of speed and quality.

1. Integrated axis setup
2. Code snippets simplify formatting
3. Auto-complete helps speed coding and reduce errors
4. Automatic color coding makes it easy to distinguish comments, parameters, print statements and other types of code
5. Full debugger accelerates development
6. Packaged program console provides instant program status
7. Menu-driven navigation provides intuitive look and feel
8. Window pinning maximizes workspace



AKD® PDMM Drive-Resident Controller

Build Simpler and Better with Drive-Resident Machine and Motion Control

Extend your design options. Control as many as eight axes or more without the need for a PLC or PAC. Reduce cabinet space and wiring requirements. Program perfect machine and motion control for any project using a single, fully integrated programming environment. Build a better machine at a lower cost.

Our new addition to the AKD® drive family combines one servo axis, a master controller that supports multiple additional axes, and the full automation capability of Kollmorgen Automation Suite™—all in a single, compact package.

Welcome to the AKD® PDMM programmable drive, multi-axis master.

Performance Specifications

120/240 Vac 1- and 3-Phase*	Continuous Current (Arms)	Peak Current (Arms)	H (mm/inches)	W (mm/inches)	D (mm/inches)
AKD-M00306-MxEC-0000	3	9	168 / 6.61	89 / 3.50	156 / 6.14
AKD-M00606-MxEC-0000	6	18	168 / 6.61	89 / 3.50	156 / 6.14
AKD-M01206-MxEC-0000	12	30	196 / 7.72	107 / 4.21	187 / 7.36
AKD-M02406-MxEC-0000	24	48	248 / 9.76	96 / 3.78	228 / 8.98

240/400/480 Vac 3-Phase*	Continuous Current (Arms)	Peak Current (Arms)	H (mm/inches)	W (mm/inches)	D (mm/inches)
AKD-M00307-MxEC-0000	3	9	256 / 10.08	99 / 3.90	185 / 7.28
AKD-M00607-MxEC-0000	6	18	256 / 10.08	99 / 3.90	185 / 7.28
AKD-M01207-MxEC-0000	12	30	256 / 10.08	99 / 3.90	185 / 7.28
AKD-M02407-MxEC-0000	24	48	306 / 12.05	99 / 3.90	228 / 8.98
AKD-M04807-MxEC-0000	48	96	385 / 15.16	185 / 7.28	225 / 8.85

*Where"x" = C is for the standard 800 MHz CPU and "x" = 1 is for the high performance v1.2 GHz CPU.

Features

- Kollmorgen Automation Suite™ provides fully integrated programming, testing, setup and commissioning
- Embedded web server utility simplifies service
- Control 32 axes or more* while reducing machine footprint
  - EtherCAT® multi-axis master motion controller integrated with a standard AKD® drive axis
  - Full IEC61131-3 soft PLC for machine control, with support for all 5 programming languages
  - Choice of PLCopen for motion or Pipe Network™ for programming motion control
  - 32 KB non-volatile memory stores machine data to eliminate scrap upon restart after power failure
  - SD Card slot simplifies backup and commissioning, with no PC required
  - On-board I/O includes 13 digital inputs, 4 digital outputs, 1 analog input, 1 analog output (expandable with AKT series of remote I/O)
- Works with Kollmorgen Visualization Builder for programming AKI2G human-machine interface panels

*Maximum axis count depends on motion/automation complexity and performance (8 axes nominal based on medium complexity at 4 kHz network update rate)

A Single, Scalable Development Suite

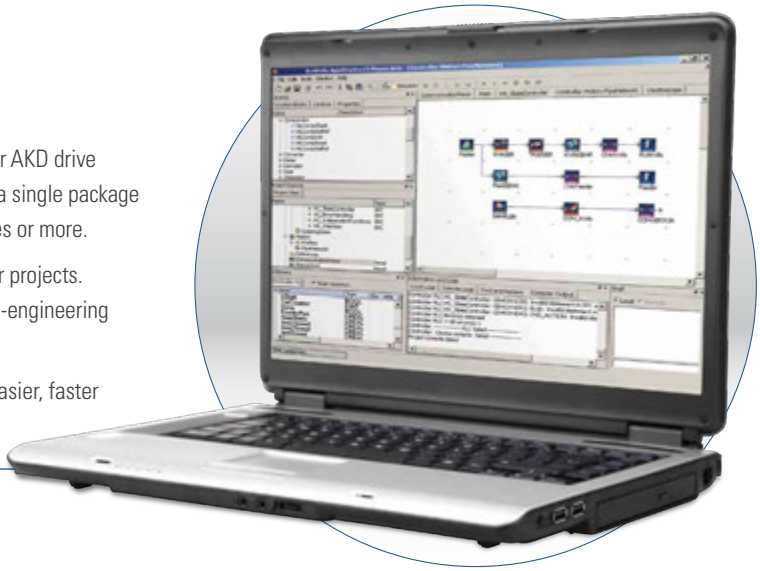
Kollmorgen Automation Suite™ simplifies and accelerates development through a unified system of software, hardware, and collaborative co-engineering. This scalable solution provides a fully integrated development environment for any application, whether you're programming a single axis of motion, a multi-axis AKD® PDMM system, or a PCMM-based system up to 64 axes or more. Kollmorgen Automation Suite has been proven to:

- Improve product throughput by up to 25% with industry-leading motion bandwidth
- Reduce scrap by up to 50% with world-class servo accuracy, seamless power-failure recovery and highly dynamic changeovers
- Increase precision for better quality, reduced waste and less downtime using EtherCAT®—the field bus with motion bus performance
- Enable more adaptable, sustainable and innovative machines that measurably improve marketability and profitability

A Single Family of Servo Drives

Kollmorgen AKD® servo drives deliver cutting-edge performance in a compact footprint. From basic torque-and-velocity applications, to indexing, to multi-axis programmable motion, these feature-rich drives offer:

- Plug-and-play compatibility with your servo motor
- All the advantages of Kollmorgen´s breadth of motor platforms including AKM®, CDDR®, and other direct-drive technologies
- The fastest velocity and position loop updates
- Full-frequency auto-tuning for perfect motion across the performance spectrum
- Real-time feedback from a wide variety of devices



Our Best Drive and Automation Solution in a Single Package

The AKD PDMM programmable drive, multi-axis master combines our AKD drive platform with the full feature set of Kollmorgen Automation Suite in a single package —providing complete machine and motion control for up to eight axes or more.

You need only one development suite and one drive family for all your projects. And you can rely on one source for all the motion components and co-engineering expertise you need to build a better machine.

With AKD PDMM, the best in machine engineering has never been easier, faster or more cost-effective.

AKD® Servo Drive

Industry-leading power density

General Specifications

120 / 240 Vac 1 & 3 Phase (85 -265 V)	Continuous Current (Arms)	Peak Current (Arms)	Drive Continuous Output Power Capacity (Watts)	Internal Regen (Watts) (Ohms)		Height mm (in)	Width mm (in)	Depth mm (in)	Depth with Cable Bend Radius mm (in)
AKD-x00306	3	9	1100	0	0	168 (6.61)	59 (2.32)	156 (6.14)	184 (7.24)
AKD-x00606	6	18	2000	0	0	168 (6.61)	59 (2.32)	156 (6.14)	184 (7.24)
AKD-x01206	12	30	4000	100	15	196 (7.72)	78 (3.07)	187 (7.36)	215 (8.46)
AKD-x02406	24	48	8000	200	8	247 (9.72)	100 (3.94)	228 (8.98)	265 (10.43)

240/480 Vac 3 Phase (187-528 V)	Continuous Current (Arms)	Peak Current (Arms)	Drive Continuous Output Power Capacity (Watts)	Internal Regen (Watts) (Ohms)		Height mm (in)	Width mm (in)	Depth mm (in)	Depth with Cable Bend Radius mm (in)
AKD-x00307	3	9	2000	100	33	256 (10.08)	70 (2.76)	185 (7.28)	221 (8.70)
AKD-x00607	6	18	4000	100	33	256 (10.08)	70 (2.76)	185 (7.28)	221 (8.70)
AKD-x01207	12	30	8000	100	33	256 (10.08)	70 (2.76)	185 (7.28)	221 (8.70)
AKD-x02407	24	48	16,000	200	23	306 (12.01)	105 (4.13)	228 (8.98)	264 (10.39)
AKD-x04807	48	96	35,000	–	–	385 (15.16)	185 (7.28)	225 (8.86)	260 (10.23)

For complete AKD servo drive nomenclature, please see page 192.

EtherCAT® PROFINET EtherNet/IP SERCOS interface SynqNet CANopen Modbus/TCP HTTP UDP UL LISTED CE ISO RoHS EAC

Feedback & I/O

AKD® servo drive is specifically designed with the versatility, communications, and power you need to expand machine performance and increase integration speeds. Motor set-up is plug-and-play and multiple Ethernet connectivity options provide both open and closed protocols. Online troubleshooting and data verification enable faster, bug-proof programming. And a broad power range in a smaller, compact design allows you to use these robust drives with a single interface while experiencing industry-leading, high-performance servo loops.

AKD Specifications

	Standard Drive	With I/O expansion - AKD-T only
Encoder Output or AUX Encoder Input	2.5 MHz Maximum line frequency	
Feedback	Smart Feedback Device (SFD), EnDat2.2, EnDat2.1, BiSS, analog Sine/Cos encoder, incremental encoder, HIPERFACE®, and resolver	
Logic supply	24 Vdc	
Digital input (24 Vdc)	8 (1 dedicated to enable)	20 (1 dedicated to enable)
Digital output (24 Vdc)	3 (1 dedicated to fault relay)	13 (1 dedicated to fault relay)
Analog input (+/- 10 Vdc, 16-bit)	1	2
Analog output (+/- 10 Vdc, 16-bit)	1	2
Programmable inputs	7	19
Programmable outputs	2	12
Sink/Source inputs/outputs	Yes	Yes

Servo Drive Accessories

Ethernet Connectivity

- Ethernet-based AKD servo drive provides the user with multiple bus choices
- EtherCAT® (DSP402 protocol), Modbus® TCP, SynqNet®, EtherNet/IP™, PROFINET® RT, SERCOS III, and CANopen®
- No option cards are required

Industrial Design

- Rugged circuit design and compact enclosure for space-saving, modern appearance – minimizes electrical noise emission and susceptibility
- Full fault protection
- UL, cUL listed, CE, and EAC
- No external line filters needed (480 Vac units) for CE & UL compliance
- Removable screw terminal connectors for easy connections
- DC Bus sharing

Safe-Torque-Off (STO)

- Switches off the power stage to ensure personnel safety and prevents an unintended restart of the drive, even in fault condition
- Allows logic and communication to remain on during power stage shut down
- AKD-x003 – AKD-x024: SIL2 / PL d
- AKD-x048: SIL3 / PL e

Internal Regenerative Braking Resistor

(all models except 120/240 V AC 3 Aeff and 6 Aeff , as well as 480 V AC, 48 Aeff)

- Simplifies system components
- Saves overhead of managing external regeneration when internal regeneration is sufficient

Performance Servo Tuner (PST)

- Exclusive patent pending auto-tuner reaches optimized set-up in seconds
- Handles inertia mismatches up to 1000:1
- Industry leading bandwidth under compliant and stiff load conditions, no matter the mechanical bandwidth of the machine

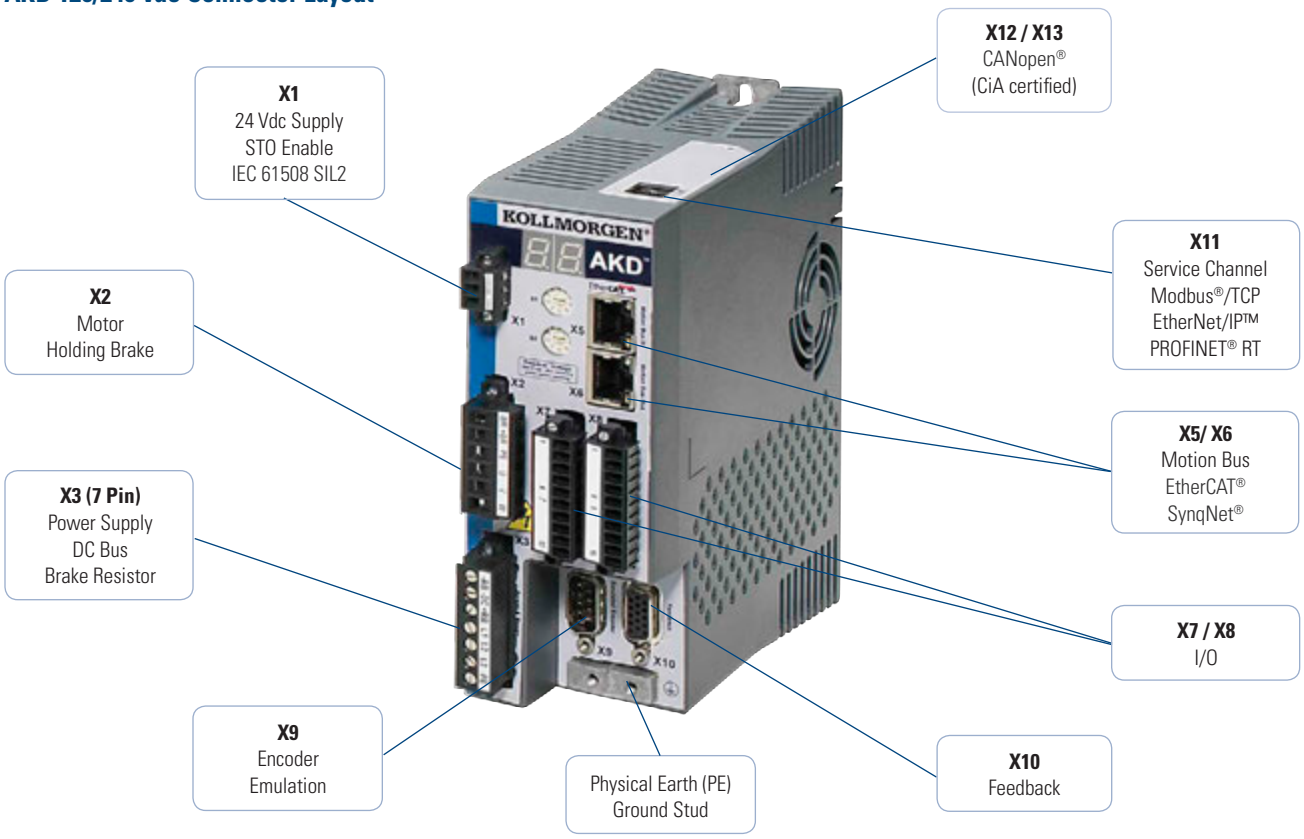
Plug-and-Play with Kollmorgen Motors and Actuators

- Electronic motor nameplates allow parameters to automatically load for fast commissioning
- Motion in seconds
- Custom motor parameters easily entered

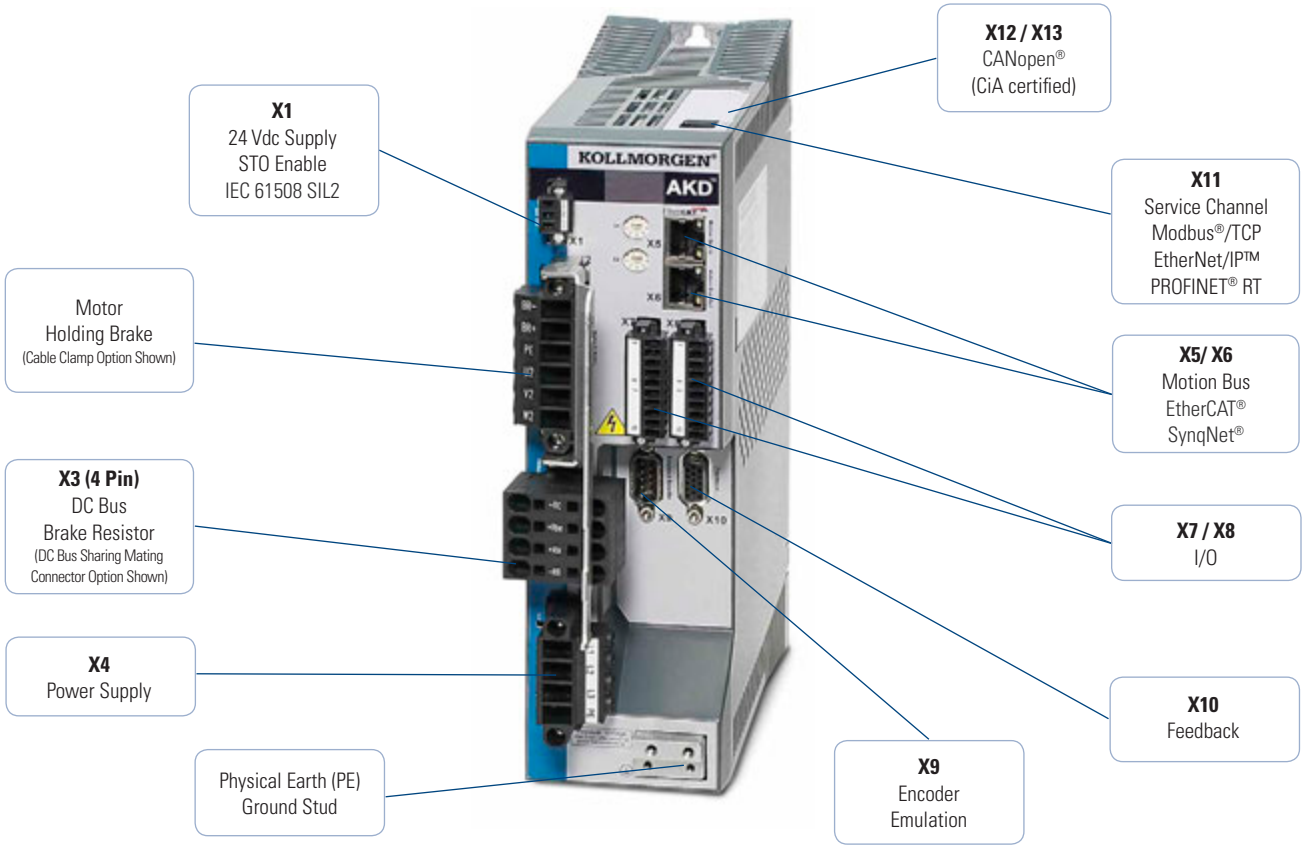
I/O (Base Drive)

- 8 digital inputs (1 dedicated to enable)
- 2 high-speed digital inputs (maximum time delay of 1.0 µs)
- 3 digital outputs (1 dedicated to fault relay)
- 1 analog input - 16 bit
- 1 analog output - 16 bit

AKD 120/240 Vac Connector Layout



AKD 240/480 Vac Connector Layout

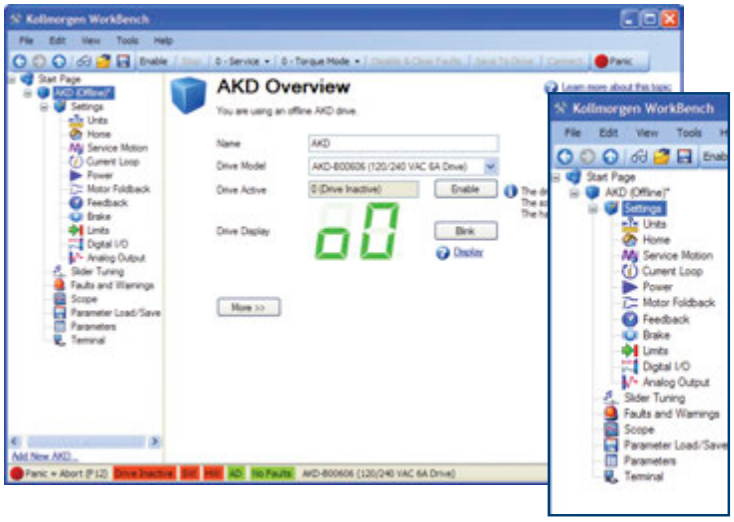


Kollmorgen Workbench

Our simple Graphical User Interface (GUI), Kollmorgen WorkBench, is designed to expedite and streamline the user's experience with the AKD® servo drive. From easy application selection and reduced math, to a sleek six-channel scope; the user interface is extremely easy to use. Kollmorgen WorkBench supports intuitive access to the exclusive Performance Servo Tuner (PST) available inside AKD. The patent pending PST makes auto-tuning the AKD high-performance servo drive with world-class Kollmorgen motors very simple.

User-Friendly Environment

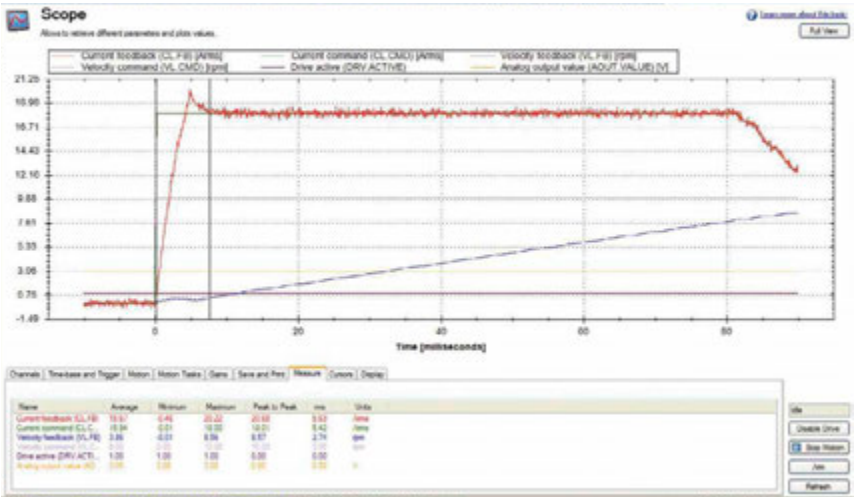
Logical flow, colorful icons and easy access simplify interactions with the AKD servo drive. The folder structure allows for instant identification and easy navigation.



Sleek Six-Channel "Real-Time" Software Oscilloscope

The easy-to-use AKD servo drive interface has a sleek digital oscilloscope that provides a comfortable environment for users to monitor performance. There are multiple options to share data in the format you prefer at the click of a button.

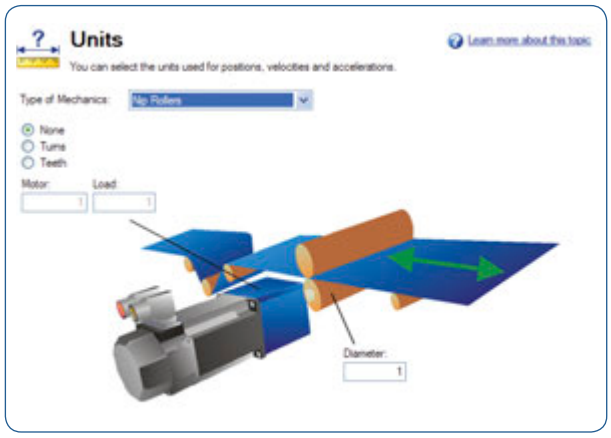
- Save as an image
- Load to an e-mail
- Print



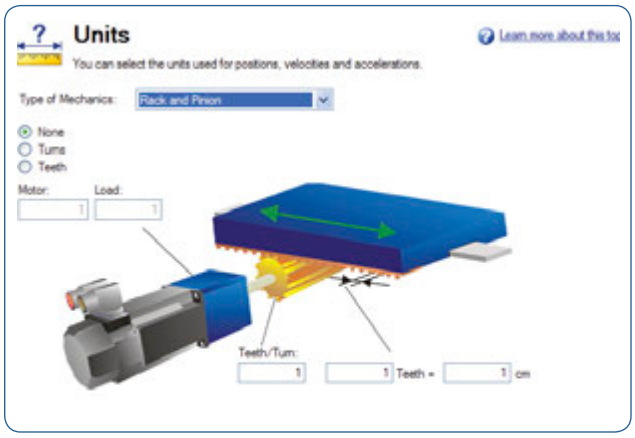
Application Selection

Simplifies set-up by allowing use of machine or application-based units. Nip roller and rack and pinion set-ups shown.

Nip Roller Application Selection

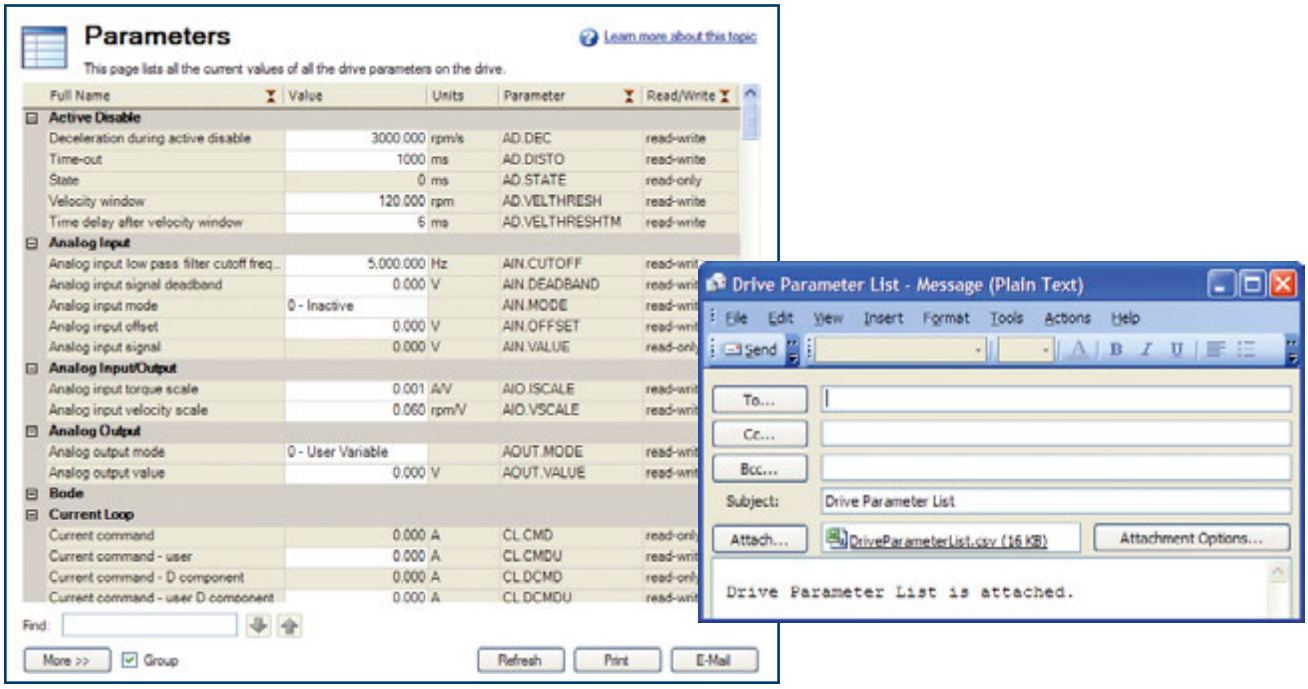


Rack and Pinion Application Selection



Data-Sharing

The ease-of-sharing continues in the parameters window. Kollmorgen WorkBench provides the user the easy options of printing or emailing the parameter values at the click of a button.



AKD®-N Decentralized Servo Drive

The new decentralized AKD-N servo drives from Kollmorgen can be placed in the immediate vicinity of the motor thanks to its robust, compact construction and protection class IP67, plug-in connections, excellent motor compatibility and high degree of integrated functionality. With the decentralized AKD-N servo drives, you can develop drive and automation architectures that are easily comprehensible, and integrate with the central AKD servo drives. Using EtherCAT® as a system bus, we reduce complexity further since the AKD-N can collect I/O signals on the axis and pass them on in bundled form.

Improved Overall Equipment Effectiveness (OEE)

With AKD-N you increase the effectiveness beyond the entire life cycle of your machine (OEE, Overall Equipment Effectiveness). The design configuration and simple connection technology decrease the time for assembly, installation, and start-up. During the operating phase, the AKD-N plays a valuable part in energy savings due to the integrated DC connection. Further advantages in production are faster cleaning cycles, thanks to a higher protection class, as well as fewer cables in combination with a space-saving switch cabinet superstructure. Moreover, the assembly and connection technology increases the availability – and thereby productivity – because maintenance and service tasks are completed faster.

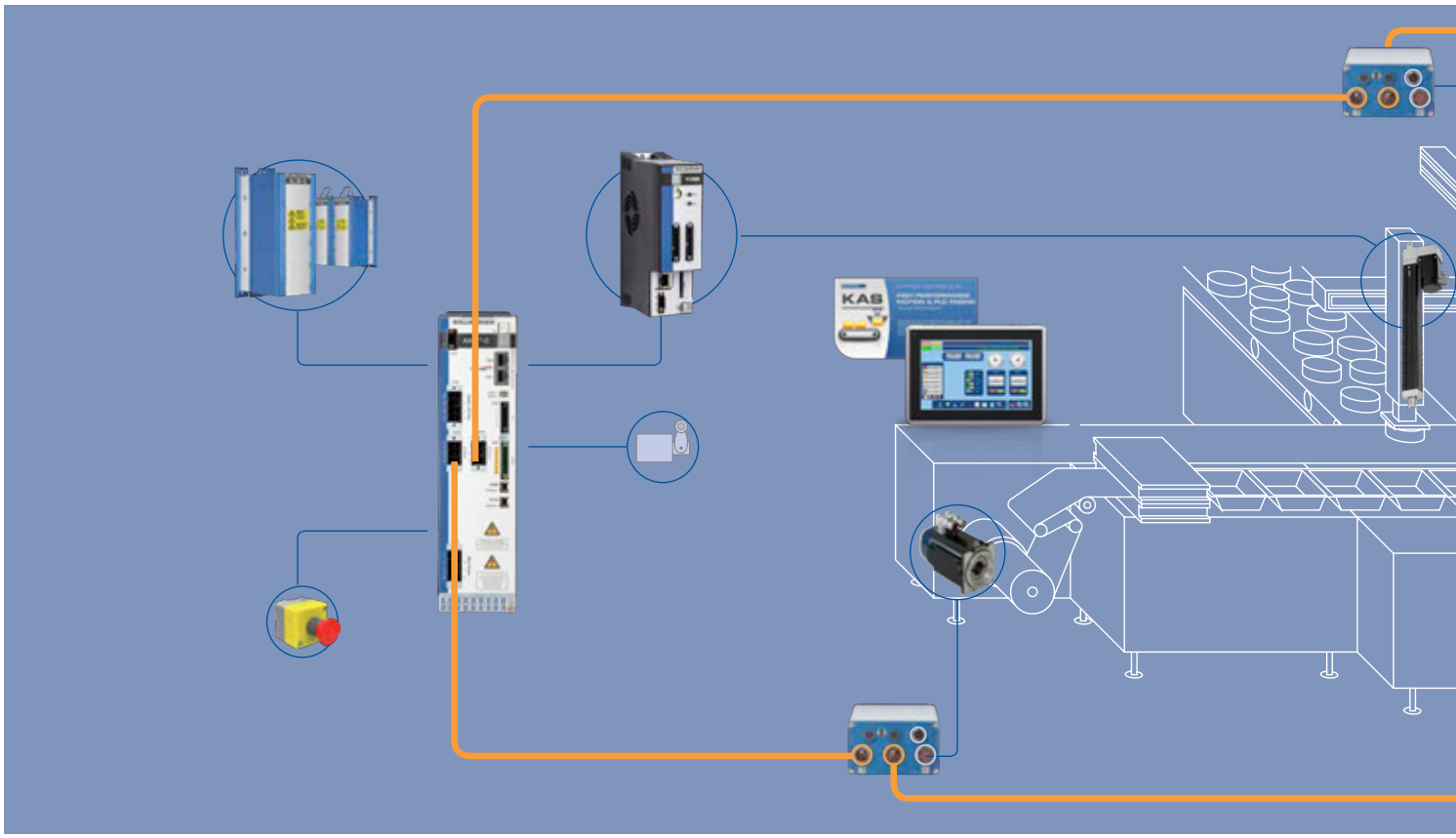
The Advantages of Decentralized Servo Drives

• Reduced costs	• Reduced cabling because DC and network, power supply, I/O level as well as safety (STO) run in one cable • Faster and simple assembly, even without special knowledge, through ready-made and tested cables • Lack of derating enables smaller motor and servo drive combinations compared to integrated system with the same output power
• Compacter machines	• Smaller and therefore more easily integrated switch cabinets • Servo drives in the immediate vicinity of the motor • Robust construction in Protection class IP67 makes protective enclosures superfluous
• Faster startup	• Plug connectors in IP67 for connection without tools • At only eleven millimeters, the thin hybrid cable can be laid in a space-saving manner – even in tight machine corners, thanks to a small bending radius • Simple connection of I/O systems or networks directly to the drive • Parameterization with the tools of the Kollmorgen WorkBench
• Higher machine effectiveness (OEE)	• Design supports fast and effective cleaning • High operating safety through robust construction • Precision through digital feedback • Everything at a glance: Status display on servo drive
• More flexibility in machine design	• Compatible with all motors from Kollmorgen with single-cable, or dual-cable, connection • Simple combination of central and decentralized controllers within the comprehensive AKD family • Faster modification and upgrade options through linear topology as well as I/O and network interfaces at the axis

AKD®-N Decentralized Servo Drives

Next Gen Machine Design Now

Next gen design requires the perfect interplay of standardized drive and automation components. Selection of a functional, freely scalable solution ultimately ensures the highest degree of design freedom in building machines that operate efficiently without complexity.



Kollmorgen Automation Suite™

- Scalable automation solution for drive-dominant applications
- Graphic motion programming
- Compatible with IEC 61131-3 and PLCopen Motion Control

AKD-C Central Power Supply Module

- Power supply for up to 16 AKD-N
- Complete integration in the AKD family
- EtherCAT® Network
- 2 STO inputs SIL 2 / PLd
- 1 each digital input and output, 1 relay output

AKD-N Distributed Servo Amplifier

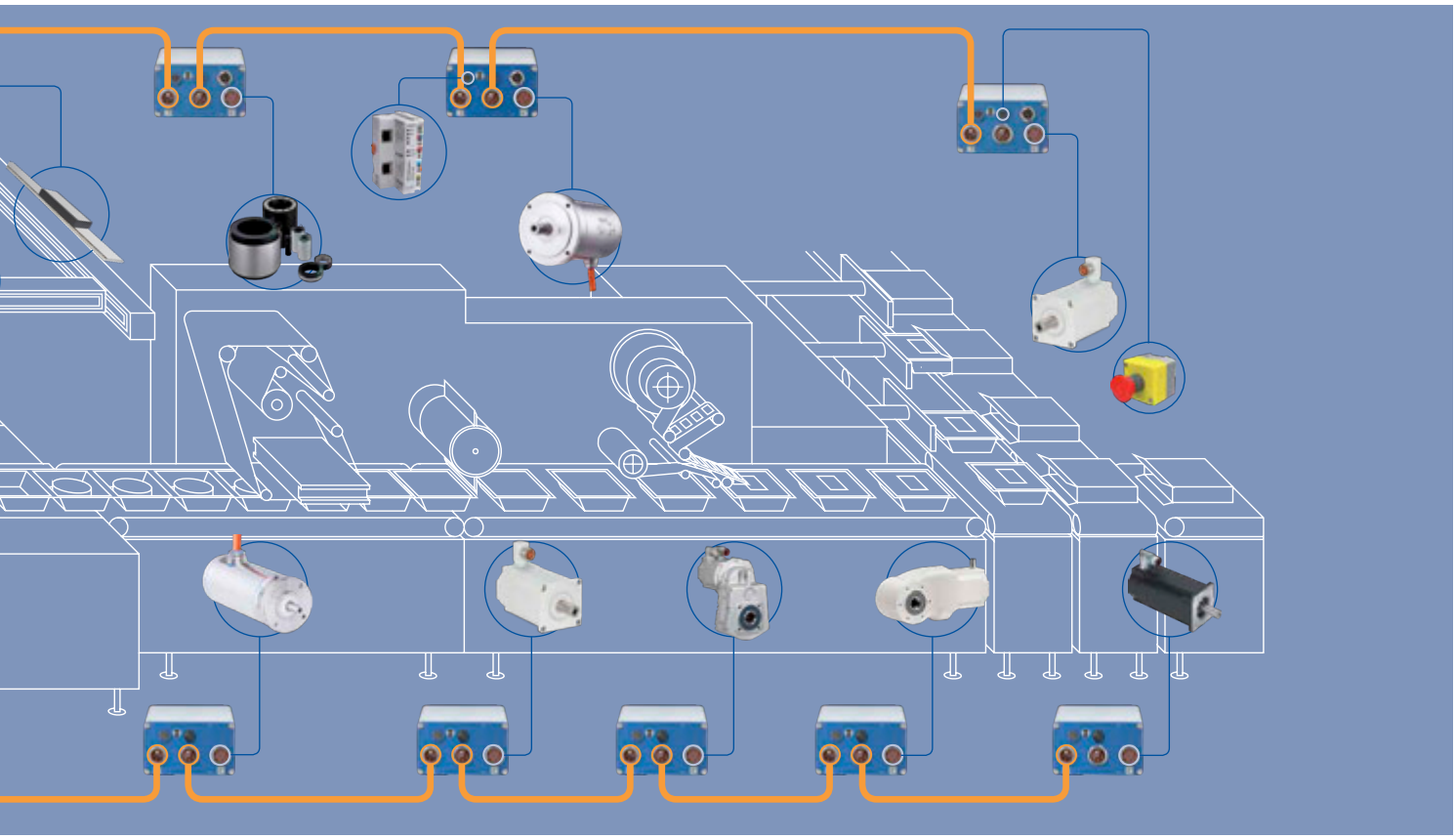
- Less cabling through single-cable solution
- Fast installation, simple assembly and connection
- IP65/IP67, UL design 4x
- Options: local EtherCAT® interface or local STO (SIL2/PLd), connection for feedback systems

PCMM™ Stand-Alone Controller

- Up to 128 axes of coordinated motion with a single controller
- Up to 1.2GHz CPU for both motion and machine control
- PipeNetwork™ motion engine for visual programming or PLCOpen Motion engine
- High performance control with flexible cycle time as low as 250 µs
- 100BaseT connection supporting MODBUS TCP/IP, EthernetIP®, Profinet®, HTTP, and UDP

KCM Condenser Modules

- Reduces the energy costs and prevents downtime
- Simple implementation
- No harmonics in the power cables
- Scalable capacity



AKM® Servo Motors

- High torque density
- High precision and dynamics
- Produced in Europe, US and Asia regions

AKM® 2G Servo Motors

- Average continuous torque increases of 30% or greater
- The same performance in 20% less space.

AKM Washdown Servo Motors

- Applications with regular cleaning
- Housing coating is Ecolab®-certified

AKM Washdown Food Servo Motors

- For use in the food and beverage industry
- Protection class IP67, FDA compliant

AKMH™ Stainless Steel Motors

- For the highest hygienic requirements
- Protection class IP69K
- Fulfills EHEDG directive

AKM Food-Grade Gearmotor

- The highest hygienic requirements
- High efficiency
- Single-cable connection

Cartridge Direct Drive Rotary® DDR

- Direct load coupling without gears or belts
- High precision, low noise generation

KBM Direct Drives with No Housing

- Low weight, exceptionally compact
- Modular system

DDL Ironcore ICH Motor

- High power density
- Large dynamics (>10g)
- Patented anti-cogging design

AKD®-N Decentralized Servo Drives

Our Way of Making Machines Simpler and More Efficient

- Advantage: Lower machine complexity
- Advantage: Greater freedom of design
- Advantage: Higher OEE (Overall Equipment Effectiveness)

Complete integration in the AKD family

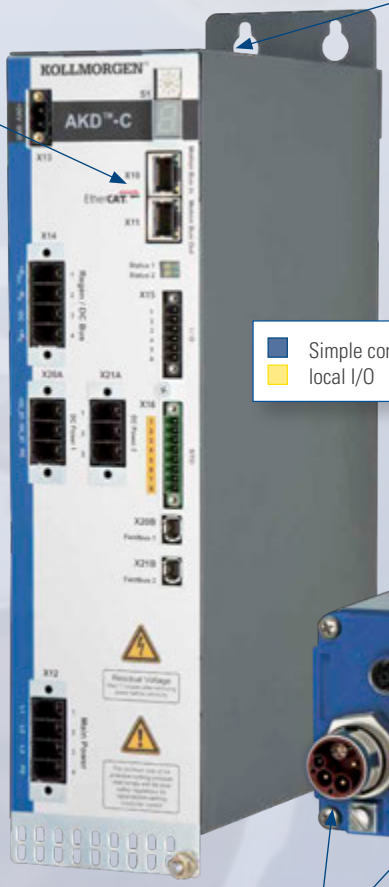
Decentralized solution reduces effort and costs for switch cabinet

Startup with the Kollmorgen WorkBench

MotionBus (EtherCAT®) for connection to automation systems

Connection of external additional components

A single AKD-C supplies up to 16 AKD-N



Status LED for simple diagnosis

Simple connection of local I/O

Options like tertiary network and local STO offer maximal flexibility

IP67 / UL type 4x housing reduces cleaning times and makes special protective enclosures redundant.

Simple and fast attachment

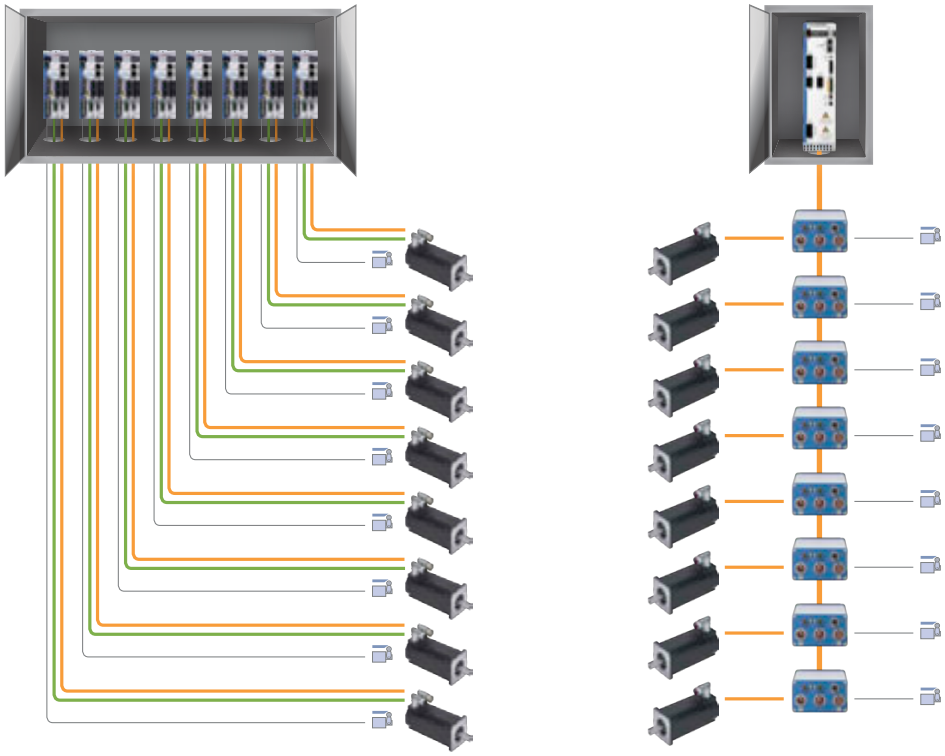
Compatible with all motors from Kollmorgen

A single cable with 11 mm diameter for DC bus, electrical supply, EtherCAT® network and STO reduces cabling outlay, increases the reliability and enables flexible machine design

Hybrid motor cable for simplified cabling, faster installation and higher reliability

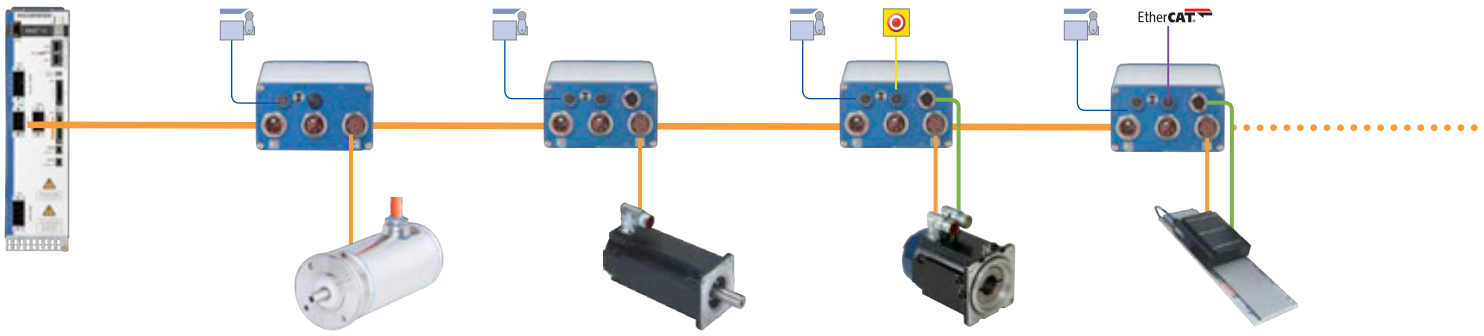
Why Lay 372 m. of Cable when 42 m. Will Suffice?

Imagine your machine includes eight axes each with a distance of three meters. The switch cabinet is 5 meters away and on each axis there is also a switch. With this thoroughly realistic example, that equates to a total of 372 meters of cable – with our AKD-N it would have been 42 meters. The decentralized servo technology of the AKD-N saves 330 meters here! That is cable that does not have to be purchased or laid and which does not require any space in the machine construction. We find that these are very good grounds for starting the comparison. We combine the AKD-N servo controllers and their power supply modules with pre-assembled and tested system cables – it doesn't get much simpler than this.



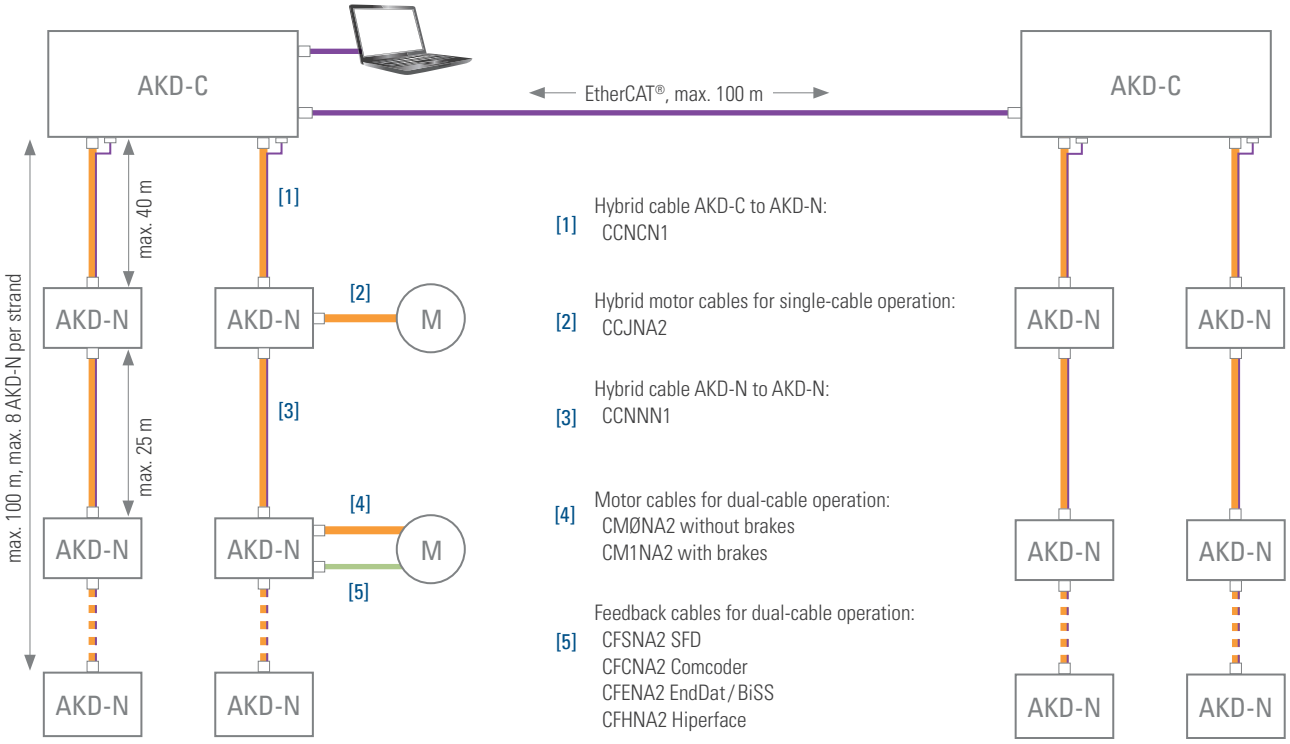
Regardless of which Motor: Plug and Play

Our AKD-N decentralized servo controllers work optimally with every motor. Within our Kollmorgen system, you can also thoroughly use all advantages of the single-cable connection technology individually.



AKD®-N Decentralized Servo Drives

Technical Data and Topology



AKD-N Decentralized Servo Drives

Continuous current	3 A, 6 A, 12 A
Peak current	9 A, 18 A, 36 A
Continuous input power	1.5 kVA, 3 kVA, 6 kVA
Protection class	IP67
Digital inputs/outputs	3 digital inputs / 1 digital output
Safety function	STO SIL 2 (only AKD-N-DS)
Feedback systems Dual-cable (not with -DB)	SFD (digital resolver), BISS-C, Comcorder, hall sensor, Endat 2.1 and 2.2, Hiperface
Feedback systems Single-cable	SFD3 (digital resolver)
Communication	EtherCAT
Dimensions (W x H x D)	Housing: 3 A, 6 A: 130 x 75 x 201 (mm) 12 A: 130 x 75 x 301 (mm) With plugs 3A, 6 A: 130 x 75 x 228 (mm) 12 A: 130 x 75 x 328 (mm)

AKD-C Power Supply Module

Line voltage	400 / 480 V
Overall performance	10 kW
Intermediate circuit voltage	560 / 680 V DC
Output current	17 A (peak 34 A)
Protection class	IP20
Output strands	2, for up to 8 AKD-N apiece
Safety function	one STO Enable and STO Status apiece for each strand, SIL 2
Digital inputs/outputs	1 input, 1 output, 1 relay output
Communication	EtherCAT®, TCP/IP service interface
Dimensions (W x H x D)	Housing (Front) 80 x 260 x 198 (mm) Installation dimension with plugs 80 x 329 x 231 (mm)

For complete AKD-N and AKD-C nomenclature, please see page 192.

Connections and Controls

[1] Network connection for service PC (TCP/IP) (on the top)

[2] Setting the IP address

[3] 24 V DC power supply

[4] Error and status displays

[5] Motion Bus I/O connections (EtherCAT®)

[6] Status display of the local network

[7] Connection for external brake resistor and KCM buffer module

[8] I/O (1 each digital input and output, 1 relay output)

[9] DC outputs for connection of up to eight decentralized AKD-N servo drives apiece

[10] STO input, STO status output (one each per strand),

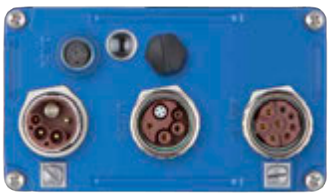
[11] Local network for communication with AKD-N

[12] Power connection 400 V / 480 V AC

Connection Options for AKD-N

AKD-N-	Single-cable technology	Separate feedback	Digital I/O	Tertiary fieldbus	Local STO
DB	✓	—	✓	—	—
DF	—	✓	✓	✓	—
DG	✓	—	✓	✓	—
DS	—	✓	✓	—	✓
DT	✓	—	✓	—	✓

AKD-N-DB



[1] [2] Connections for hybrid cable

[3] Motor connection

[4] 3 digital inputs, 1 digital outputs

[5] Status/error display with LED

AKD-N-DF, -DS

[6] STO connection (-DS) / Tertiary fieldbus (-DF)

[7] Connection for feedback with dual-cable technology

AKD-N-DG, -DT

Servo Motors

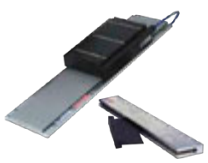
When you need precise position control, choose from Kollmorgen's broad portfolio of servo system components. Our unparalleled product line breadth provides great flexibility for any application. Whether it's any combination of motors and drives, cables, controller, electric cylinders or gearboxes, all components are plug-and-play for easy, seamless integration. These best-in-class servo systems can be matched with single-axis or multi-axis motion controllers for a system solution that's precise, reliable and durable.

The Advantages of Kollmorgen Servo Motors

• Optimized AKM family and direct drive motor windings for the AKD® family of servo drives • Amplifier and motor dimensions reduced • Lower system costs	• With the same size, the AKM offers up to 47% more power on the motor shaft • For a given frame size the AKM2G provides an average continuous torque increase of 30% compared to most competitive motors of equivalent size
• Quicker start-up of all servo systems • Immediate and adaptive reaction to dynamic loads optimizes performance within seconds • Precise regulation of all motor types • Compensation for stiff and compatible gearboxes and clutches	• Start-up of amplifiers with plug-and-play detection for AKM family and Cartridge DDR series motors
• More precise machines due to higher resolution and improved accuracy • With multi-turn absolute encoders: reduced cycle times and lower costs for sensors and cabling through the omission of conventional reference run methods	• New, cost-efficient multi-turn feedback options
• Machine design independent of motor size • Installation of motors in the tightest space	• Motors with the highest power densities in the whole industry
• Millions of standard motor versions available in various mounting, connection, and feedback variants, as well as further options • Available with single cable technology with digital feedback (Kollmorgen exclusive SFD3, HIPERFACE® DSL or EnDat 2.2) • Our flexible products deliver a perfectly suited solution to your application • Simplifies mechanical modifications and design adjustments or renders them totally superfluous	• AKM offers 28 housing and design length combinations, as well as 120 different standard windings for a single motor series • AKM2G is available in 6 frame sizes, 23 frame-stack length combinations, and 70 standard windings • The AKM2G design has the potential for greater CoEngineering (modification) thanks to the new housing design. With a more flexible design for CoEngineering addressing applications not covered by catalog standards is increased
• AKM Washdown and AKM Washdown Food offer maximum reliability and a long service life for the most demanding industrial applications • AKM2G is available with the choice of optional Mineral filled PTFE shaft seal (Teflon®) for dry running environments or Viton® shaft seal for wet running environments	• AKM and AKM2G are available in standard IP54 rating (AKM1 standard IP40) or optional IP65 with shaft seal. AKM is also available with IP67 rating

Kollmorgen Servo Motor Overview

Kollmorgen offers a comprehensive range of servo motors including electric cylinders, rodless actuators, and precision tables to meet a wide range of application requirements. For actuator products not included in this catalog go to www.kollmorgen.com for information about other Kollmorgen linear positioning products.

	Model	Product Family	Applications
	AKM®2G and AKM® Servo Motors	AKM	Designed with industry leading torque density and configurability. The medium-inertia AKM line includes over 4.8 million standard options to fit applications from general automation to applications that require IP67 sealing. The low-inertia AKM2G expands the AKM family to offer smaller footprint, higher torque versions for applications requiring the maximum torque density and the highest dynamic performance.
	AKMH IP69K Hygienic Motors	AKMH	The AKMH meets the food industry's strictest hygienic design criteria while being rugged enough to withstand the toughest of daily washdown regimens. Perfect for Food Processing, Primary Food Packaging, Pharmaceutical and Medical applications.
	Cartridge Direct Drive Servo Motors	CDDR	The CDDR is designed to provide the benefit of embedded frameless motor technology in an easy-to-integrate package. Perfect for applications in Printing, Packaging and Converting.
	Housed Direct Drive Servo Motors	HDDR	Housed DDR motors are designed for precise positioning of larger loads without the use of a mechanical transmission. Increasing OEE through the removal of belts and gearboxes that fail unexpectedly or require frequent maintenance.
	KBM Frameless Direct Drive Motors	KBM	With a wide variety of sizes and an extensive range of torque and speed options the KBM frameless direct drive motors are engineered to provide the high-performance, long life and simple installation that today's design engineers demand.
	TBM Frameless Direct Drive Motors	TBM	The Kollmorgen TBM frameless direct direct drive motors are designed for applications that require high power in a small, compact form factor with minimized weight and inertia. These motors provide the highest performance in applications such as robotic joints, medical robotics, sensor gimbals, guidance systems and other motion-critical applications.
	Direct Drive Linear Servo Motors	IC IL	Ideal for applications requiring very low bearing friction, high acceleration of lighter loads, and for maximizing constant velocity, even at ultra low speeds.

Model	Product Family	Features
AKM®2G and AKM® Servo Motors	AKM	Designed to deliver precise motion and more power for your money. More than 500,000 standard configurations that include various feedback, connector, paint and sealing options.
AKMH IP69K Hygienic Motor	AKMH	The AKMH is designed to withstand the toughest of daily washdown regimens without the need for covers. The AKMH's hygienic design makes it easy to clean, keeping your machine running and protecting your brand. Designed with a single cable that combines power, feedback and an innovative venting feature that extends the life of the motor.
Cartridge Direct Drive Servo Motors	CDDR	The CDDR is a patented design that allows for this torque dense frameless motor to be installed on your machine in 5 minutes. The CDDR lowers your machines maintenance, increases your machines uptime and increase your machines peformance.
Housed Direct Drive Servo Motors	HDDR	Housed DDR motors are maintenance free and run more quietly and with better dynamics than systems that use gears, belts, cams or other mechanical transmission components.
KBM Frameless Direct Drive Motors	KBM	KBM motors cover a range of frameless motor solutions across a variety of applications. KBM is engineered to provide the high-performance, long life and simple installation that today's design engineers demand.
TBM Frameless Direct Drive Motors	TBM	Typical applications include robotic joints, weapon stations, sensor gimbals, sight systems, UAV propulsion and guidance, as well as many others.
Direct Drive Linear Servo Motors	IC IL	Kollmorgen linear motors provide precise placement of product by directly coupling to your load and eliminating the backlash associated with high maintenance linear transmission components.

AKM® Servo Motor

Kollmorgen's AKM family of servo motors gives you unprecedented choice and flexibility from a wide range of standard products so you can select the best servo motor for your application. By pairing AKM servo motors with our family of plug-and-play AKD® servo drives, selecting the right motion control products has never been easier. Pick from thousands of servo motor/servo drive combinations outlined in this selection guide or go to our website to find the best solution for your application.

Standard AKM family of servo motors and AKD family of servo drives offer the best of both worlds – the exact specifications of a custom solution with the faster delivery times and lower cost of a standard catalog product. For your truly unique motion control applications, work with our engineering team to customize a solution for your machine design. Either way, standard product or customized, we can help you choose the motion control solution that meets your exact requirements.

The Benefits of AKM® Servo Motor

• Best-in-Class Performance	• Industry-leading motor power density • Same size AKM/AKD family system delivers up to 47% more shaft power • Compensation for stiff and compliant transmissions and couplings • Exceptionally low cogging
• Flexibility to Find an Exact-fit Solution in a Standard Product	• AKM offers 28 frame-stack combinations and 120 standard windings in a single motor line • 4.8 million possible AKM part number combinations and growing • Simplifies or eliminates mechanical modifications and engineering adaptation • Available with single cable technology with digital feedback (Kollmorgen exclusive SFD3 or HIPERFACE® DSL) • Washdown and Food Grade options for AKM • Higher torque models up to 180 Nm of continuous torque
• Ease-of-Use and Faster Commissioning	• Plug-and-play motor recognition drive commissioning • Reduce cycle time and sensor-and-wiring costs by eliminating traditional homing methods • Reduction in set-up time for each servo system

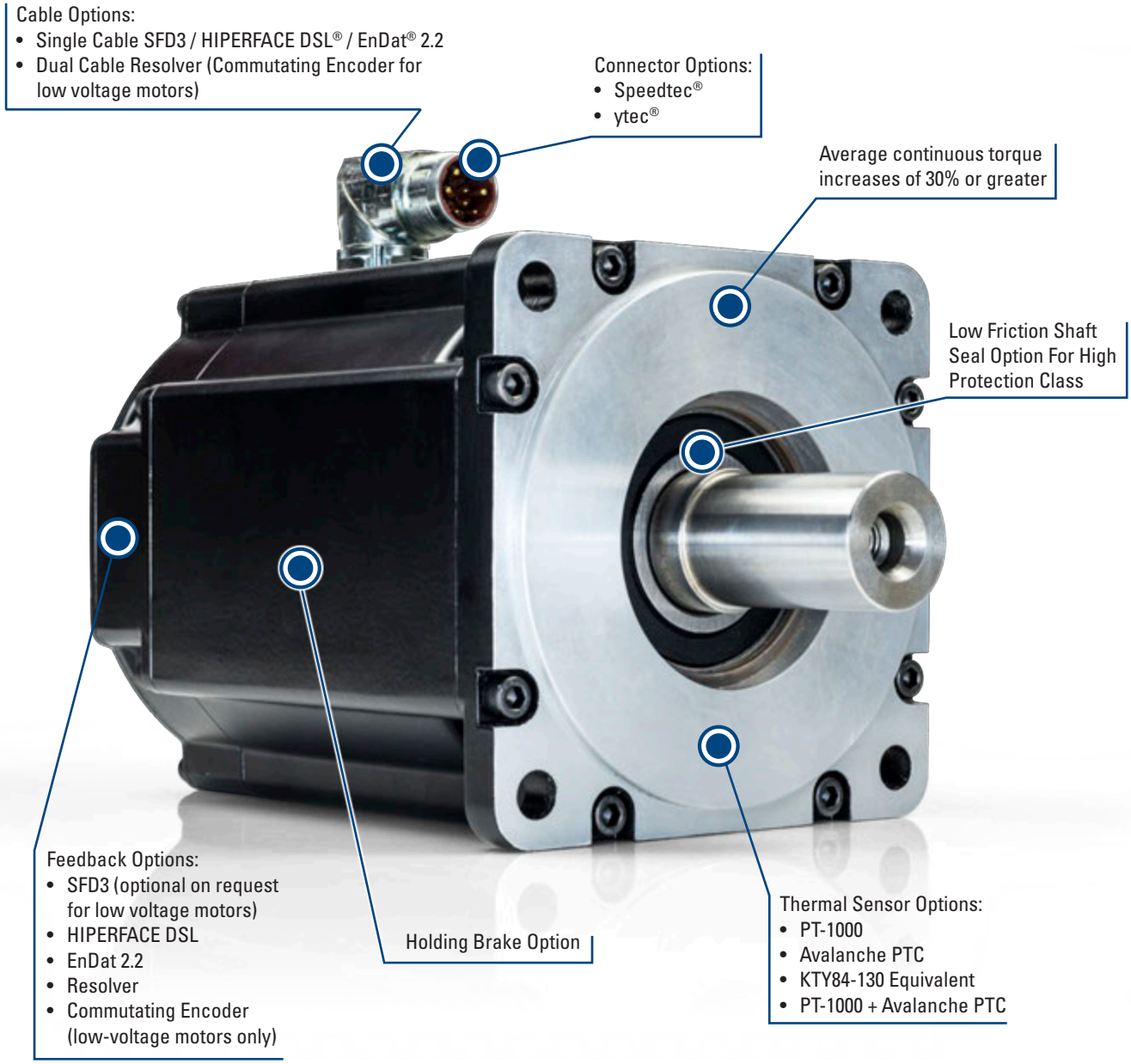
AKM® 2G Brushless Servo Motor

AKM® 2G represents the latest evolution of the industry leading AKM motor product family.

With average continuous torque increases of 30%, OEMs and users can achieve substantial machine performance increases without increasing the size of the motor.

The improved torque density allows a smaller motor to be used which reduces the machine footprint without sacrificing performance.

- Extensive Selection of Feedback options to match application and performance requirements
- Shaft, mounting and connector options for optimal flexibility
- Holding Brake option



Get the same performance in 20% less space.

For new machine designs, the AKM2G allows customers to decrease the size, footprint, and complexity of the machine, while still getting the power and performance they need.

The AKM2G drops right into existing machine designs to increase performance, when compared to competing motors, without increasing the size of the motor.

The AKM2G features six sizes with performance levels between 0.3 and 10kW. It offers selectable options such as feedbacks, mounting configurations, and performance capabilities. Due to the modular structure of the motor, Kollmorgen is better equipped than competitors to adapt motors to the requirements of a specific application in parallel with standard production needs. Machine builders are then able to choose from a wider range of standard models that leverage Kollmorgen's extensive product and application knowledge.

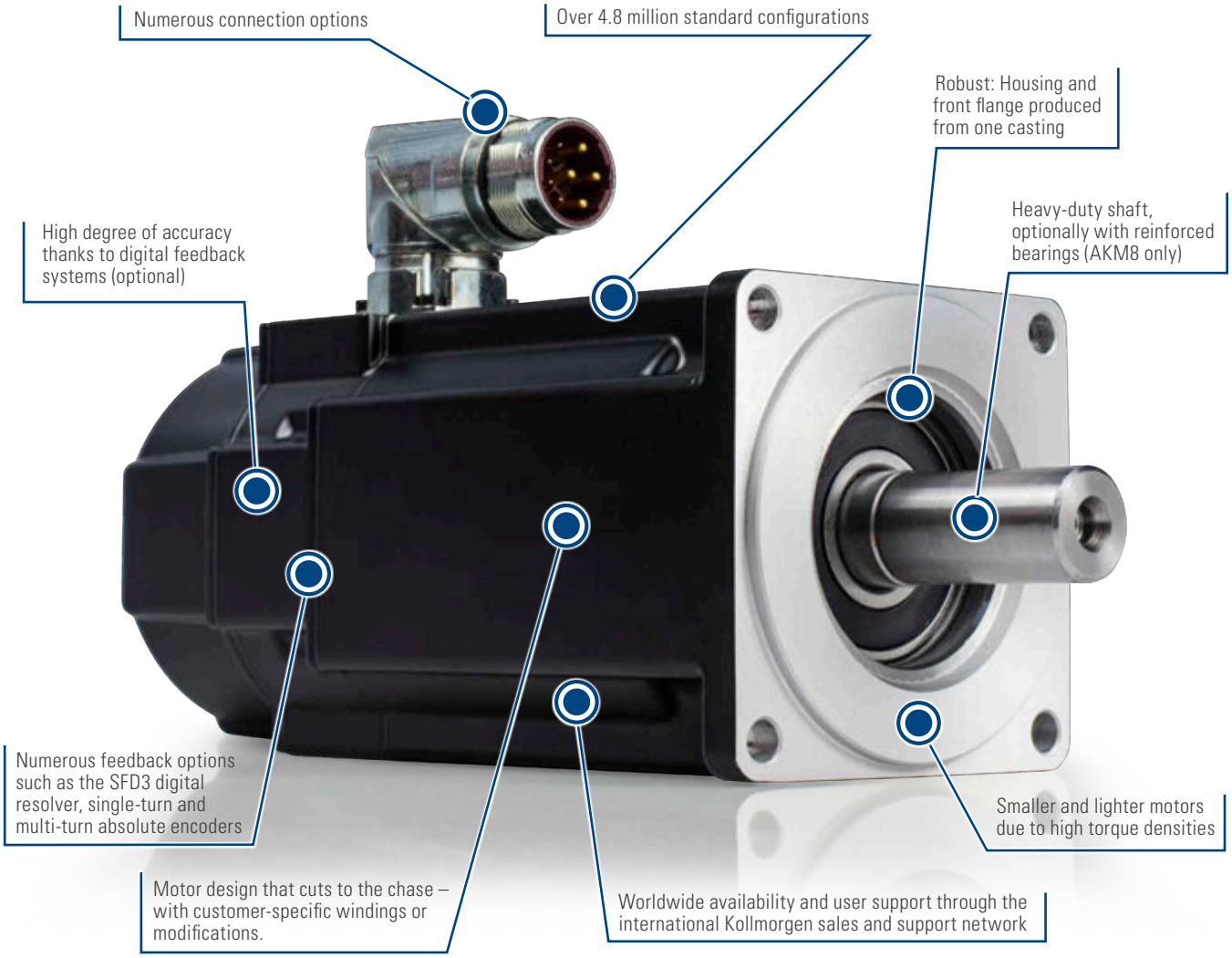
The Benefits of AKM2G Servo Motor

Smaller Footprint	**Reduce machine space** • For equivalent torque it is possible to use a smaller size motor than most competitive motors. • The range of AKM2G sizes provides for optimizing for length or flange square depending on which dimension is most critical. • Use of the smaller motor saves space achieving equivalent performance in a smaller footprint machine or saving space for other machine elements.
Increased Torque	**Higher performance** • For a given frame size the AKM2G provides an average continuous torque increase of 30% compared to most competitive motors of equivalent size. • Higher torque in the same package size increases machine performance (greater throughput, move heavier loads, etc.).
Wider Speed Range	**Faster operation** • For many AKM2G sizes the maximum speeds are higher than competitive motors. • Higher speeds ⇨ operate machines faster ⇨ greater throughput.
Greater Flexibility	**More options to match needs** • AKM2G is designed to support a wider array of feedback, brake, thermal sensor and shaft seal options – this greater flexibility means a higher probability of meeting application requirements with a standard product. • The AKM2G design has the potential for greater CoEngineering (modification) thanks to the new three-piece housing. With a more flexible design for CoEngineering addressing applications not covered by catalog standards is increased. • Standard voltage selections of 24, 48, 72 and 96 Vdc meet most available power sources for Low Voltage motors. 120, 240, 400 and 480 Vac for higher voltage systems. • Kollmorgen can work with you to meet your specific requirements for the exact solution you need.
Higher Efficiency	**Reduce energy consumption** • AKM2G has lower equivalent resistance than many competitive solutions. For equivalent motor frame sizes AKM2G will typically be more energy efficient (2-5%). • Energy consumption is reduced with AKM2G compared to many competitors. • When weight and space are critical such as on portable, mobile or battery power applications higher efficiency translates to a smaller motor with lower energy demand.

AKM2G Series Servo Motor Family

AKM® Brushless Servo Motor

The AKM® brushless servo motor stands alone in the marketplace in terms of flexibility and performance advantages. Kollmorgen's culture of continuous improvement has paid dividends again. The AKM servo motor's innovative design has been polished and optimized. With the AKD® amplifier and the new AKD®2G amplifier, the distinguished AKM servo motor sets a new standard of refined servo performance, designed to deliver precise motion and more power for your money. Nowhere else will you find a more versatile and complete servo family to meet your needs and exceed your expectations.



- 8 frame sizes from 40 to 260 mm
- 28 housing and design length combinations
- 120+ standard windings for 120/240/400/480 V
- Winding options for low DC voltage
- Numerous flange and shaft options
- Minimal cogging and high degree of efficiency
- Extensive customization options with special windings and shafts

Power Range

AKM frame sizes 1 to 8, standstill torques of 0.16 to 180 Nm, speed range 1000 to 8000 rpm, voltages 75 Vdc, 120, 240, 400, or 480 Vac.

Application Criteria

Universally deployable, brushless servo motors for all positioning and motion tasks with normal and high requirements and with accuracy and speed in a torque range between 0.16 Nm and 180 Nm.

Feedback Systems and Connectivity

Standard with SFD3 and HIPERFACE DSL single-cable options. In addition, AKM supports dual-cable feedback options such as Resolver, Encoder, EnDAT, and BiSS.

Protection Class

IP65 with optional Teflon® shaft seal, IP67 in the Washdown or Washdown Food version (page 70). Standard version IP54 (AKM1 standard version IP40).

Smooth Running and Long Service Life

Very smooth running due to minimal cogging. The single-cast stator ensures high stability and improved heat dissipation from the motor. Front flange and motor housing are produced from a single cast. This ensures a high degree of sealing, strength and a long service life.

High Accuracy

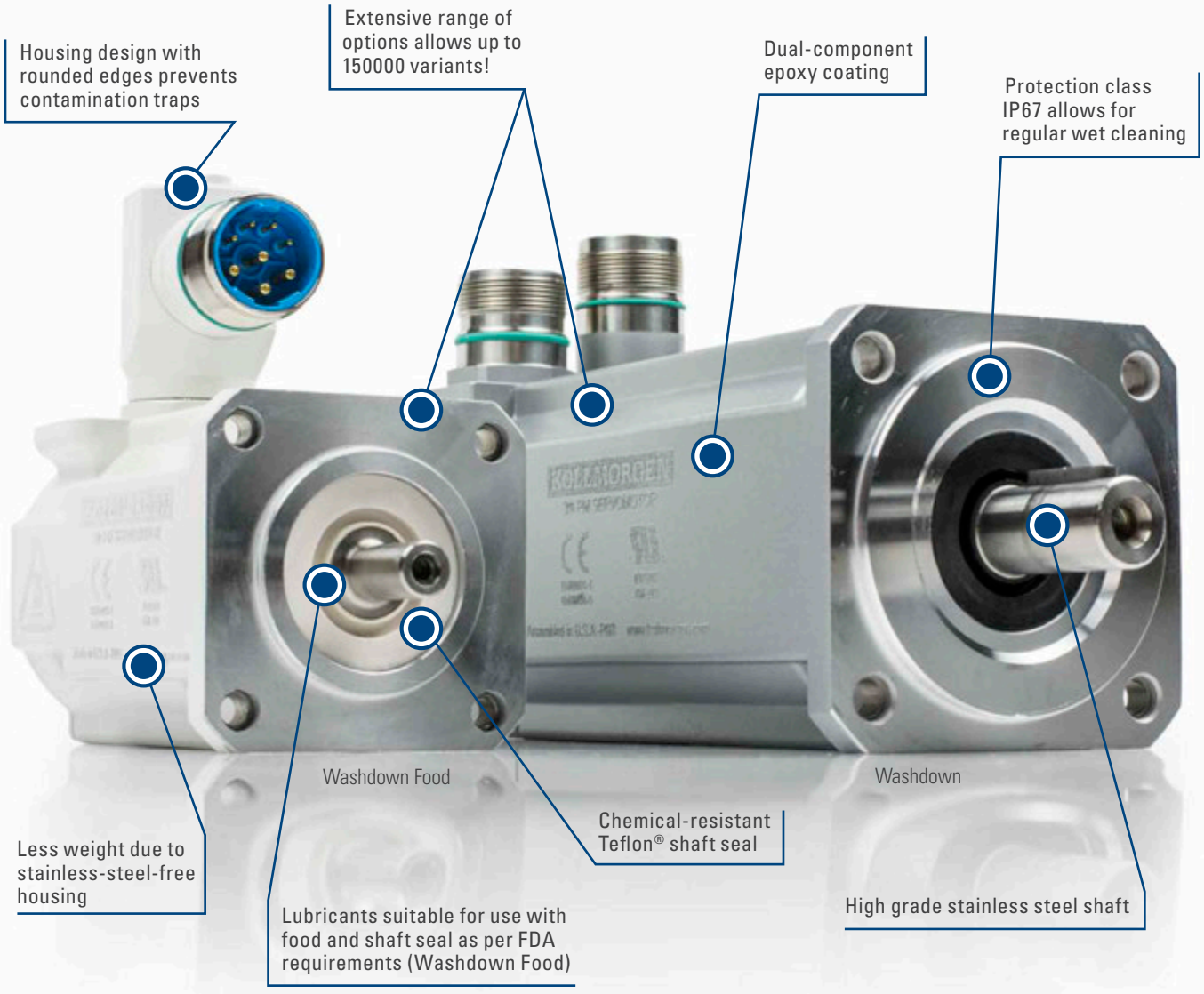
Cable Type	AKM Motor	Single-turn absolute			Multi-turn absolute		
		Accuracy (arc-min)	Resolution (bits)	Feedback type	Accuracy (arc-min)	Resolution (bits)	Feedback type
Value line	AKM1	16	24	CA	–	–	–
	AKM2 - AKM3	9	24	CA	8	18	LB
	AKM4 - AKM8	9	24	CA	4.66	18	LB
Performance line	AKM1	7,2	9	GP	7.2	9	GR
	AKM2 - AKM4	1.0	20	DA	1.0	20	DB
	AKM5 - AKM8	0.333	20	DA	0.333	20	DB

The AKM1 – one of the smallest servo motors on the market offers outstanding power density despite its compact design

AKM® Washdown and Washdown Food

Servo motors Suitable for use with Food

More durable in washdown conditions than standard AKM motors, lighter and more cost-effective than stainless-steel servo motors: In many applications with demanding environmental requirements, the AKM Washdown and Washdown Food versions are good alternatives to costly stainless steel motors or expensive protective enclosures.



Specially for applications with demanding environmental requirements in the

- Packaging industry
- Pharmaceutical industry
- Food industry
- Beverage industry
- Laboratory automation
- Medical device technology

EAC CE ✓RoHS

Power Range

AKM frame sizes 2 to 6 with standstill torques of 1 to 25 Nm, supply voltages of 75 to 480 V, large selection of different construction lengths, winding variants, as well as feedback systems and connection technologies.

Application Criteria

Designed for environments with acids, bases, or aggressive substances such as frequent cleaning with cleaning agents with pH values of between 2 and 12 (painted areas only).

Housing Coating

The coating material of the AKM Washdown motors is resistant to acids and bases and aggressive substances and meets the global migration requirement of the FDA. The rounded and smooth surfaces prevent hazardous contamination traps and germ formation.

Seals and Bearings

Both Washdown versions meet the IP67 protection rating. The proven AKM PTFE shaft seal is used. For the AKM Washdown Food version, the shaft seal meets FDA requirements and only food-safe lubricants are used.

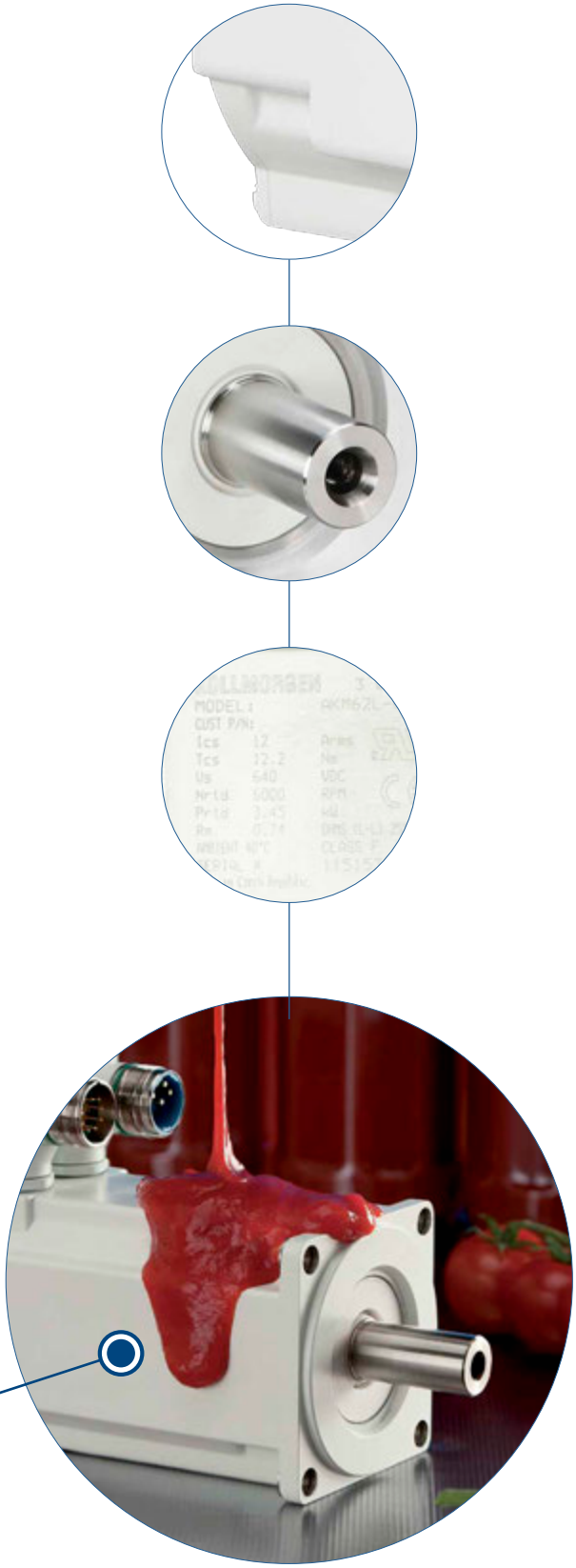
Connectors and Cables

Each connector is a size 1 (M23) special stainless steel design with a smooth surface. Cables with special mating connectors are made from stainless steel or a material appropriate for maintaining food quality. The cables are clamped using a special clamping method.

International Standards

UL, CE, FDA*, RoHS, EAC

*Global migration requirement



Also proven in harsh environments: The AKM Washdown Food is resistant to most acids and bases, as well as aggressive substances.

AKM® Servo Motor Performance Data

AKM2G

Performance Data

Parameters	Frame Size	Max Cont. Torque for ΔT wdg. = 100°C	Max Cont. Current for ΔT wdg. = 100°C	Max Cont. Torque for ΔT wdg. = 60°C	Max mechanical speed	Peak Torque	Peak Current	120 V AC			240 V AC			400 V AC			480 V AC			Inertia (incl. Resolver feedback)	Optional Brake Inertia (additional)	Weight
								Rated Torque (speed)	Rated Speed	Rated Power (speed)	Rated Torque (speed)	Rated Speed	Rated Power (speed)	Rated Torque (speed)	Rated Speed	Rated Power (speed)	Rated Torque (speed)	Rated Speed	Rated Power (speed)			
21D	58	0.636	2.17	0.494	8000	1.78	8.66	0.583	4800	0.293	0.534	8000	0.448	0.525	8000	0.439	0.52	8000	0.435	0.093	0.04	1.1
21E	58	0.642	2.73	0.498	8000	1.79	10.9	0.568	6200	0.369	0.534	8000	0.448	-	-	-	-	-	-	0.093	0.04	1.1
21G	58	0.649	4.18	0.503	8000	1.79	16.7	0.545	8000	0.456	-	-	-	-	-	-	-	-	-	0.093	0.04	1.1
22C	58	1.11	1.65	0.859	8000	3.33	6.62	1.09	1800	0.206	1.04	4400	0.48	0.956	7800	0.781	0.944	8000	0.791	0.155	0.04	1.4
22D	58	1.11	2.37	0.861	8000	3.33	9.49	1.07	2900	0.326	0.991	6600	0.685	0.938	8000	0.786	0.928	8000	0.777	0.155	0.04	1.4
22E	58	1.11	2.93	0.863	8000	3.34	11.7	1.06	3800	0.422	0.955	8000	0.8	-	-	-	-	-	-	0.155	0.04	1.4
23D	58	1.48	2.11	1.15	8000	4.69	8.44	1.45	1800	0.273	1.37	4300	0.615	1.23	7600	0.977	1.2	8000	1	0.217	0.04	1.7
23E	58	1.48	2.92	1.151	8000	4.69	11.7	1.42	2800	0.416	1.29	6200	0.839	1.19	8000	0.993	1.17	8000	0.978	0.217	0.04	1.7
23F	58	1.5	4.07	1.168	8000	4.74	16.3	1.39	4100	0.599	1.22	8000	1.02	-	-	-	-	-	-	0.217	0.04	1.7
24D	58	1.82	2.11	1.41	8000	7.11	8.45	1.76	1500	0.277	1.66	3500	0.607	1.48	6100	0.948	1.39	7400	1.07	0.279	0.04	2
24E	58	1.82	2.92	1.42	8000	7.14	11.7	1.73	2300	0.417	1.58	4900	0.808	1.34	8000	1.12	1.31	8000	1.1	0.279	0.04	2
24F	58	1.85	4.11	1.44	8000	7.22	16.4	1.69	3400	0.603	1.43	7200	1.08	1.31	8000	1.09	1.27	8000	1.06	0.279	0.04	2
31C	72	1.68	1.48	1.3	8000	5.99	5.9	1.67	1000	0.175	1.64	2400	0.412	1.58	4300	0.713	1.55	5200	0.844	0.426	0.12	1.8
31D	72	1.68	2.06	1.31	8000	6	8.23	1.67	1500	0.263	1.62	3500	0.594	1.52	6100	0.972	1.46	7300	1.12	0.426	0.12	1.8
31E	72	1.7	2.9	1.33	8000	6.06	11.6	1.68	2300	0.404	1.59	5000	0.832	1.43	8000	1.2	1.39	8000	1.16	0.426	0.12	1.8
32D	72	2.81	2.17	2.18	8000	10.4	8.66	-	-	-	2.72	2200	0.628	2.58	3900	1.06	2.5	4700	1.23	0.813	0.12	2.5
32E	72	2.8	2.75	2.18	8000	10.3	11	2.78	1300	0.378	2.67	2900	0.811	2.46	5000	1.29	2.33	6100	1.49	0.813	0.12	2.5
32G	72	2.9	4.24	2.26	8000	10.6	17	2.82	2300	0.68	2.6	4700	1.28	2.17	7600	1.72	-	-	-	0.813	0.12	2.5
33E	72	3.86	2.99	3	8000	14.6	12	-	-	-	3.64	2300	0.878	3.33	4000	1.39	3.14	4800	1.58	1.2	0.12	3.3
33G	72	3.81	4.24	2.97	8000	14.4	16.9	3.71	1600	0.622	3.44	3350	1.21	2.83	5800	1.72	2.42	7000	1.77	1.2	0.12	3.3
33H	72	3.85	5.8	3.01	8000	14.6	23.2	3.68	2250	0.866	3.2	4600	1.54	1.88	8000	1.57	-	-	-	1.2	0.12	3.3
AKM2G-3 Low Voltage Motors								24 V DC			48 V DC			72 V DC			96 V DC					
31ML	72	1.73	14.2	1.34	8000	6.14	56.8	-	-	-	1.65	3300	0.570	1.57	5200	0.853	1.46	7200	1.10	0.426	0.12	1.8
31PL	72	1.69	20.0	1.33	8000	6.09	80.7	1.67	2200	0.385	1.57	4900	0.804	1.41	7800	1.15	-	-	-	0.426	0.12	1.8
32ML	72	2.89	14.8	2.25	8000	10.7	59.1	-	-	-	2.81	2000	0.589	2.70	3200	0.906	2.57	4400	1.18	0.813	0.12	2.5
32PL	72	2.77	20.0	2.23	8000	10.6	82.4	2.79	1300	0.379	2.70	3000	0.849	2.51	4700	1.23	2.26	6400	1.51	0.813	0.12	2.5
33ML	72	3.82	14.8	2.97	8000	14.5	59.0	-	-	-	3.69	1500	0.579	3.54	2400	0.890	3.34	3400	1.19	1.2	0.12	3.3
33PL	72	3.85	5.8	3.01	8000	14.6	23.2	3.68	2250	0.866	3.2	4600	1.54	1.88	8000	1.57	-	-	-	1.2	0.12	3.3
41D	88	2.85	2.32	2.22	6000	7.25	9.27	2.84	900	0.267	2.76	2100	0.607	2.62	3800	1.04	2.53	4600	1.22	0.774	0.36	2.9
41E	88	2.87	2.92	2.24	6000	7.26	11.7	2.84	1200	0.357	2.73	2700	0.773	2.52	4800	1.27	2.38	5900	1.47	0.774	0.36	2.9
41G	88	2.86	4.53	2.24	6000	7.26	18.1	2.79	2100	0.613	2.57	4500	1.21	2.28	6000	1.43	2.19	6000	1.37	0.774	0.36	2.9
42D	88	5.04	2.27	3.93	6000	14.35	9.07	-	-	-	4.94	1200	0.62	4.79	2100	1.05	4.69	2600	1.28	1.36	0.36	3.86
42E	88	5.08	2.88	3.97	6000	14.4	11.5	-	-	-	4.93	1600	0.83	4.71	2700	1.33	4.56	3300	1.58	1.36	0.36	3.86
42H	88	5.12	5.64	4.02	6000	14.44	22.6	5	1500	0.79	4.65	3200	1.56	3.87	5600	2.27	3.56	6000	2.23	1.36	0.36	3.86
43D	88	6.97	2.33	5.44	6000	21.1	9.31	-	-	-	-	-	-	6.67	1600	1.12	6.58	1900	1.31	1.95	0.36	4.81
43G	88	6.97	4.52	5.46	6000	21.1	18.1	-	-	-	6.61	1900	1.32	6.1	3200	2.05	5.76	3900	2.35	1.95	0.36	4.81
43I	88	6.98	7.14	5.51	6000	21.1	28.6	6.81	1400	1	6.21	3000	1.95	4.83	5300	2.68	4.02	6000	2.53	1.95	0.36	4.81
44E	88	8.48	2.99	6.63	6000	26.9	11.97	-	-	-	8.31	900	0.783	7.99	1700	1.42	7.8	2100	1.72	2.53	0.36	5.76
44H	88	8.51	5.87	6.69	6000	27	23.5	8.39	900	0.79	7.92	2000	1.66	6.98	3500	2.56	6.32	4300	2.85	2.53	0.36	5.76
44J	88	8.47	7.3	6.7	6000	26.9	29.2	8.28	1200	1.04	7.58	2600	2.06	6.04	4500	2.84	4.92	5400	2.78	2.53	0.36	5.76

Continued on following page.

AKM2G

Performance Data (continued)

Parameters	Frame Size	Max Cont. Torque for ΔT wdg. = 100°C	Max Cont. Current for ΔT wdg. = 100°C	Max Cont. Torque for ΔT wdg. = 60°C	Max mechanical speed	Peak Torque	Peak Current	120 V AC			240 V AC			400 V AC			480 V AC			Inertia (incl. Resolver feedback)	Optional Brake Inertia (additional)	Weight
								Rated Torque (speed)	Rated Speed	Rated Power (speed)	Rated Torque (speed)	Rated Speed	Rated Power (speed)	Rated Torque (speed)	Rated Speed	Rated Power (speed)	Rated Torque (speed)	Rated Speed	Rated Power (speed)			
51H	114	6.82	5.78	5.33	6000	15.7	17.3	6.73	1100	0.78	6.44	2400	1.62	5.89	4200	2.59	5.53	5100	2.96	2.52	1.2	5.13
51I	114	6.83	6.35	5.35	6000	15.7	19	6.72	1200	0.85	6.38	2700	1.8	5.74	4600	2.77	5.29	5700	3.16	2.52	1.2	5.13
51K	114	6.81	10.2	5.36	6000	15.7	30.5	6.54	2100	1.44	5.77	4500	2.72	4.67	6000	2.93	-	-	-	2.52	1.2	5.13
52H	114	12	6.3	9.4	6000	29	18.9	-	-	-	11.5	1500	1.8	10.7	2700	3.02	10.3	3200	3.44	4.58	1.2	7.03
52K	114	11.9	10	9.43	6000	29	30.1	11.7	1200	1.47	10.8	2500	2.83	9	4400	4.14	7.81	5300	4.34	4.58	1.2	7.03
52L	114	11.93	12.5	9.42	6000	28.9	37.6	11.5	1500	1.8	10.2	3200	3.42	7.42	5600	4.35	-	-	-	4.58	1.2	7.03
53H	114	16.2	5.69	12.7	6000	41.8	17.1	-	-	-	15.7	1000	1.65	14.9	1800	2.81	14.4	2200	3.32	6.64	1.2	8.89
53L	114	16	12.5	12.7	6000	41.4	37.6	15.6	1100	1.8	14.1	2400	3.53	10.9	4200	4.77	8.64	5100	4.61	6.64	1.2	8.89
53M	114	16.1	14.2	12.7	6000	41.4	42.5	15.4	1300	2.09	13.5	2800	3.97	9.74	4800	4.9	-	-	-	6.64	1.2	8.89
54L	114	20.1	10.6	15.9	6000	54.8	31.7	-	-	-	18.4	1600	3.09	15.9	2800	4.66	14.3	3400	5.08	8.7	1.2	10.8
54M	114	20	14.5	15.9	6000	54.7	43.9	19.3	1100	2.22	17.2	2300	4.13	12.9	3900	5.28	9.8	4800	4.92	8.7	1.2	10.8
54N	114	20	16.3	15.9	6000	54.7	48.8	19.1	1200	2.4	16.5	2600	4.49	11	4500	5.2	-	-	-	8.7	1.2	10.8
62K	142	15.3	9.32	12	6000	37.6	28	-	-	-	14.4	1700	2.56	12.9	3000	4.05	11.9	3700	4.59	9.1	3.6	10
62L	142	15.2	11.6	12	6000	37.4	34.9	14.9	1000	1.56	13.8	2200	3.19	11.5	3900	4.7	9.84	4800	4.95	9.1	3.6	10
62M	142	15.1	14.6	11.9	6000	37.4	43.7	14.6	1300	1.99	13.1	2800	3.85	9.6	5000	5.03	-	-	-	9.1	3.6	10
63H	142	21.7	6.11	17	6000	55.1	18.3	-	-	-	21.5	750	1.69	20.6	1300	2.8	20.1	1600	3.37	13	3.6	12.3
63K	142	21.5	9.79	16.9	6000	54.7	29.4	-	-	-	20.5	1300	2.79	18.9	2200	4.35	17.8	2700	5.03	13	3.6	12.3
63M	142	21.4	15.2	16.9	6000	54.5	45.5	20.9	1000	2.19	19.2	2100	4.21	15.6	3600	5.88	12.84	4500	6.05	13	3.6	12.3
63N	142	21.4	16.8	16.9	6000	54.5	50.5	20.7	1100	2.39	18.7	2300	4.51	14.1	4100	6.07	-	-	-	13	3.6	12.3
64L	142	27	11.4	21.3	6000	70.7	34.1	-	-	-	25.7	1200	3.23	23.4	2100	5.15	21.9	2600	5.95	16.9	3.6	14.5
64M	142	26.9	15.8	21.3	6000	70.5	47.5	-	-	-	24.6	1700	4.37	20.5	3000	6.45	17.7	3700	6.84	16.9	3.6	14.5
64N	142	26.8	17.8	21.2	6000	70.3	53.3	26.2	900	2.47	23.8	2000	4.98	18.9	3400	6.72	15.2	4200	6.67	16.9	3.6	14.5
65L	142	32.6	12.4	25.8	6000	86.8	37.1	-	-	-	31.1	1100	3.58	28.5	1900	5.67	26.8	2300	6.46	20.8	3.6	16.8
65M	142	32.6	15.3	25.8	6000	86.8	45.9	-	-	-	30.3	1400	4.44	26.7	2400	6.71	24.3	2900	7.38	20.8	3.6	16.8
65N	142	32.7	19	25.9	6000	87	56.9	-	-	-	29.5	1700	5.25	23.6	3100	7.67	19.6	3800	7.79	20.8	3.6	16.8
71L	192	22.9	12.1	18	6000	49.5	30.2	-	-	-	21.2	1500	3.34	19	2600	5.17	17.5	3200	5.87	25.9	12.3	16.8
71N	192	22.8	17.3	18	6000	49.3	43.3	22	1050	2.42	19.9	2200	4.58	15.2	4000	6.38	12	4900	6.14	25.9	12.3	16.8
71P	192	23.0	21.1	18.2	6000	49.8	52.8	21.9	1300	2.97	19	2700	5.36	12.1	4900	6.18	-	-	-	25.9	12.3	16.8
72L	192	40.5	12.3	32	6000	89.3	30.8	-	-	-	38.7	900	3.64	36.1	1550	5.86	34.2	1900	6.81	46.8	12.3	22.9
72N	192	41.1	18.7	32.7	6000	90.4	46.9	-	-	-	37.4	1400	5.48	31.9	2400	8.03	28.4	2900	8.63	46.8	12.3	22.9
72P	192	40.7	21.2	32.4	6000	89.6	53	-	-	-	36.1	1600	6.05	29	2800	8.51	24.2	3400	8.6	46.8	12.3	22.9
72R	192	40.5	37	32.2	6000	89.4	92.4	-	-	-	28.6	2800	8.38	-	-	-	-	-	-	46.8	12.3	22.9
73L	192	56.6	11.6	44.7	6000	127.3	29	-	-	-	-	-	-	52.5	1050	5.77	50.6	1300	6.89	67.7	12.3	29
73N	192	57.9	17.6	45.9	6000	129.6	43.9	-	-	-	54.6	900	5.15	49.5	1600	8.29	46.6	1900	9.3	67.7	12.3	29
73Q	192	57.1	27.4	45.6	6000	128.1	68.5	-	-	-	50	1500	7.85	38.9	2600	10.6	30.8	3200	10.3	67.7	12.3	29
74P	192	72.2	23.1	57.7	6000	164.6	57.8	-	-	-	66.5	1000	6.96	58.1	1700	10.3	52.4	2100	11.5	88.6	12.3	35.2
74Q	192	71.7	28.8	57.7	6000	163.8	72.1	-	-	-	64	1250	8.37	50.7	2200	11.7	41.7	2700	11.8	88.6	12.3	35.2
74R	192	71.3	32.5	57.5	6000	162.9	81.1	-	-	-	61.5	1450	9.34	45.1	2500	11.8	34	3000	10.7	88.6	12.3	35.2
74R	192	71.3	32.4	57.5	6000	162.7	81				61.5	1450	9.34	44.9	2500	11.8	33.5	3000	10.5	88.6	12.3	35.2

AKM® Servo Motor Performance Data

AKM, AKM Washdown, and AKM Washdown Food

Performance Data

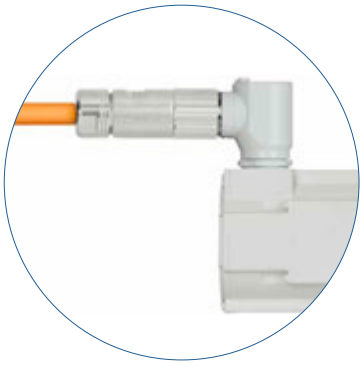
AKM Servo Motor	Flange size [mm]	Cont. Torque at Stall Tcs [Nm]	Continuous Current I_0 [A]	Peak Torque at stall Tps [Nm]	75 V DC			115 V			230 V			400 V			480 V			Inertia (Jm) [kg·cm²]	Weight [kg]
					Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm]	Rated Power Prtd [kW]	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm]	Rated Power Prtd [kW]	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm]	Rated Power Prtd [kW]	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm]	Rated Power Prtd [kW]	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm]	Rated Power Prtd [kW]		
11B	40	0.18	1.16	0.61	–	–	–	4000	0.18	0.08	8000	0.17	0.14	–	–	–	–	–	–	0.017	0.35
11C	40	0.18	1.45	0.61	–	–	–	6000	0.18	0.11	–	–	–	–	–	–	–	–	–	0.017	0.35
11E	40	0.18	2.91	0.61	6000	0.18	0.11	–	–	–	–	–	–	–	–	–	–	–	–	0.017	0.35
12C	40	0.31	1.51	1.08	–	–	–	4000	0.30	0.13	8000	0.28	0.23	–	–	–	–	–	–	0.031	0.49
12E	40	0.31	2.72	1.08	3000	0.31	0.10	8000	0.28	0.23	–	–	–	–	–	–	–	–	–	0.031	0.49
13C	40	0.41	1.48	1.46	–	–	–	3000	0.41	0.13	8000	0.36	0.30	–	–	–	–	–	–	0.045	0.63
13D	40	0.40	2.40	1.44	2000	0.40	0.08	7000	0.36	0.27	–	–	–	–	–	–	–	–	–	0.045	0.63
21C	60	0.48	1.58	1.47	–	–	–	2500	0.46	0.12	8000	0.39	0.32	–	–	–	–	–	–	0.11	0.82
21E	60	0.50	3.11	1.49	2000	0.48	0.10	7000	0.41	0.30	–	–	–	–	–	–	–	–	–	0.11	0.82
21G	60	0.50	4.87	1.51	4000	0.46	0.19	–	–	–	–	–	–	–	–	–	–	–	–	0.11	0.82
22C	60	0.84	1.39	2.73	–	–	–	1000	0.83	0.09	3500	0.78	0.29	8000	0.68	0.57	8000	0.68	0.57	0.16	1.10
22E	60	0.87	2.73	2.76	1000	0.85	0.09	3500	0.81	0.30	8000	0.70	0.59	–	–	–	–	–	–	0.16	1.10
22G	60	0.88	4.82	2.79	2500	0.83	0.22	7000	0.74	0.54	–	–	–	–	–	–	–	–	–	0.16	1.10
23C	60	1.13	1.41	3.77	–	–	–	1000	1.11	0.12	2500	1.08	0.28	5500	0.99	0.57	7000	0.95	0.70	0.22	1.38
23D	60	1.16	2.19	3.84	–	–	–	1500	1.12	0.18	5000	1.03	0.54	8000	0.92	0.77	8000	0.92	0.77	0.22	1.38
23F	60	1.18	4.31	3.88	1500	1.15	0.18	4500	1.07	0.50	8000	0.94	0.79	–	–	–	–	–	–	0.22	1.38
24C	60	1.38	1.42	4.67	–	–	–	–	–	–	2000	1.32	0.28	4500	1.25	0.59	5500	1.22	0.70	0.27	1.66
24D	60	1.41	2.21	4.76	–	–	–	1500	1.36	0.21	4000	1.29	0.54	8000	1.11	0.93	8000	1.11	0.93	0.27	1.66
24F	60	1.42	3.89	4.82	1000	1.39	0.15	3000	1.33	0.42	8000	1.12	0.94	–	–	–	–	–	–	0.27	1.66
31C	80	1.15	1.37	3.88	–	–	–	–	–	–	2500	1.12	0.29	5000	1.00	0.52	6000	0.91	0.57	0.33	1.55
31E	80	1.20	2.99	4.00	750	1.19	0.09	2500	1.17	0.31	6000	0.95	0.60	–	–	–	–	–	–	0.33	1.55
31H	80	1.23	5.85	4.06	2000	1.20	0.25	6000	0.97	0.61	–	–	–	–	–	–	–	–	–	0.33	1.55
32C	80	2.00	1.44	6.92	–	–	–	–	–	–	1500	1.95	0.31	3000	1.86	0.58	3500	1.83	0.67	0.59	2.23
32D	80	2.04	2.23	7.10	–	–	–	1000	2.00	0.21	2500	1.93	0.51	5500	1.65	0.95	6000	1.58	0.99	0.59	2.23
32E	80	2.04	2.82	7.11	–	–	–	–	–	–	3500	1.87	0.69	7000	1.41	1.03	7000	1.22	1.02	0.59	2.23
32H	80	2.10	5.50	7.26	1200	2.06	0.26	3000	1.96	0.62	7000	1.45	1.06	–	–	–	–	–	–	0.59	2.23
33C	80	2.71	1.47	9.76	–	–	–	–	–	–	1000	2.64	0.28	2000	2.54	0.53	2500	2.50	0.65	0.85	2.9
33E	80	2.79	2.58	9.96	–	–	–	–	–	–	2000	2.62	0.55	4500	2.34	1.10	5000	2.27	1.19	0.85	2.9
33H	80	2.88	5.62	10.22	800	2.82	0.24	2500	2.66	0.70	5500	2.27	1.31	–	–	–	–	–	–	0.85	2.9
41C	90	1.95	1.46	6.12	–	–	–	–	–	–	1200	1.88	0.24	3000	1.77	0.56	3500	1.74	0.64	0.81	2.44
41E	90	2.02	2.85	6.28	–	–	–	1200	1.94	0.24	3000	1.82	0.57	6000	1.58	0.99	6000	1.58	0.99	0.81	2.44
41H	90	2.06	5.6	6.36	1000	1.99	0.21	3000	1.86	0.58	6000	1.62	1.02	–	–	–	–	–	–	0.81	2.44
42C	90	3.35	1.40	11.3	–	–	–	–	–	–	–	–	–	1500	3.10	0.49	2000	3.02	0.63	1.5	3.39
42E	90	3.42	2.74	11.3	–	–	–	–	–	–	1800	3.12	0.59	3500	2.81	2.35	4000	2.72	1.14	1.5	3.39
42G	90	3.53	4.80	11.5	–	–	–	–	–	–	3500	2.90	1.06	6000	2.35	1.48	6000	2.35	1.48	1.5	3.39
42J	90	3.56	8.4	11.6	–	–	–	3000	3.03	0.95	6000	2.36	1.50	–	–	–	–	–	–	1.5	3.39
43E	90	4.70	2.76	15.9	–	–	–	–	–	–	1500	4.24	0.67	2500	3.92	1.03	3000	3.76	1.18	2.1	4.35
43G	90	4.80	4.87	16.1	–	–	–	–	–	–	2500	4.00	1.05	5000	3.01	1.58	6000	2.57	1.61	2.1	4.35
43K	90	4.90	9.60	16.4	–	–	–	2500	4.08	1.07	6000	2.62	1.65	–	–	–	–	–	–	2.1	4.35
44E	90	5.76	2.90	19.9	–	–	–	–	–	–	1200	5.22	0.66	2000	4.80	1.01	2500	4.56	1.19	2.7	5.3
44G	90	5.88	5.00	20.3	–	–	–	–	–	–	2000	4.90	1.03	4000	3.76	1.57	5000	3.19	1.67	2.7	5.3
44J	90	6.00	8.80	20.4	–	–	–	–	–	–	4000	3.84	1.61	6000	2.75	1.73	6000	2.75	1.73	2.7	5.3
51E	115	4.70	2.75	11.6	–	–	–	–	–	–	1200	4.41	0.55	2500	3.98	1.04	3000	3.80	1.19	3.4	4.2
51G	115	4.75	4.84	11.7	–	–	–	–	–	–	2500	4.02	1.05	5000	2.62	1.37	6000	1.94	1.22	3.4	4.2
51H	115	4.79	6.00	11.7	–	–	–	–	–	–	3000	3.87	1.22	6000	1.95	1.23	6000	1.95	1.23	3.4	4.2
51K	115	4.90	9.40	11.9	–	–	–	2500	4.15	1.09	5500	2.35	1.35	–	–	–	–	–	–	3.4	4.2

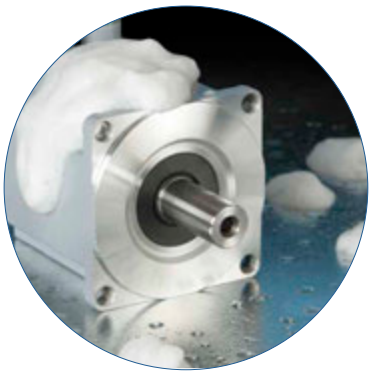
Continued on following page.

AKM, AKM Washdown, and AKM Washdown Food

Performance Data (continued)

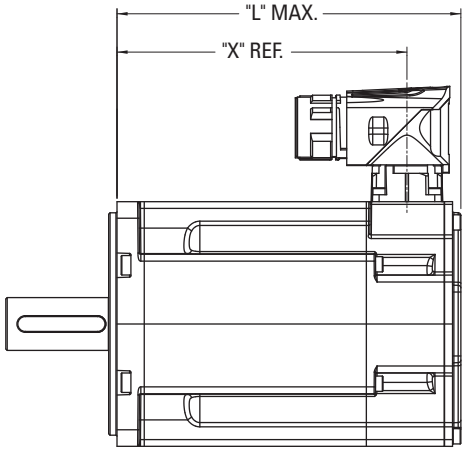
AKM Servo Motor	Frame size [mm]	Cont. Torque at Stall Tcs [Nm]	Continuous Current I_0 [A]	Peak Torque at stall Tps [Nm]	230 V			400 V			480 V			Inertia (Jm) [kg·cm²]	Weight [kg]
					Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm]	Rated Power Prtd [kW]	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm]	Rated Power Prtd [kW]	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm]	Rated Power Prtd [kW]		
52E	115	8.34	2.99	21.3	–	–	–	1500	7.61	1.20	2000	7.28	1.52	6.2	5.8
52G	115	8.43	4.72	21.5	1200	7.69	1.21	2500	7.06	1.85	3000	6.66	2.09	6.2	5.8
52H	115	8.48	5.90	21.6	1800	7.53	1.42	3500	6.26	2.30	4000	5.77	2.42	6.2	5.8
52K	115	8.60	9.30	21.9	3000	6.80	2.14	5500	3.90	2.25	6000	3.25	2.04	6.2	5.8
52M	115	8.60	13.1	21.9	4500	5.20	2.45	–	–	–	–	–	–	6.2	5.8
53G	115	11.4	4.77	29.7	1000	10.7	1.12	2000	9.85	2.06	2400	9.50	2.39	9.1	7.4
53H	115	11.5	6.60	30.0	–	–	–	3000	8.63	2.77	3500	8.23	3.02	9.1	7.4
53K	115	11.6	9.40	30.3	2000	10.1	2.12	4000	7.65	3.20	4500	6.85	3.23	9.1	7.4
53M	115	11.4	13.4	29.7	3000	8.72	2.74	–	–	–	–	–	–	9.1	7.4
53P	115	11.4	19.1	29.8	5000	5.88	3.08	–	–	–	–	–	–	9.1	7.4
54G	115	14.3	5.00	38.0	–	–	–	1500	12.9	2.03	2000	12.3	2.57	12	9
54H	115	14.2	5.50	37.5	–	–	–	1500	12.6	2.38	2000	12.2	2.56	12	9
54K	115	14.4	9.7	38.4	1800	12.7	2.39	3500	10.0	3.68	4000	9.25	3.87	12	9
54L	115	14.1	12.5	37.5	2500	11.5	3.00	4500	8.13	3.83	–	–	–	12	9
54N	115	14.1	17.8	37.6	3500	9.85	3.61	–	–	–	–	–	–	12	9
62G	142	11.9	4.9	29.7	–	–	–	1800	10.4	1.96	2000	10.2	2.14	17	8.9
62K	142	12.2	9.6	30.2	2000	10.4	2.18	3500	9.00	3.30	4500	8.00	3.77	17	8.9
62M	142	12.2	13.4	30.2	3000	9.50	2.98	6000	5.70	3.58	6000	5.70	3.58	17	8.9
62P	142	12.3	18.8	30.3	4500	8.10	3.82	–	–	–	–	–	–	17	8.9
63G	142	16.5	4.5	42.1	–	–	–	1200	14.9	1.87	1500	14.6	2.29	24	11.1
63K	142	16.8	9.9	42.6	1500	14.9	2.34	3000	12.9	4.05	3500	12.0	4.40	24	11.1
63M	142	17.0	13.8	43.0	2000	14.3	2.99	4000	11.3	4.73	4500	10.5	4.95	24	11.1
63N	142	17.0	17.4	43.0	3000	13.0	4.08	5000	9.60	5.03	6000	7.00	4.40	24	11.1
64K	142	20.8	9.2	53.5	1200	18.8	2.36	2000	17.2	3.60	2500	16.3	4.27	32	13.3
64L	142	21.0	12.8	54.1	1500	18.4	2.89	3000	15.6	4.90	3500	14.4	5.28	32	13.3
64P	142	20.4	18.6	52.9	2500	16.0	4.19	4500	11.9	5.62	5500	9.00	5.18	32	13.3
64Q	142	20.0	20.7	53.2	3000	15.3	4.81	5000	10.7	6.45	6000	7.40	4.65	32	13.3
65K	142	24.8	9.8	64.5	1000	22.8	2.39	2000	20.2	4.23	2200	19.7	4.54	40	15.4
65M	142	25.0	13.6	65.2	1500	21.9	3.44	2500	19.2	5.03	3000	18.1	5.69	40	15.4
65N	142	24.3	17.8	63.7	2000	19.8	4.15	3500	16.0	5.86	4000	14.7	6.16	40	15.4
65P	142	24.5	19.8	64.1	2400	19.1	4.8	4000	14.9	6.24	5000	11.6	6.08	40	15.4
72K	180	29.7	9.3	79.4	–	–	–	1500	25.1	3.94	1800	24.0	4.52	65	19.7
72M	180	30.0	13.0	79.8	–	–	–	2000	23.6	4.94	2500	22.1	5.79	65	19.7
72P	180	29.4	18.7	78.5	1800	23.8	4.49	3000	20.1	6.31	3500	18.2	6.67	65	19.7
72Q	180	29.5	23.5	78.4	2000	23.2	4.89	4000	16.3	6.83	4500	14.1	6.65	65	19.7
73M	180	42.0	13.6	112	–	–	–	1500	33.8	5.31	1800	32.1	6.05	92	26.7
73P	180	41.6	19.5	111	1300	34.7	4.72	2400	28.5	7.16	2800	26.3	7.71	92	26.7
73Q	180	41.5	24.5	111	1500	33.4	5.25	3000	25.2	7.92	3500	22	8.07	92	26.7
74L	180	53.0	12.9	143	–	–	–	1200	43.5	5.47	1400	41.5	6.08	120	33.6
74P	180	52.5	18.5	142	–	–	–	1800	39.6	7.46	2000	35.9	7.52	120	33.6
74Q	180	52.2	26.1	141	1300	41.9	5.71	2500	31.5	8.25	3000	27.3	8.58	120	33.6
82T	260	75	48	210	–	–	–	2500	47.5	12.4	3000	38.0	11.9	172	49
83T	260	130	62	456	–	–	–	2200	70.0	16.1	2500	60.0	15.7	334	73
83V	260	130	91	304				3000	65	20.4	–	–	–	334	73
84T	260	180	67	668	–	–	–	1800	105	19.8	2000	93.0	19.5	495	97

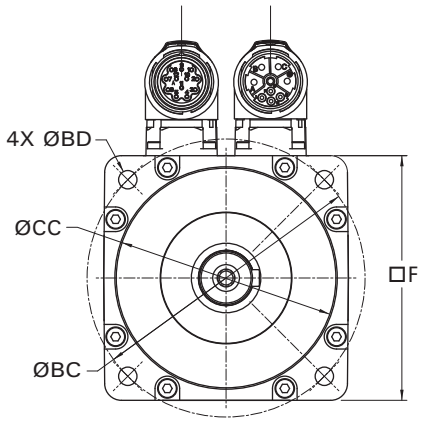




AKM® Servo Motor Dimensional Data

AKM2G-xx General Dimensions for Brake and Non-Brake Models





All measurement specifications in mm

	Model	No Brake			Brake			Flange	Bolt Circle	Bore Diameter	Centering Collar
			Resolver / SFD3	DSL / EnDat 2.2		Resolver / SFD3	DSL / EnDat 2.2				
		X	L[1]	L	X	L[1]	L	□F	ØBC	ØBD	ØCC
	AKM2G-21	90.75	111.15	118.15	129.75	150.15	157.15	58	63	5.5	40
	AKM2G-22	110	130.4	137.4	149	169.4	176.4	58	63	5.5	40
	AKM2G-23	129.25	149.65	156.65	168.25	188.65	195.65	58	63	5.5	40
	AKM2G-24	148.5	168.9	175.9	187.5	207.9	214.9	58	63	5.5	40
	AKM2G-31	101.1	121.4	129.4	142.3	162.6	170.6	72	75	5.5	60
	AKM2G-32	132.25	152.55	160.55	173.45	193.75	201.75	72	75	5.5	60
	AKM2G-33	163.4	183.7	191.7	204.6	224.9	232.9	72	75	5.5	60
	AKM2G-41	104.3	124.6	132.6	152.1	172.4	180.4	88	100	6.6	80
	AKM2G-42	130.55	150.85	158.85	178.35	198.65	206.65	88	100	6.6	80
	AKM2G-43	156.8	177.1	185.1	204.6	224.9	232.9	88	100	6.6	80
	AKM2G-44	183.05	203.35	211.35	230.85	251.15	259.15	88	100	6.6	80
	AKM2G-51	120.1	142.8	148.4	177.1	199.8	205.4	114	130	9.0	110
	AKM2G-52	149.5	172.2	177.8	206.5	229.2	234.8	114	130	9.0	110
	AKM2G-53	178.9	201.6	207.2	235.9	258.6	264.2	114	130	9.0	110
	AKM2G-54	208.3	231	236.6	265.3	288	293.6	114	130	9.0	110
	AKM2G-62	144.4	168.1	178.4	210.1	233.8	244.1	142	165	10.9	130
	AKM2G-63	166.45	190.15	200.45	232.15	255.85	266.15	142	165	10.9	130
	AKM2G-64	288.5	212.2	222.5	254.2	277.9	288.2	142	165	10.9	130
	AKM2G-65	210.55	234.25	244.55	276.25	299.95	310.25	142	165	10.9	130
Small Connector	AKM2G-71	143.9	169.1	181.1	221.35	246.55	258.55	192	215	13.4	180
Small Connector	AKM2G-72	177.85	203.05	215.05	255.35	280.55	292.55	192	215	13.4	180
Small Connector	AKM2G-73	211.8	237	249	289.3	314.5	326.5	192	215	13.4	180
Small Connector	AKM2G-74	245.75	270.95	282.95	323.25	348.45	360.45	192	215	13.4	180
Large Connector	AKM2G-71	149.6	181.1	181.1	227.1	258.55	258.55	192	215	13.4	180
Large Connector	AKM2G-72	183.55	215.05	215.05	261.05	292.55	292.55	192	215	13.4	180
Large Connector	AKM2G-73	217.5	249	249	295	326.5	326.5	192	215	13.4	180
Large Connector	AKM2G-74	251.45	282.95	282.95	328.95	360.45	360.45	192	215	13.4	180

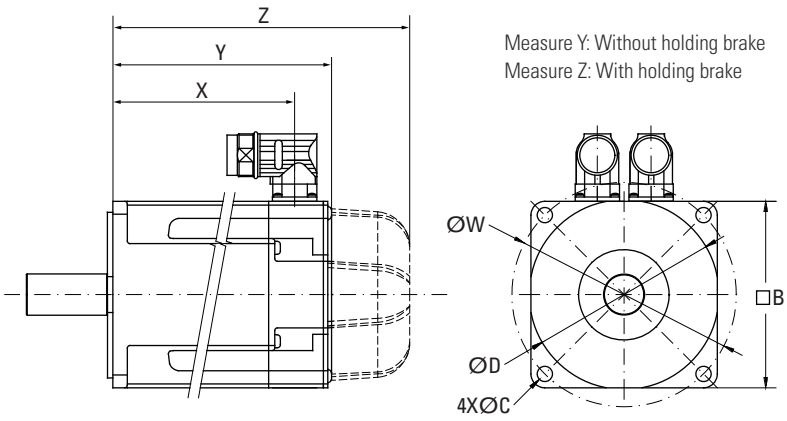
1. For AKM2G-3 low voltage models: feedback = resolver / commutating encoder

AKM2G-7x Explanation:
On Size 7 only motors with H/J connector, the feedback device does not influence the motor length, only brake or non-brake. The larger M40 connector is the same as the extra space needed for a DSL / EnDat 2.2 compared to the SFD or resolver feedback.

AKM, AKM Washdown, and AKM Washdown Food

Model with Power and Signal Connector

Dimensional drawing for AKM11 - AKM84



Measure Y: Without holding brake
Measure Z: With holding brake

All measurement specifications in mm – Measure Y: Measurement without holding brake, Measure Z: Measurement with holding brake

Model	X	Resolvers		Comcoder		Biss/Endat		Hiperface		Drive Cliq		Flange	Bolt circle	Bore diameter	Centering collar
		Y	Z	Y	Z	Y	Z	Y	Z	Y	Z	□B	ØW	ØC	ØD
AKM11	56.1	69.6	106.6	79.0	–	–	–	79	116	–	–	40	46	4.3	30
AKM12	75.1	88.6	125.6	98.0	–	–	–	98	135	–	–	40	46	4.3	30
AKM13	94.1	107.6	144.6	117.0	–	–	–	117	154	–	–	40	46	4.3	30
AKM21	76.1	95.4	129.5	95.4	129.5	95.4	129.5	113.4	147.1	–	–	58	63	4.8	40
AKM22	95.1	114.4	148.5	114.4	148.5	114.4	148.5	132.4	166.1	–	–	58	63 / 65 (1)	4.8	40
AKM23	114.1	133.4	167.5	133.4	167.5	133.4	167.5	151.4	185.1	–	–	58	63 / 65 (1)	4.8	40
AKM24	135.1	152.4	186.5	152.4	186.5	152.4	186.5	170.4	204.1	–	–	58	63 / 65 (1)	4.8	40
AKM31	87.9	109.8	141.3	109.8	141.3	109.8	141.3	125.3	159.3	–	–	70	75 / 85 (2)	5.8	60
AKM32	118.9	140.8	172.3	140.8	172.3	140.8	172.3	156.3	190.3	–	–	70	75 / 85 (2)	5.8	60
AKM33	149.9	171.8	203.3	171.8	203.3	171.8	203.3	187.3	221.3	–	–	70	75 / 85 (2)	5.8	60
AKM41	96.4	118.8	152.3	118.8	152.3	118.8	152.3	136.8	170.3	152.3	170.3	84	90 / 100 (3)	7	60 / 80 (3)
AKM42	125.5	147.8	181.3	147.8	181.3	147.8	181.3	165.8	199.3	181.3	199.3	84	90 / 100 (3)	7	60 / 80 (3)
AKM43	154.4	176.8	210.3	176.8	210.3	176.8	210.3	194.8	228.3	210.3	228.3	84	90 / 100 (3)	7	60 / 80 (3)
AKM44	183.4	205.8	239.3	205.8	239.3	205.8	239.3	223.8	257.3	239.3	257.3	84	90 / 100 (3)	7	60 / 80 (3)
AKM51	105.3	127.5	172.5	127.5	172.5	145.0	189.0	145.0	189.0	146.0	189.0	108	115 / 130 (4)	7	95 / 110 (4)
AKM52	136.3	158.5	203.5	158.5	203.5	177.0	220.0	177.0	220.0	177.0	220.0	108	115 / 130 (4)	7	95 / 110 (4)
AKM53	167.3	189.5	234.5	189.5	234.5	208.0	251.0	208.0	251.0	208.0	251.0	108	115 / 130 (4)	7	95 / 110 (4)
AKM54	198.3	220.5	265.5	220.5	265.5	239.0	282.0	239.0	282.0	239.0	282.0	108	115 / 130 (4)	7	95 / 110 (4)
AKM62	130.5	153.7	200.7	153.7	200.7	172.2	219.7	172.2	219.7	172.2	219.7	138	165	11	130
AKM63	155.5	178.7	225.7	178.7	225.7	197.2	244.7	197.2	244.7	197.2	244.7	138	165	11	130
AKM64	180.5	203.7	250.7	203.7	250.7	222.2	269.7	222.2	269.7	222.2	269.7	138	165	11	130
AKM65	205.5	228.7	275.7	228.7	275.7	247.2	294.7	247.2	294.7	247.2	294.7	138	165	11	130
AKM72	164.5	192.5	234.5	192.5	234.5	192.5	234.5	192.5	234.5	201.7	253.3	188	215	13,5	180
AKM73	198.5	226.5	268.5	226.5	268.5	235.7	287.3	235.7	287.3	235.7	287.3	188	215	13,5	180
AKM74	232.5	260.5	302.5	260.5	302.5	269.7	321.3	269.7	321.3	269.7	321.3	188	215	13,5	180
AKM82	170	267	333	267	333	267	333	267	333	–	–	260	300	18.5	250
AKM83	250.5	347.5	413.5	347.5	413.5	347.5	413.5	347.5	413.5	–	–	260	300	18.5	250
AKM84	331	428	494	428	494	428	494	428	494	–	–	260	300	18.5	250

(1) ØW = 63 mm AKM2xx-Ax
ØW = 65 mm AKM2xx-Dx

(2) ØW = 75 mm AKM3xx-Ax
ØW = 85 mm AKM3xx-Cx

(3) ØW = 100 mm, ØV = 80 mm AKM4xx-Ax
ØW = 90 mm, ØV = 60 mm AKM4xx-Cx

(4) ØW = 130 mm ØV = 110 mm AKM5xx-Ax
ØW = 115 mm ØV = 95 mm AKM5xx-Ax

AKMH™
Hygienic Stainless Steel Servo Motors

For more than 70 years, Kollmorgen has been developing special motors for use in difficult environments. For example, the remotely controlled submarine vehicle called the Jason Jr. discovered the wreck of the Titanic with the help of Kollmorgen motors developed especially for this purpose.

Long motor life and improved uptime. The specially designed AKMH housing, seals and cables can endure heavy wash downs with high pressure, high temperature, and caustic chemicals. These features ensure that AKMH motors are able to have a long life even in extremely harsh environments, which ultimately leads to minimization of downtime and improved uptime of machines.

Fast cleaning and higher productivity. The water and chemical resistant designs in housing, seals and cables of AKMH mean that no guards and covers are required to protect the motor from harsh cleaning regimens, so that clean-up and changeover time can be significantly reduced to save labor cost and increase productivity.

Reduced recall risk. Designed to meet the toughest hygienic requirements in the industry, AKMH carefully eliminates flat surfaces, cracks, and crevices to prevent the build-up of foreign material and bacteria. That significantly reduces the possibility of food borne illnesses and costly recalls enforced by Food Modernization Safety Act (FMSA).

The Advantages of AKMH Hygienic Stainless Steel Servo Motors

Increase in Overall Equipment Effectiveness (OEE)	
Faster and environmentally friendly cleaning	• Open, hygienic machine design without protective housings • Considerably lower consumption of cleaning agents; less dirty water
No machine downtimes as a result of cleaning or corrosion	• Protection class IP69K for motor housing, cable gland, and shaft seal • Designed for regular high-pressure and high-temperature cleaning • Cable and sealing components are resistant to common cleaning agents • No corrosion inside the motor: Pressure compensation through the cable prevents moisture in the motor
Lower operating costs	• Higher machine availability due to quicker cleaning • Faster cleaning reduces the consumption of cleaning agents and energy • High energy efficiency due to motor / servo drive combination with a high degree of efficiency
Higher throughput	• Quick and precise drives in combination with the AKD servo drives • Process monitoring and optimization with Kollmorgen's software tools
Lower risk of recalls	
Hygiene-optimized housing design	• Housing is 316L or DIN 1.4404 Stainless Steel with smooth surface prevents the build-up of pathogens • Fluids drained with vertical installation thanks to convex cover • No place for pathagens to hide - no nooks and crannies in housing design • Thanks to a laser annealed nameplate, the surface finish is undisturbed
Use of approved hygienic components	• Bearing lubrication and shaft seals FDA-approved • Observance of the EHEDG and 3A Sanitary Certificate hygienic regulations
Hygienic cable technology	• Silicon tubing option provides an FDA-approved cable option suitable for use with food • Low cabling costs due to single-cable technology - no need for expensive stainless steel conduit • Non absorbant cabling prevent pathogens from hiding in the cable jacket material
Reduced development times and design freedom	
Ideal motor design	• Large selection of standard motors allowing customers to optimize their motor selection • 19 frame sizes, flange and shaft measurements as per IEC and NEMA • Continuous torques up to 22 Nm, peak torques up to 92 Nm • Speeds up to 8000 rpm^{-1} • SFD3 and Hiperface DSL digital feedback systems • Brake and cable options
Simple start-up and parameterization	• Plug-and-play connection with pre-assembled connectable cables, no screw connections • Simple machine architecture due to single-cable and decentralized connection technology • Digital nameplate for quick start-up • Software tools for parameterization and drive monitoring
Low energy consumption	• High efficiency due to permanent magnet technology • 20% less derating due to special motor design
Kollmorgen support	• Kollmorgen's global support team has a wealth of industry knowledge to help optimize your machine
Co-engineering	• Kollmorgen welcomes customization to help optimize your motor/drive solution

AKMH Hygienic Stainless Steel Servo Motors

The stainless steel AKMH motors have been designed for hygienic machine applications in wet areas with food contact in accordance with the EHEDG regulations as well as 3A, USDA* and NFS hygiene standards. Shorter cleaning times and high reliability ensure noticeably greater overall equipment effectiveness.

* In preparation

Higher Productivity Due to Quicker Cleaning

- Ideal for machines with an open design
- No costly protective equipment; no hidden spaces to trap pathogens
- Quick, easy, yet safe cleaning

Reduced Recall Risk

- Lubricants and seals meet FDA standards.
- Round, stainless steel housing with a roughness of < 0.8 µm and the design of all edges with radii of R1.5 prevent dirt deposits

Higher Machine Uptime

- IP69K: Motor is protected for water pressures up to 1450 PSI
- Cable is directly mounted to motor; no connectors to fail or trap pathogens
- Single-cable technology with digital feedback (SFD3 or HIPERFACE® DSL digital resolvers); less cabling to clean

Outstanding Efficiency Thanks to Novel Motor Design

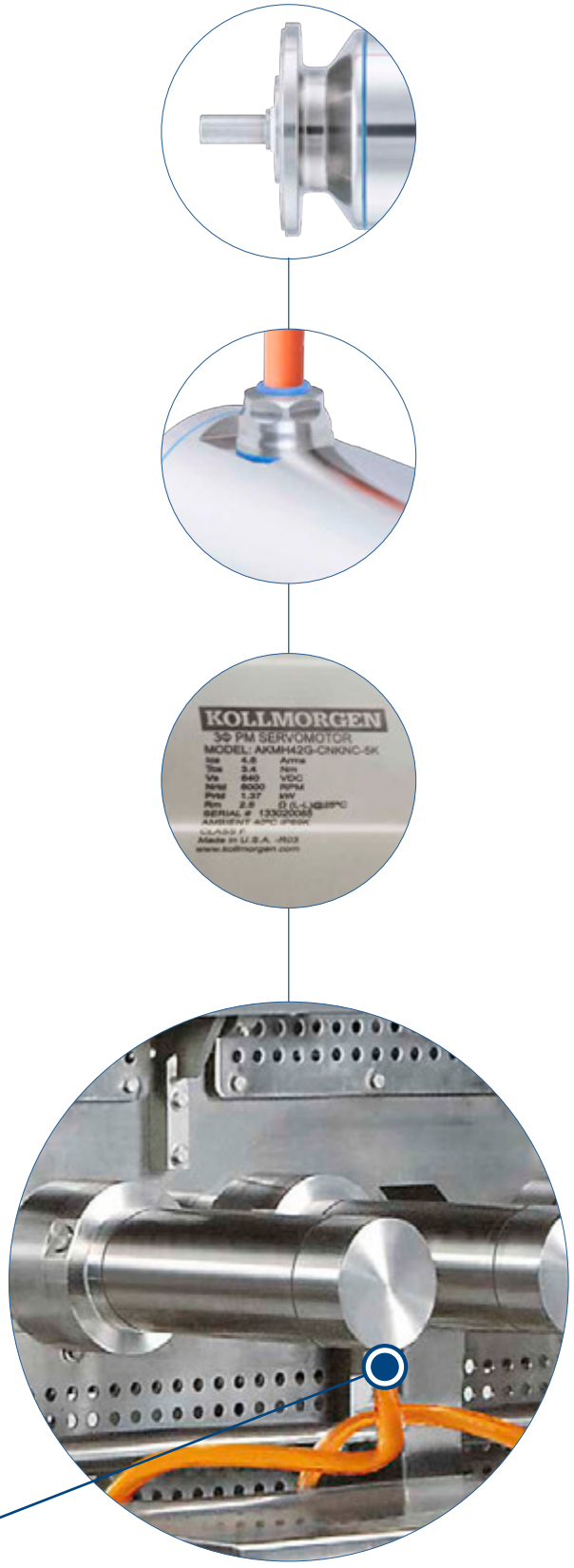
- Torque derating under 20%
- High speeds of up to 8000 RPM offer more flexibility for gearbox attachment and higher productivity due to higher output speeds with the same torque
- AKMH2 is the most compact hygienic servo motor on the market

Optimized Motion with 19 Frame Sizes

- 5 sizes each with 4 rotor lengths and winding options for perfect adaptation to servo drives
- Two housing shapes for front and flange mounting

One Source for Your Complete Automation Solution

- The Kollmorgen Automation Suite™ provides all the tools for motion and PLC programming and for drive management in operation
- AKD®-PDMM multi-axis controller: The 3-in-1 solution combines servo drive, motion controller, and PLC in one device



Thanks to the open machine design without protective housings, machines can also be cleaned quickly and safely using high-pressure and high-temperature processes.

AKMH™ Design Features

The key benefits of AKMH hygienic design features:

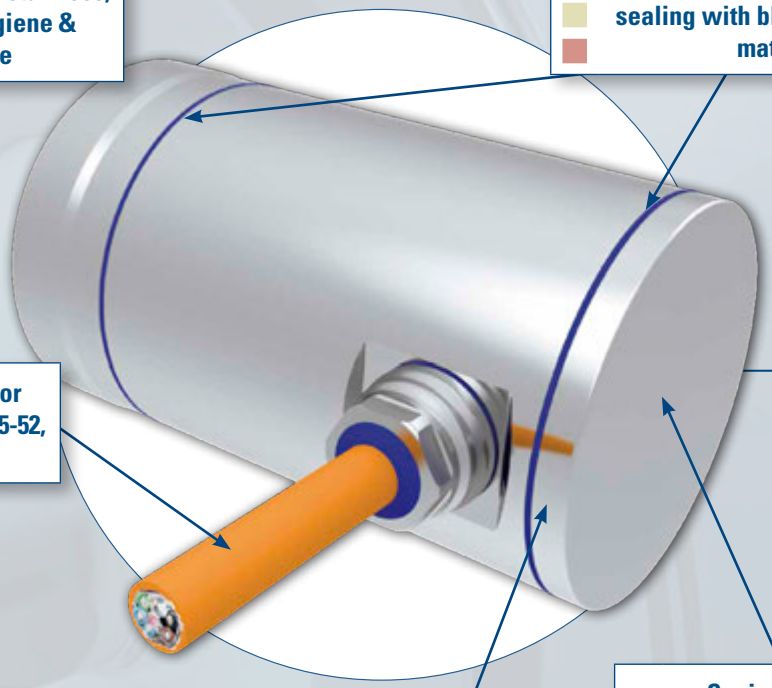
- Reduces risk of food recall
- Increases reliability in wash-down application
- Reduces cleaning time: higher OEE

No protective covers required for washdown... no secondary cleaning disassembly required

Smooth surface meeting EHEDG & 3A criteria, promotes rapid cleaning and no harboring of pathogens

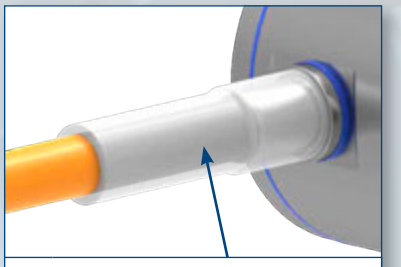
All exposed surfaces are 316 stainless, superior to 304/303 for hygiene & corrosion resistance

External O-ring and gasket sealing with blue FDA approved materials



Chemical resistant cable for pH of 2-12, meeting IEC60364-5-52, UL, CSA, CE, RoHS

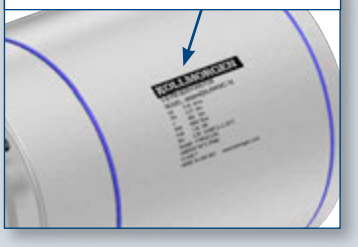
Conical end cover to eliminate water puddling, even in vertical mounting



FDA food-grade approved tubing over cable for food zone applications

No external hardware (no bolts, washers, or screws) to trap soil & pathogens or fall into food

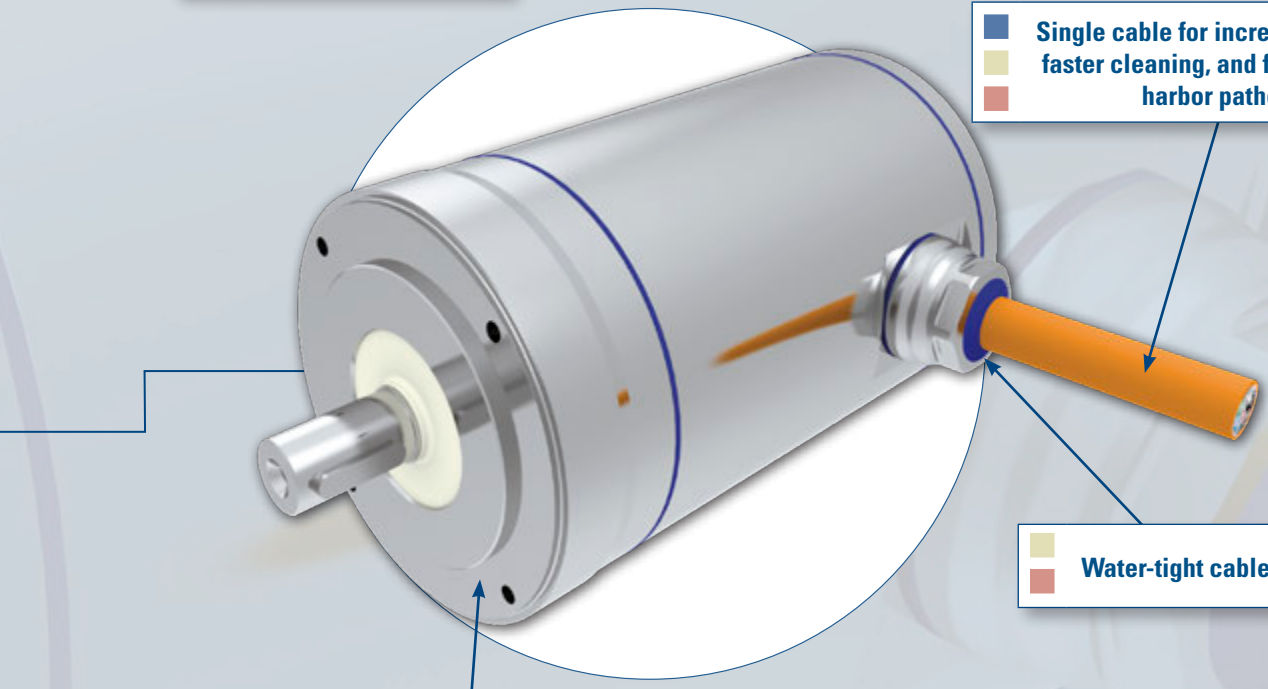
Hygienic marking method eliminates harboring of pathogens



Unique design technique to eliminate condensation

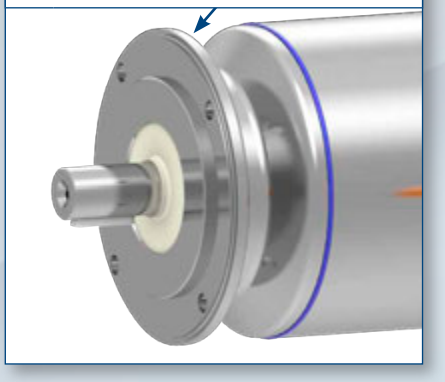
Dual cable option for use with 3rd party drives

Single cable for increased reliability, faster cleaning, and fewer places to harbor pathogens

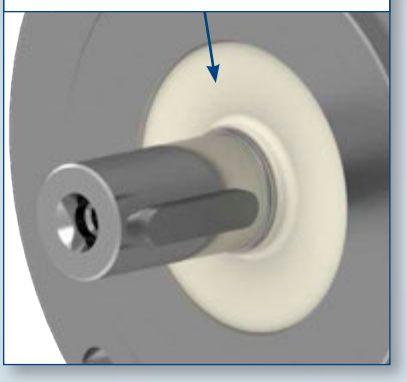


Water-tight cable exit

Face Mount for most hygienic design, Flange Mount option for easy mounting



Hygienic, IP69K shaft seal, special shaft treatment for long life



AKMH Hygienic Stainless Steel Servo Motors

Performance Data

AKMH Servo Motor	Cont. Torque at Stall Tcs [Nm] ①②③	Continuous Current I_0 [A] ①②③	Peak Torque at stall Tps [Nm] ①②③	160 V DC			320 V DC V			560 V DC			640 V DC			Inertia (Jm) [kg·cm²]	Weight [kg]
				Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm] ①②③	Rated Power Prtd [kW] ①②③	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm] ②③④	Rated power P_n [kW] ①②③	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm] ①②③	Rated Power Prtd [kW] ①②③	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm] ①②③	Rated Power Prtd [kW] ①②③		
21C	0.3	1.33	1.76	2500	0.34	0.09	8000	0.27	0.23	8000	0.25	0.21	8000	0.25	0.21	0.11	3.6
21E	0.35	2.61	1.81	7000	0.30	0.22	–	–	–	–	–	–	–	–	–	0.11	3.6
21G	0.36	4.02	1.60	–	–	–	–	–	–	–	–	–	–	–	–	0.11	3.6
22C	0.6	1.16	3.16	1000	0.62	0.06	3500	0.59	0.22	8000	0.44	0.37	8000	0.44	0.37	0.16	4.1
22E	0.63	2.27	3.23	3500	0.62	0.23	8000	0.60	0.22	–	–	–	–	–	–	0.16	4.1
22G	0.63	3.90	3.27	7000	0.51	0.37	–	–	–	–	–	–	–	–	–	0.16	4.1
23D	0.83	1.84	4.37	1500	0.86	0.14	5000	0.75	0.39	8000	0.55	0.46	8000	0.54	0.45	0.22	4.6
23E	0.88	2.34	4.43	2500	0.86	0.23	6500	0.63	0.46	–	–	–	–	–	–	0.22	4.6
23F	0.86	3.55	4.46	4500	0.78	0.37	8000	0.56	0.47	–	–	–	–	–	–	0.22	4.6
24D	1.07	1.92	5.35	1500	1.09	0.17	4000	0.97	0.41	8000	0.64	0.54	8000	0.62	0.52	0.27	5.1
24E	1.13	2.47	5.36	2000	1.09	0.23	5500	0.89	0.51	–	–	–	–	–	–	0.27	5.1
24F	1.10	3.35	5.39	3000	1.03	0.32	8000	0.65	0.54	–	–	–	–	–	–	0.27	5.1
31C	0.89	1.22	3.76	–	–	–	2500	0.86	0.23	5000	0.73	0.38	6000	0.67	0.42	0.33	4.1
31E	0.94	2.58	3.88	2500	0.91	0.24	6000	0.71	0.46	–	–	–	–	–	–	0.33	4.1
31H	0.97	4.93	3.95	6000	0.74	0.46	–	–	–	–	–	–	–	–	–	0.33	4.1
32C	1.64	1.27	6.92	–	–	–	1500	1.60	0.25	3000	1.46	0.46	3500	1.40	0.51	0.59	5.0
32E	1.65	2.44	7.06	–	–	–	3500	1.47	0.54	7000	0.91	0.67	8000	0.63	0.53	0.59	5.0
32H	1.73	4.71	7.21	3000	1.59	0.50	7000	0.92	0.67	–	–	–	–	–	–	0.59	5.0
33C	2.41	1.34	9.94	–	–	–	1000	2.37	0.25	2000	2.25	0.47	2500	2.18	0.57	0.85	5.9
33E	2.45	2.29	10.19	–	–	–	2000	2.34	0.49	4500	1.90	0.90	5000	1.77	0.93	0.85	5.9
33H	2.55	4.90	10.43	2500	2.37	0.62	5500	1.71	0.98	8000	–	–	–	–	–	0.85	5.9
41C	1.73	1.43	5.75	–	–	–	1200	1.70	0.27	3000	1.59	0.50	3500	1.54	0.56	0.81	6.1
41E	1.71	2.67	5.84	1500	1.74	0.27	3000	1.62	0.51	6000	1.28	0.79	6000	1.23	0.77	0.81	6.1
41H	1.79	5.23	5.92	3000	1.69	0.53	6000	1.30	0.82	–	–	–	–	–	–	0.81	6.1
42C	3.08	1.38	10.62	–	–	–	–	–	–	1500	2.96	0.46	2000	2.89	0.61	1.45	7.4
42E	3.05	2.58	10.79	–	–	–	1800	2.92	0.61	3500	2.56	0.94	4000	2.40	1.01	1.45	7.4
42H	3.08	5.53	11.04	2000	3.09	0.65	4500	2.38	1.12	6000	1.26	0.79	6000	1.04	0.65	1.45	7.4
42J	3.30	7.95	11.08	3000	2.99	0.94	6000	1.60	1.01	–	–	–	–	–	–	1.45	7.4
43E	4.29	2.56	15.50	–	–	–	1500	4.17	0.66	2500	3.84	1.01	3000	3.65	1.15	2.09	8.8
43H	4.45	5.11	15.65	–	–	–	3000	3.93	1.23	6000	1.47	0.92	6000	0.97	0.61	2.09	8.8
43L	3.93	9.72	15.58	3000	3.48	1.09	6000	0.64	0.40	–	–	–	–	–	–	2.09	8.8
44E	5.37	2.67	19.77	–	–	–	1200	5.31	0.56	2000	4.93	1.03	2500	4.71	1.23	2.73	10.2
44H	5.36	5.19	19.73	–	–	–	2500	4.87	1.27	5000	2.64	1.38	5000	2.21	1.16	2.73	10.2
44K	5.37	9.35	19.75	2000	5.07	1.06	5000	2.56	1.34	–	–	–	–	–	–	2.73	10.2
51E	3.84	2.55	10.09	–	–	–	1500	3.76	0.59	2500	3.52	0.92	3000	3.39	1.06	3.42	8.9
51H	3.71	5.37	10.17	–	–	–	3000	3.38	1.06	5500	2.43	1.40	5500	2.03	1.17	3.42	8.9
51L	3.81	10.36	10.33	3000	3.48	1.09	5500	2.14	1.23	–	–	–	–	–	–	3.42	8.9

① Motor winding excess temperature, ΔT = 100 K with ambient temperature = 40°C

② All specifications refer to sinusoidal supply

③ Rated data with reference flange (aluminum, dims (mm): AKMH2, AKMH3, AKMH4: 254 x 254 x 6.35 AKMH5: 305 x 305 x 12.7 AKMH6: 457 x 457 x 12.7)

Performance Data

AKMH Servo Motor	Cont. Torque at Stall Tcs [Nm] ①②③	Continuous Current I_0 [A] ①②③	Peak Torque at stall Tps [Nm] ①②③	160 V DC			320 V DC V			560 V DC			640 V DC			Inertia (Jm) [kg·cm²]	Weight [kg]
				Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm] ①②③	Rated Power Prtd [kW] ①②③	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm] ②③④	Rated power P_n [kW] ①②③	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm] ①②③	Rated Power Prtd [kW] ①②③	Rated Speed Nrtd [RPM]	Rated Torque Trtd [Nm] ①②③	Rated Power Prtd [kW] ①②③		
52E	6.55	2.63	18.79	–	–	–	–	–	–	1500	6.28	0.99	2000	6.10	1.28	6.22	11.1
52H	6.58	5.06	19.01	–	–	–	1500	6.42	1.01	3500	5.22	1.91	4000	4.70	1.92	6.22	11.1
52L	6.51	9.67	19.30	–	–	–	3500	5.26	1.93	4500	2.42	1.14	4500	1.26	0.59	6.22	11.1
52M	6.56	10.92	19.20	–	–	–	4500	4.15	1.96	–	–	–	–	–	–	6.22	11.1
53H	9.25	5.80	26.74	–	–	–	–	–	–	3000	6.82	2.14	3500	5.88	2.16	9.12	13.4
53L	8.80	9.88	26.95	–	–	–	3000	6.70	2.10	3500	3.85	1.41	3500	2.82	1.09	9.12	13.4
53P	8.12	15.34	26.56	–	–	–	3500	3.80	1.39	–	–	–	–	–	–	9.12	13.4
54H	12.94	5.19	35.62	–	–	–	1000	12.64	1.32	2000	11.48	2.40	2000	11.27	2.36	11.90	15.7
54L	11.84	11.06	35.65	–	–	–	2500	9.94	2.60	3000	7.14	2.24	–	–	–	11.90	15.7
54P	11.56	16.34	36.08	–	–	–	3000	7.59	2.38	–	–	–	–	–	–	11.90	15.7
62H	10.3	5.21	32.24	–	–	–	1000	9.93	1.04	2000	8.96	1.88	2000	8.89	1.86	16.90	19.6
62L	9.91	10.83	33.03	–	–	–	2500	8.17	2.14	5000	1.89	0.99	4500	3.07	1.45	16.90	19.6
62M	10.10	12.27	33.13	–	–	–	3000	7.67	2.41	4500	3.31	1.56	4500	2.46	1.16	16.90	19.6
63H	14.3	5.31	44.73	–	–	–	–	–	–	1500	13.04	2.05	2000	12.36	2.59	24.20	23.1
63L	13.80	10.02	45.29	–	–	–	2000	12.22	2.56	3000	9.83	3.09	3500	8.31	3.06	24.20	23.1
63M	13.90	12.33	46.02	–	–	–	2000	12.22	2.56	4000	6.67	2.79	4500	3.38	1.59	24.20	23.1
64K	17.6	8.56	55.79	–	–	–	1000	16.99	1.78	2000	15.09	3.16	2500	13.91	3.64	31.60	26.7
64L	17.50	11.63	56.46	–	–	–	1500	16.24	2.55	3000	12.29	3.86	3500	10.22	3.75	31.60	26.7
65K	20.9	9.15	65.87	–	–	–	1000	20.23	2.12	2000	18.03	3.76	2500	16.66	4.36	40.00	30.2
65L	21.00	11.21	66.72	–	–	–	1500	19.61	3.08	2500	16.63	4.35	3000	14.77	4.54	40.00	30.2
65M	20.70	12.32	66.63	–	–	–	1500	19.24	3.02	3000	14.69	4.61	3000	14.02	4.40	40.00	30.2

① Motor winding excess temperature, ΔT = 100 K with ambient temperature = 40°C

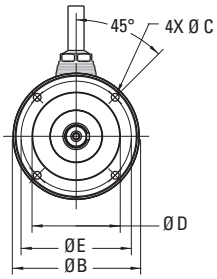
② All specifications refer to sinusoidal supply

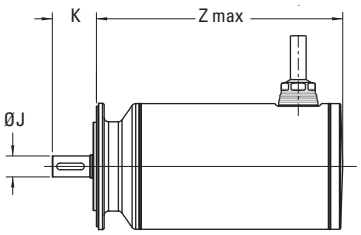
③ Rated data with reference flange (aluminum, dims (mm): AKMH2, AKMH3, AKMH4: 254 x 254 x 6.35 AKMH5: 305 x 305 x 12.7 AKMH6: 457 x 457 x 12.7)

Flange / Shaft Combinations

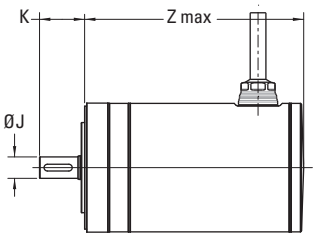
Type	AC	AN	BK	BN	CC	CN	DK	DN	EK	EN	GC	GN	HC	HN	LK
Mounting	Flange	Flange	Flange	Flange	Front	Front	Front	Front	Front	Front	Flange	Flange	Front	Front	Flange
Standard	IEC	IEC	NEMA	NEMA	IEC	IEC	NEMA	NEMA	NEMA	NEMA	IEC	IEC	IEC	IEC	NEMA
Shaft	Closed Keyway	Smooth	Open Keyway	Smooth	Closed Keyway	Smooth	Open Keyway	Smooth	Open Keyway	Smooth	Closed Keyway	Smooth	Closed Keyway	Smooth	Open Keyway
AKMH 2x	●	●	–	●	●	●	–	●	–	–	–	–	–	–	–
AKMH 3x	●	●	–	●	●	–	–	–	–	–	–	–	–	–	–
AKMH 4x	●	●	●	●	●	●	●	●	●	●	–	–	–	–	●
AKMH 5x	●	●	●	●	●	●	●	●	●	●	●	●	●	●	–
AKMH 6x	●	●	–	–	●	●	●	●	●	●	–	–	–	–	–

AKMH Hygienic Stainless Steel Servo Motors

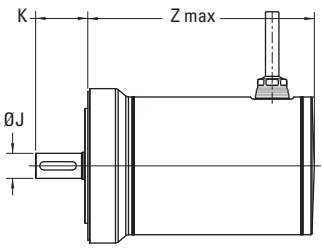




AKMH flange mounting

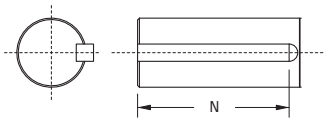


AKMH front mounting

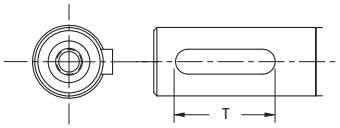


Only AKMH5x front mounting

Open keyway (BK, CN, DK versions)



Closed keyway (AC, BN, GC, HC versions)



Dimensions (mm)

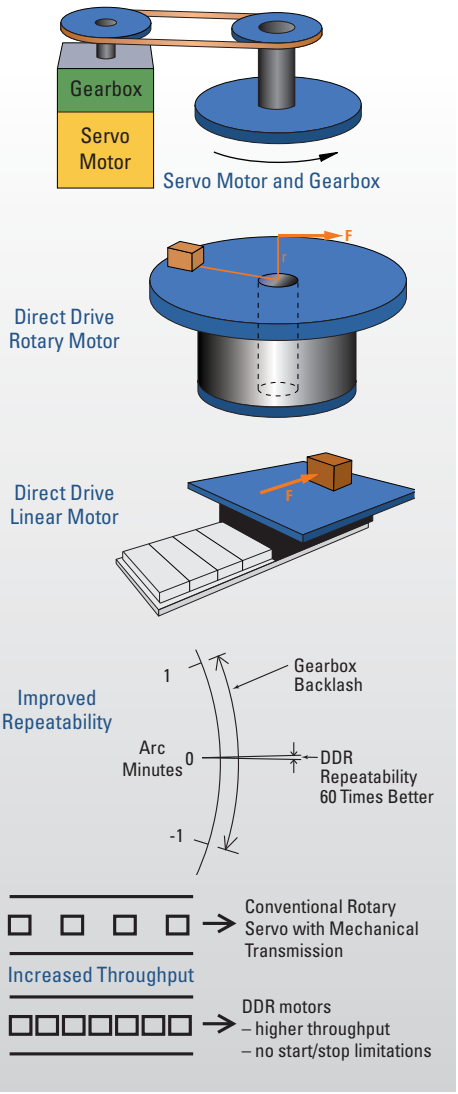
Model	Z max. SFD3 digital resolver		Z max. Hiperface DSL		Flange
	without brake	with brake	without brake	with brake	ØB
AKMH21	167.2	201.2	180.2	214.2	79
AKMH22	186.2	220.2	199.2	233.2	79
AKMH23	205.2	239.2	218.2	252.2	79
AKMH24	224.2	258.2	237.2	271.2	79
AKMH31	166.5	198.0	182.5	214.0	89
AKMH32	197.5	229.0	213.5	245.0	89
AKMH33	228.5	260.0	244.5	276.0	89
AKMH41	166.7	201.0	182.7	217.0	113
AKMH42	195.7	230.0	211.7	246.0	113
AKMH43	224.7	259.0	240.7	275.0	113
AKMH44	253.7	288.0	269.7	304.0	113
AKMH51	187.4	229.4	198.4	240.4	148
AKMH52	218.4	260.4	229.4	271.4	148
AKMH53	249.4	291.4	260.4	302.4	148
AKMH54	280.4	322.4	291.4	333.4	148
AKMH61	209.9	256.5	220.9	267.5	186
AKMH62	234.9	281.5	245.9	292.5	186
AKMH63	259.9	306.5	270.9	317.5	186
AKMH64	284.9	331.5	295.9	342.5	186

Dimensions (mm)

AKMH XX-		AC	AN	BK	BN	CC	CN	DK	DN	EK	EN	GC	GN	HC	HN	LK
Mounting		Flange		Flange		Front	Front	Front	Front	Front	Front	Flange	Flange	Front	Front	Flange
Standard		IEC		NEMA		IEC	IEC	NEMA	NEMA	NEMA	NEMA	IEC	IEC	IEC	IEC	NEMA
Shaft		Closed Keyway	Smooth	Open Keyway	Smooth	Closed Keyway	Smooth	Open Keyway	Smooth	Open Keyway	Smooth	Closed Keyway	Smooth	Closed Keyway	Smooth	Open Keyway
AKMH 2x	Ø C	4.80		–	5.10	M4 x 0.7 x 8.0		–	UNF10-32	–		–		–		–
	Ø D	40		–	38.10	40		–	38.1	–		–		–		–
	Ø E	63		–	66.68	63		–	66.68	–		–		–		–
	Ø J	11		–	9.524	11		–	9.524	–		–		–		–
	K	30		–	31.8	30.0		–	31.8	–		–		–		–
	N/T	T = 16	NA	–	NA	T = 16	NA	–	NA	–		–		–		–
AKMH 3x	Ø C	5.80		–		M5 x 0.8 x 10.0		–		–		–		–		–
	Ø D	60		–		60		–		–		–		–		–
	Ø E	75		–		75		–		–		–		–		–
	Ø J	14		–		14		–		–		–		–		–
	K	30		–		30.0		–		–		–		–		–
	N/T	T = 16	NA	–		T = 16	NA	–		–		–		–		–
AKMH 4x	Ø C	7.0		6.91		M6 x 1 x 12		UNC 1/4 - 20 x 12.3		M6 x 1 x 12		–		–		UNC 3/8 - 16 x 19.1
	Ø D	80		73.025		80		73.025	73	80		–		–		114.30
	Ø E	100		98.43		100		98.43		100		–		–		149.23
	Ø J	19		15.875		19		15.875		16		–		–		15.862
	K	40.0		52.40		40.0		52.40		52.40		–		–		50.8
	N/T	T = 25	NA	N = 34.93	NA	T = 25	NA	N = 34.93	NA	N = 30.00	NA	–		–		T = 25
AKMH 5x	Ø C	9		8.33		M8 x 1.25 x 16.0		UNC 3/8 - 16 x 19.05		M8 x 1.25 x 16.0		9		M8 x 1.25 x 16.0		–
	Ø D	110		55.560		110		55.563		110		95		95		–
	Ø E	130		125.73		130		125.73		130		115		115		–
	Ø J	24		19.05		24		19.05		24		24		24		–
	K	50.0		57.15		50.0		57.15		50.0		50.0		50.0		–
	D	T = 36	NA	N = 38.1	NA	T = 36	NA	N = 38.1	NA	N = 36.00	NA	T = 36	NA	T = 36	N = 38.1	–
AKMH 6x	Ø C	11.00		–		M10 x 1.5 x 20.0		UNC 3/8 - 16 x 19.05		M10 x 1.5 x 20.0		–		–		–
	Ø D	130		–		130		114.3		130		–		–		–
	Ø E	165.0		–		165.0		149.23		165.0		–		–		–
	Ø J	32		–		32		28.580		28		–		–		–
	K	58		–		58		69.9		60.0		–		–		–
	D	40	NA	–		T = 40	NA	N = 38.10	NA	N = 45.00	NA	–		–		–

Direct Drive Motor Overview

Conventional servo systems commonly have a mechanical transmission which can consist of gears, gearboxes, belts/pulleys or cams connected between the motor and the load. With Direct Drive Motors, the mechanical transmission is eliminated and the motor is coupled directly to the load.



Why Use Direct Drive Motors?

Increased Accuracy and Repeatability

A "precision" planetary gearbox could have a backlash of 1 arc-minute. This can result in the load moving by 1 arc-minute with an absolutely stationary drive motor. Kollmorgen's standard direct drive rotary (DDR) and direct drive linear (DDL) servo motors have repeatability better than 1 arc-second. Therefore, a direct drive motor can hold a position 60 times better than a conventional motor/gearbox.

The increased accuracy of direct drive rotary motors results in a higher quality product out of the machine:

- Print registration is more accurate
- Cut or feed lengths can be held more precisely
- Coordination with other machine axes is more accurate
- Indexing location is more exact
- Tuning issues due to backlash are eliminated

Higher Bandwidth

Mechanical transmission components impose a limit on how fast a machine can start and stop and also extend the required settling time. These factors limit the possible throughput of a machine.

Direct drive rotary motors remove these limitations and allows for much faster start/stop cycles and also provide greatly reduced settling time. Users of direct drive systems have reported up to a 2X increase in throughput.

Improved Reliability and Zero Maintenance

Gears, belts, and other mechanical transmission parts break. By eliminating these parts and using DDR and DDL motors, the reliability of the machine is improved. Gearboxes require periodic lubrication and/or replacement in aggressive start/stop applications. Belts require periodic tightening. There are no time-wear components in a direct drive motor and consequently they require zero maintenance.

Fewer Parts

With direct drive motors, all you need is the motor and the mounting bolts. This often replaces many parts including brackets, guards, belts, pulleys, tensioners, couplings, and bolts, resulting in:

- Fewer parts on the BOM. Less parts to purchase, schedule, inventory and control, and less parts to assemble.
- Assembly time of the servo drops from several hours with the mechanical transmission to several minutes with the DDR.
- Reduced cost. Although a direct drive motor may carry a small price-premium compared to a motor/gearbox with the same torque, consider that there is an overall cost reduction when eliminating the parts and labor of all the extra components required in a servo system with mechanical transmission.

No Inertia Matching

Servo systems with mechanical transmissions require inertia matching that limits the reflected load inertia at 5 to 10 times the motor inertia. If this limitation is not met, the system becomes difficult to control due to instability issues. Inertia matching limitations of mechanical transmission systems often force machine designers to use a larger motor than would otherwise be required just to satisfy the inertia matching requirement.

Such sizing conventions are not required with direct drive rotary motors. Since the motor is directly connected to the load, the inertia of the motor and the load become a common inertia. Therefore, no inertia matching is required when using DDR and DDL. DDR and DDL applications have run with inertia ratios greater than 11,000:1.

Reduced Audible Noise

Machines with DDR motors have audible noise levels as low as 20 dB less than the same machine with a mechanical transmission.

Which Direct Drive Motor is Right for Your Application?

Kollmorgen's 70 years of electromagnetic and electromechanical design experience combined with our quality and service, allowed us to refine and expand DDR motors into three product categories for easy installation, use, and short lead times: Frameless DDR, Housed DDR, and the Cartridge DDR™. This allows you to select the right DDR solution for your application.

Applications where the load rides on the motor's bearings such as indexing or rate tables

Cartridge DDR Motor

This motor is the first in the industry to combine the space-saving and performance advantages of Frameless DDR motors with the ease of installation of a full-frame motor. Consisting of a rotor, stator, and factory-aligned high-resolution feedback device, the motor uses the machine's bearings to support the rotor. An innovative compression coupling engages the rotor to the load and the frame of the motor mounts to the machine with a bolt circle and pilot diameter just like a conventional servo motor, saving space and design time and simplifying the overall system.

Any application with existing bearings

Housed DDR Motor

The Housed DDR is a housed motor assembly featuring a factory aligned high-resolution feedback device and precision bearings, allowing it to function as the core of rotary indexing and rate table applications. The system can also be used as a flexible indexer, providing programmable, rapid indexing far exceeding the throughput and accuracy of conventional mechanical or variable reluctance indexers.

Applications where size and weight must be absolutely minimized

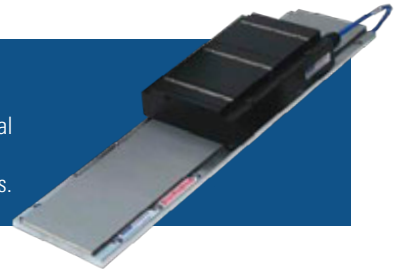
Frameless DDR Motors

Frameless motors include a rotor and stator as separate components which are integrated into, ride on the bearings of, and become a part of the driven load. Frameless motors offer the most compact and lightweight DDR solution available. The KBM™ and TBM series are Kollmorgen's Frameless DDR products. The KBM provides excellent torque/volume with the use of a proprietary neodymium-iron magnet rotor structure and skewed armature assembly. The KBM series is the first UL recognized parts set available on the market. This provides OEMs with the benefits of UL component ratings for easier agency approval on their machines. The TBM frameless motor is a series of direct drive torque motors designed for applications that require high power in a small, compact form factor with minimized weight and inertia.

Applications where linear motion is required

Direct Drive Linear (DDL) Motor

Directly coupling a linear motor to the driven load offers many advantages, including eliminating all mechanical transmissions, such as ball/lead screws, rack & pinions, belts/pulleys, and eliminating gearboxes. This in turn also eliminates backlash and compliance, and other problems associated with these mechanical transmissions.



Direct Drive Linear Motor

Our direct drive linear motor series provide new dimension in performance with high throughput, accuracy, and zero maintenance. The product line are frameless, permanent magnet, three phase, brushless servo motors. The DDL product line consists of two fundamental constructions, Ironless (slotless) and Ironcore. Ironless motors have no attractive force between the framless components and zero cogging for the ultra smooth motion. Ironcore motors provide the highest force per frame size. They feature a patented anti-cogging design which yields extremely smooth operation.

The Benefits of Direct Drive Linear Motor

• Zero Maintenance with Greater Accuracy and Higher Bandwidth	• Smoother velocity and reduced audible noise • Power transmission without backlash • Transmission elements such as couplings, toothed belts, ball/lead screws, rack & pinions, and other fitted components can be eliminated • No gears or screws, no lubrication required • Improved machine reliability
• Wide Range of Sizes and Force to Cover any Linear Application	• Increased performance for the entire system • Flat, compact drive solution • Easily mix / match motors and drives • Real-life acceleration up to 10 G
• Simplified, High Force Permanent Magnet Design	• Higher bandwidth and faster response than ball/lead screws or rack & pinion solutions • Rapid indexing of heavy loads with peak force up to 12,500 N (2,800 lb) • Reduced audible noise, fewer parts and lower cost of ownership • More compact machine design

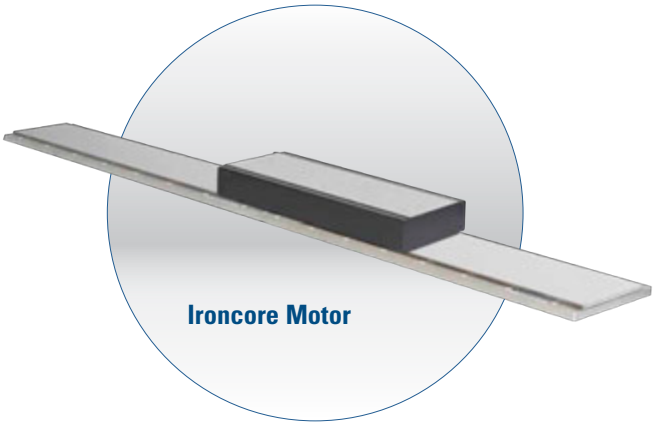
Direct Drive Linear (DDL) Motor

Direct Drive Linear Motor Options

Two types of linear motors are available, **Ironcore** and **Ironless**. Each one provides characteristics and features that are optimal depending upon the application. Ironcore motors have coils wound on silicon steel laminations, to maximize the generated force, with a single sided magnet way.

Using a patented electromagnetic design, DDL linear motors have the highest rated force per size, a high Km motor constant (equals low thermal losses), and low cogging forces without the need for skewing of the magnets. The high thrust forces possible with these motors make them ideal for accelerating and moving high masses, and maintaining stiffness during machining or process forces. Ironless motors have no iron, or slots for the coils to be wound on.

Therefore, these motors have zero cogging, a very light mass, and absolutely no attractive forces between the coil assembly and the magnet way. These characteristics are ideal for applications requiring very low bearing friction, high acceleration of lighter loads, and for maximizing constant velocity, even at ultra low speeds. The modular magnet ways consists of a double row of magnets to maximize the generated thrust force and to provide a flux return path for the magnetic circuit.



Feedback Types

All brushless motors require feedback for commutation. The conventional rotary motor typically utilizes a resolver mounted on the rear of the motor or Hall effect devices mounted integrally in the coil windings. For a linear motor, commutation feedback can also be accomplished with a variety of methods. Digital or linear Hall effect devices are available from Kollmorgen for the DDL motor series which allow the drive electronics to commutate the linear motors in a manner identical to rotary motors.

For exceptionally smooth motion requirements, sinusoidal drive electronics such as the Kollmorgen's AKD® series, using digital Hall effects, provide sinusoidal drive currents to the motor for the best constant force and velocity performance. As an alternative, it is typical for linear motor applications to have a linear encoder present in the system for position feedback. It is increasingly common today for drive amplifiers, such as the AKD digital amplifier, to derive the necessary commutation information directly from this linear encoder, either with or without supplemental digital Hall effect devices on startup. Other types of feedback used on linear motor applications include linear Inductosyns, laser interferometers, and LVDT.

Advantages

Wide Speed Range

Since the frameless parts of the linear motor are non-contact, and no limitations of a mechanical transmission are present, both very high speeds and very low speeds are easily obtainable. Speeds are truly not limited by the motor. Instead, by eliminating the mechanical transmission, speed becomes limited by other elements in the system such as the linear bearings, and the achievable bandwidth from any feedback devices. Application speeds of greater than 5 meters per second (200 in./sec.) or less than 1 micron per second (.00004 in./sec.) are typically achievable. In comparison, mechanical transmissions such as ball screws are commonly limited to linear speeds of 0.5 to 0.7 meters per second (20-30 in./sec.) because of resonances and wear. In addition to a wide speed range, linear motors, both ironcore and ironless, have excellent constant velocity characteristics, typically better than ± 0.01% speed variation.

High System Dynamics

In addition to high speed capability, direct drive linear motors are capable of very high accelerations. Limited only by the system bearings, accelerations of 3 to 5 G are quite typical for the larger motors and accelerations exceeding 10 G are easily achievable for smaller motors.

Easy Selection Process:

1. Determine peak and continuous force required for your applications (see Motioneering Online, page 219, for information about sizing)
2. Use the motor selection guide on pages 84-86 to choose your motor
3. Refer to the appropriate pages in the data publication for technical details
4. Build model number for ordering using pages 78-80 of the Direct Drive Linear Motor Selection Guide

Smooth Operation and Positional Accuracy

Both ironless and ironcore motors exhibit very smooth motion profiles due to the inherent motor design of Kollmorgen's DDL series. Cogging, which is a component of force, is greatly reduced in the ironcore designs and is zero in the ironless designs. As a result, these direct drive linear motors provide very low force and velocity ripple for ultra smooth motion. Positioning accuracies are limited only by the feedback resolution, and sub-micron resolutions are commonly achievable.

Unlimited Travel

With the DDL motor series, magnet ways are made in 5 modular sections: 64 mm, 128 mm, 256 mm, 512 mm and 1024 mm long. Each module can be added in unlimited numbers to any other module to allow for unlimited travel. Whether the travel required is 1mm (0.04 inches) or 100 meters (330 feet), the DDL series can accommodate the need.

No Wear or Maintenance

Linear motors have few components, therefore the need for ball screw components such as nuts, bearing blocks, couplings, motor mounts and the need to maintain these components have been eliminated. Very long life and clean operation, with no lubrication or maintenance of these parts are the result.

Integration of Components is Much Simpler

Frameless linear motors require much fewer components than rotary motors with mechanical transmissions. A 0.8 mm airgap (0.031 inches) for the ironcore design and 0.5 mm airgap (0.020 inches) for the ironless design is the only alignment of the frameless linear motor components that is necessary. No critical alignments are required as with ball screws. Straightness of travel as provided by the system linear bearings is more than sufficient for the Kollmorgen linear motors.

Typical Applications for Linear Motors Include:

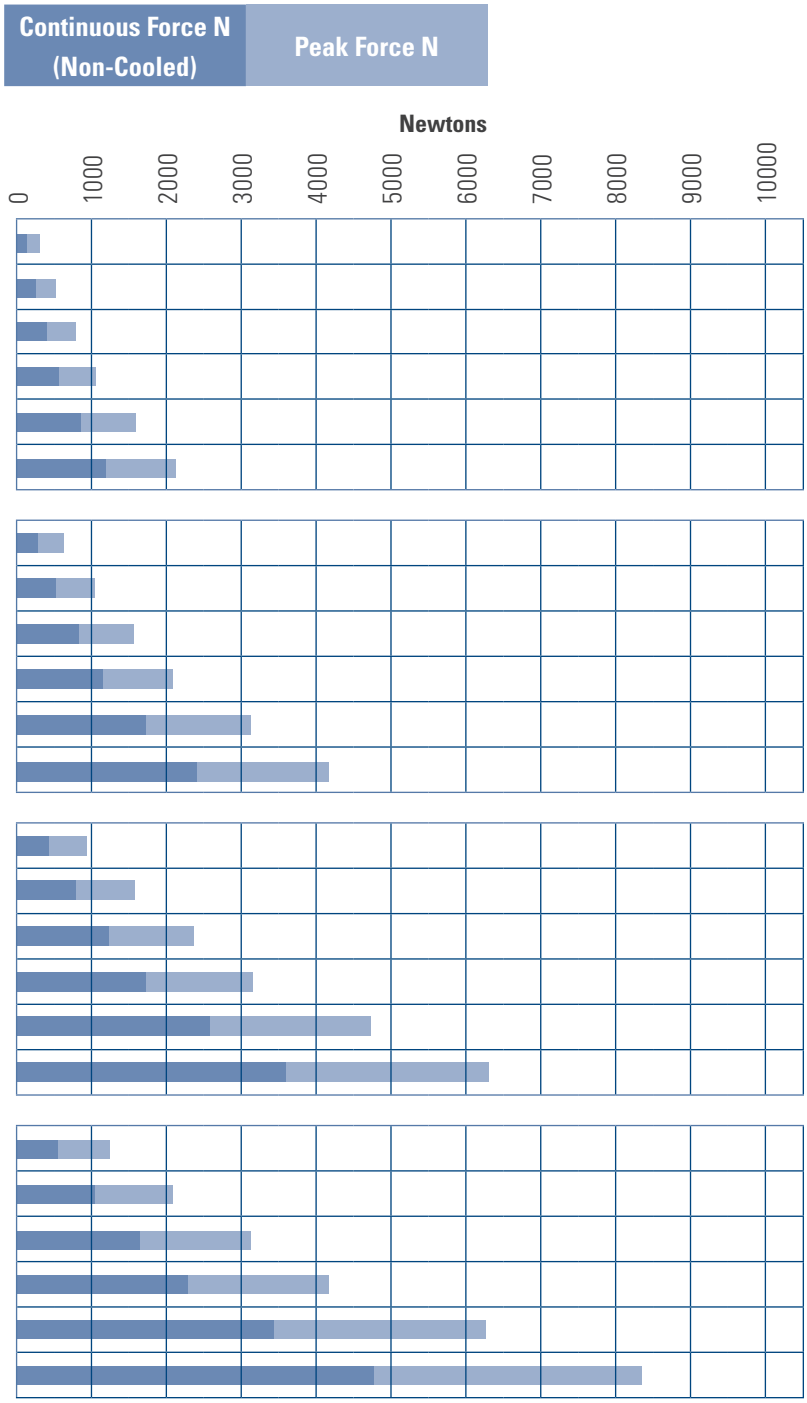
Machine Tool
Drilling
Milling
Grinding
Laser cutting
Cam grinding
Semiconductor
Wafer handling process
Wafer-inspection
Wafer slicing
Tab bonding
Wire bonding
Ion implantation
Lithography
Textile
Carpet tufting

Measurement/inspection
Coordinate measurement machines
Electronic assembly
Pick-and-place machines
Component insertion
Screen printers
Adhesive dispensers
PC board inspection, drilling

Other applications include:
Flight simulators
Acceleration sleds
Catapult
G-Force measurement

Direct Drive Linear (DDL) Motor

Ironcore Linear Motors – 230 Vac

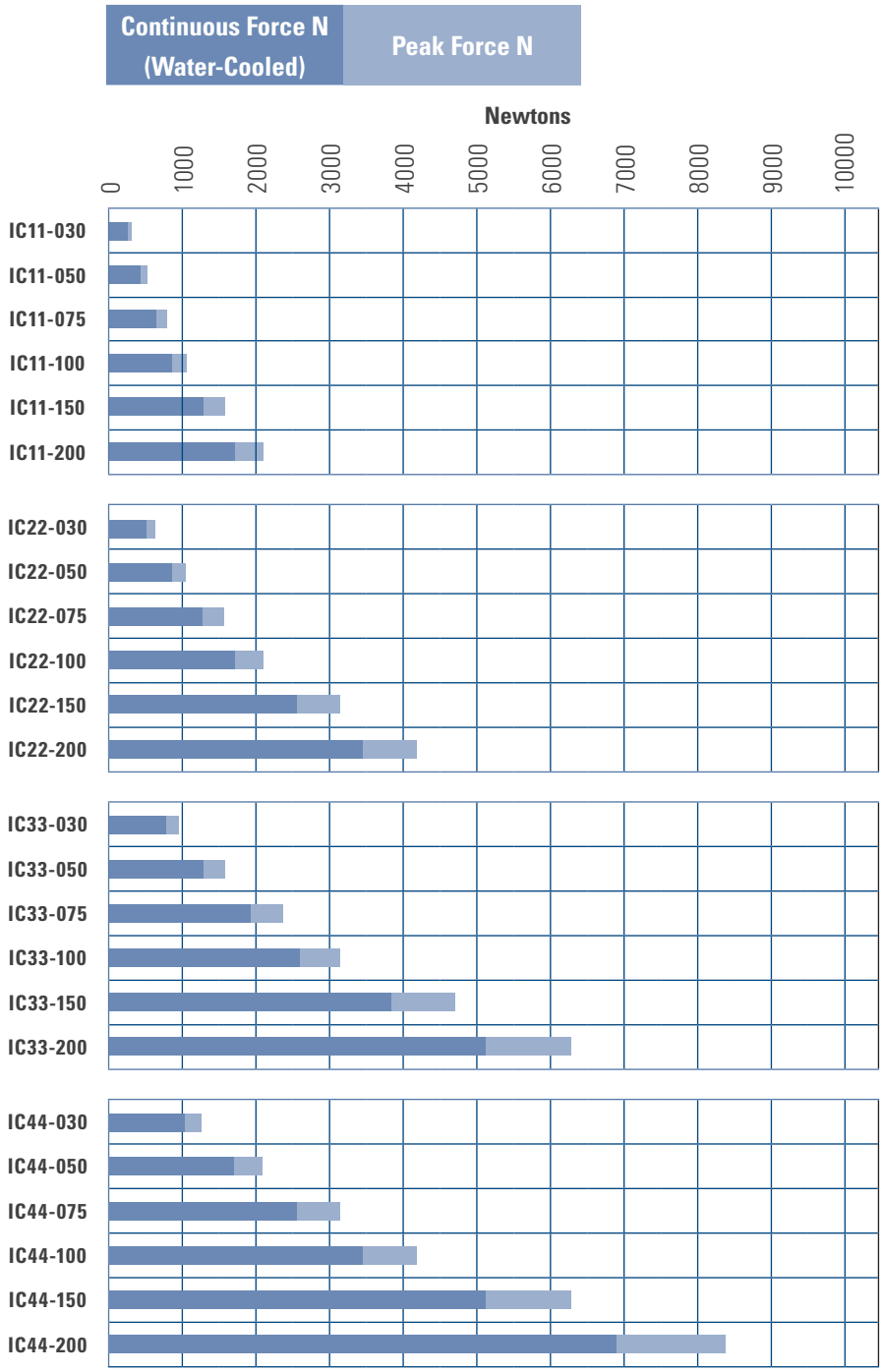


Motor Type	Max. Force (N)			
	Continuous		Peak	
	N	(lbf)	N	(lbf)
IC11-030	144	32.4	320	71.9
IC11-050	263	59.1	533	120
IC11-075	413	92.8	800	180
IC11-100	574	129	1067	240
IC11-150	861	194	1600	360
IC11-200	1197	269	2135	480
IC22-030	280	62.9	624	140
IC22-050	526	118	1039	234
IC22-075	825	185	1558	350
IC22-100	1148	258	2077	467
IC22-150	1723	387	3117	701
IC22-200	2393	538	4156	934
IC33-030	431	96.9	944	212
IC33-050	789	177	1572	353
IC33-075	1238	278	2358	530
IC33-100	1722	387	3144	707
IC33-150	2583	581	4716	1060
IC33-200	3590	807	6291	1414
IC44-030	560	126	1259	283
IC44-050	1053	237	2096	471
IC44-075	1651	371	3144	707
IC44-100	2296	516	4192	942
IC44-150	3445	774	6289	1414
IC44-200	4786	1076	8388	1885

Note: Performance data summarized here represents motor data only. For system performance data with Kollmorgen drives use the Motioneering Application Engine sizing software. See page 219 for more information about Motioneering.

Note: See the DDL Selection Guide for more detailed motor data and dimension drawings.

Ironcore Linear Motors – 230 Vac



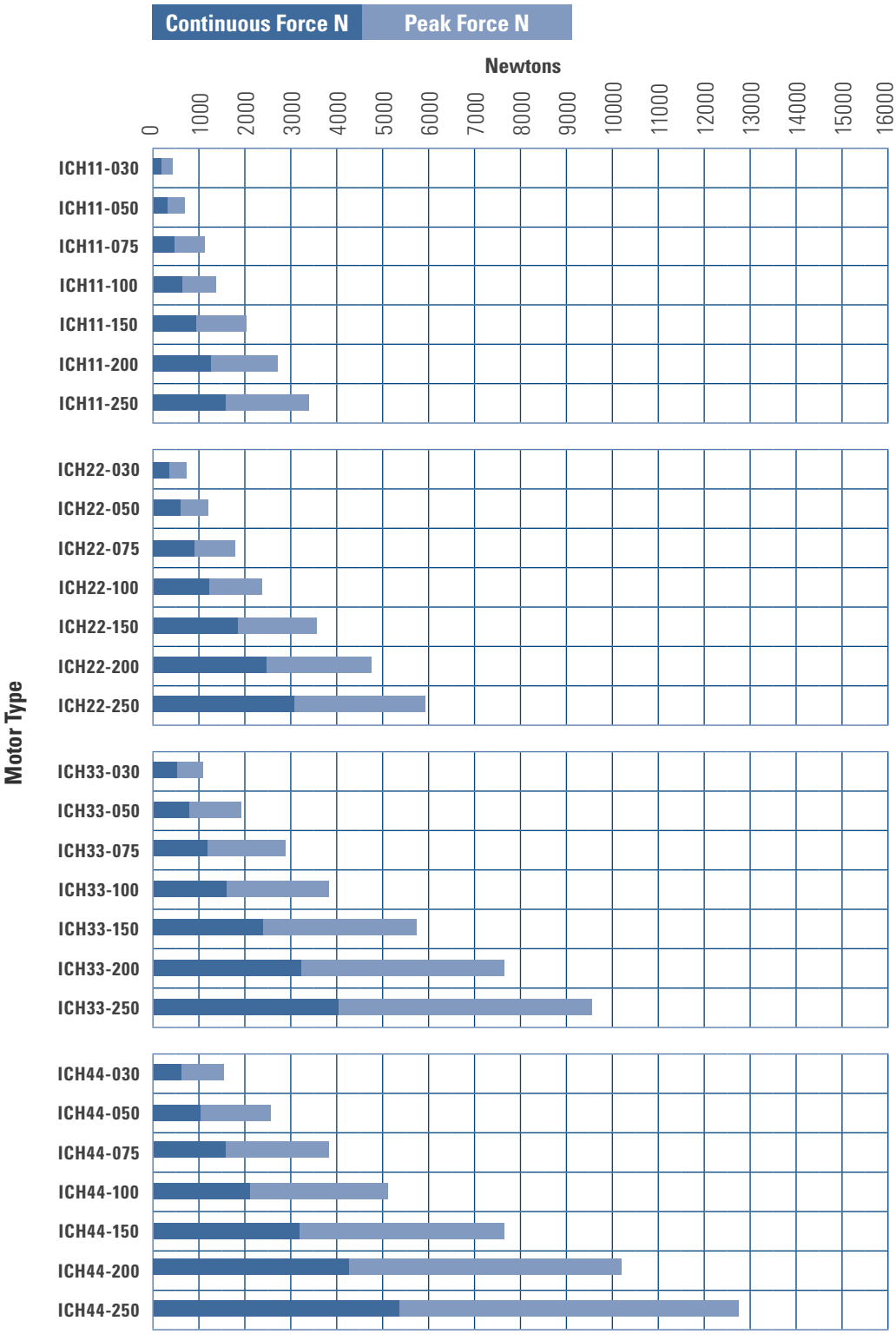
Motor Type	Max. Force (N)			
	Continuous		Peak	
	N	(lbf)	N	(lbf)
IC11-030	254	57.1	315	70.8
IC11-050	432	97.1	525	118
IC11-075	649	146	798	179
IC11-100	864	194	1051	236
IC11-150	1285	289	1576	354
IC11-200	1712	385	2102	473
IC22-030	519	117	630	142
IC22-050	864	194	1051	236
IC22-075	1284	287	1576	354
IC22-100	1715	386	2106	473
IC22-150	2566	577	3152	709
IC22-200	3458	777	4204	945
IC33-030	769	173	945	212
IC33-050	1283	288	1575	354
IC33-075	1926	433	2365	532
IC33-100	2593	583	3152	709
IC33-150	3849	865	4724	1063
IC33-200	5135	1154	6306	1418
IC44-030	1036	233	1260	283
IC44-050	1711	385	2101	472
IC44-075	2568	577	3154	709
IC44-100	3457	777	4202	945
IC44-150	5133	1154	6303	1417
IC44-200	6916	1555	8407	1890

Note: Performance data summarized here represents motor data only. For system performance data with Kollmorgen drives use the Motioneering Application Engine sizing software. See page 219 for more information about Motioneering.

Note: See the DDL Selection Guide for more detailed motor data and dimension drawings.

Direct Drive Linear (DDL) Motor

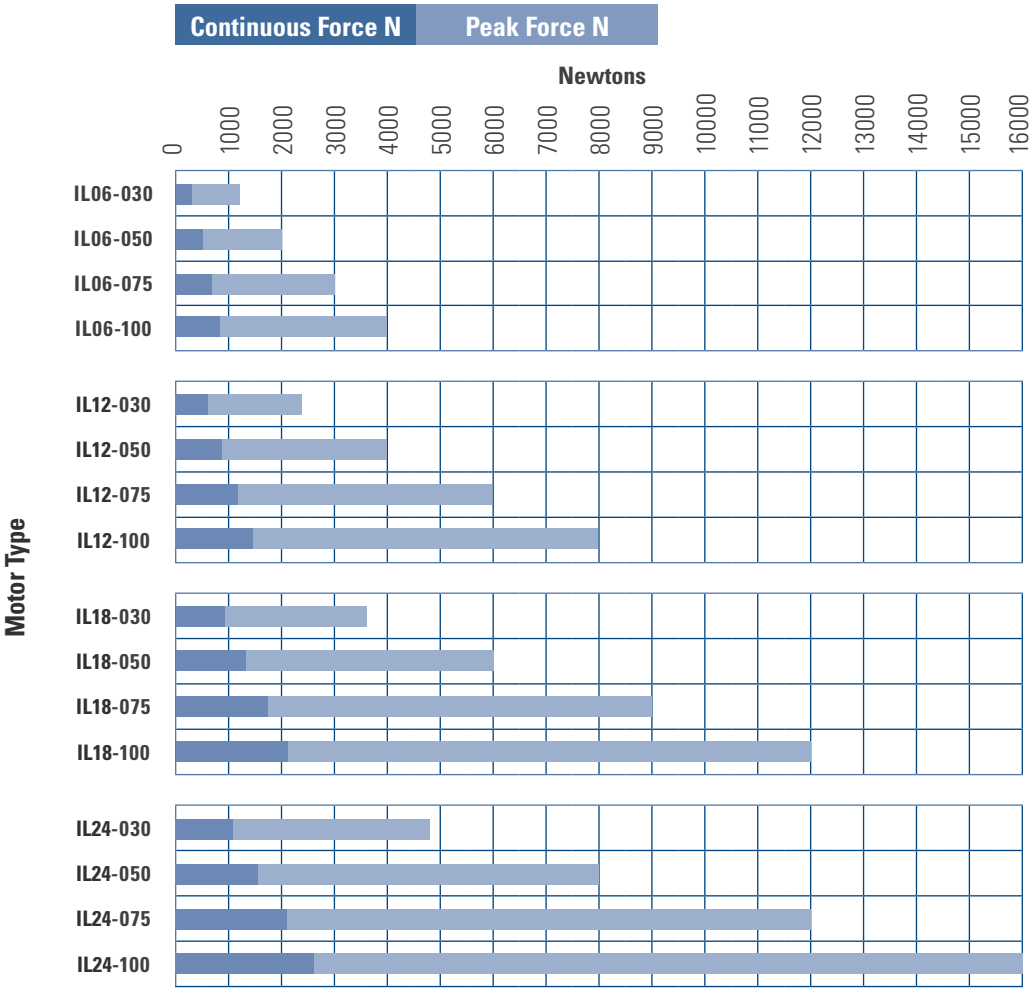
Ironcore Linear Motors – 480 Vac



	Max. Force (N)			
	Continuous		Peak	
	N	(lbf)	N	(lbf)
ICH11-030	175	39.3	405	91.0
ICH11-050	299	67.2	674	151.5
ICH11-075	455	102.3	1012	227.5
ICH11-100	612	137.6	1349	303.3
ICH11-150	927	208.4	2023	454.8
ICH11-200	1251	281.2	2698	606.5
ICH11-250	1569	352.7	3372	758.1
ICH22-030	342	76.9	710	159.6
ICH22-050	584	131.3	1184	266.2
ICH22-075	889	199.9	1775	399
ICH22-100	1203	270.4	2367	532.1
ICH22-150	1823	409.8	3551	798.3
ICH22-200	2445	549.7	4734	1064.2
ICH22-250	3067	689.5	5918	1330.4
ICH33-030	511	114.9	1065	239.4
ICH33-050	769	172.9	1909	429.2
ICH33-075	1171	263.3	2863	643.6
ICH33-100	1575	354	3818	858.3
ICH33-150	2387	536.6	5727	1287.5
ICH33-200	3201	719.6	7636	1716.6
ICH33-250	4016	902.8	9545	2145.8
ICH44-030	600	134.9	1527	343.3
ICH44-050	1023	230	2545	572.1
ICH44-075	1557	350	3818	858.3
ICH44-100	2095	471	5090	1144.3
ICH44-150	3175	713.8	7636	1716.6
ICH44-200	4258	957.2	10181	2288.8
ICH44-250	5341	1200.7	12726	2860.9

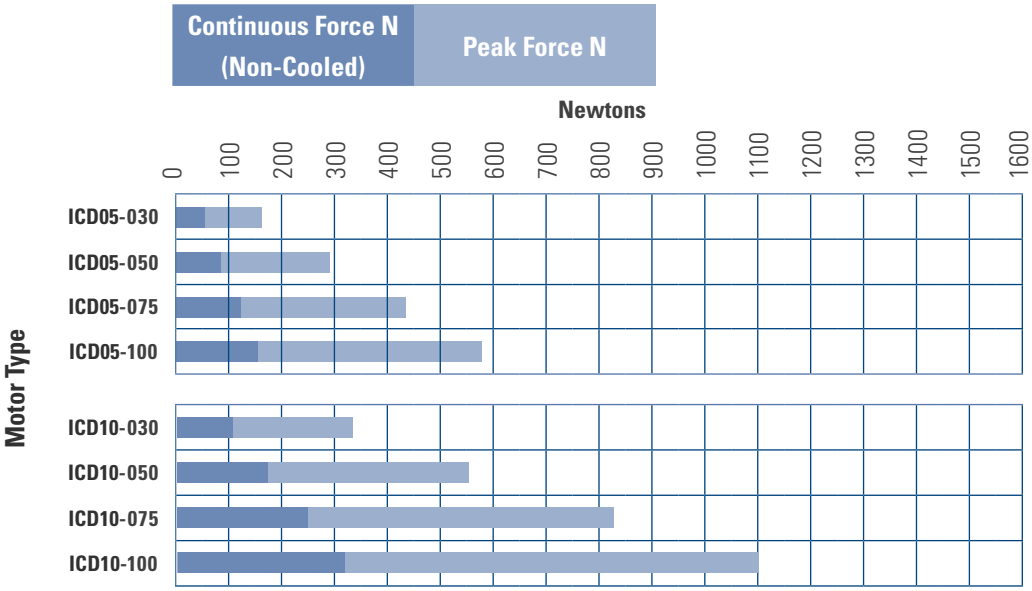
Note: Performance data summarized here represents motor data only. For system performance data with Kollmorgen drives use the Motioneering Application Engine sizing software. See page 219 for more information about Motioneering.

Ironless Linear Motors



Motor Type	Max. Force (N) Continuous N	Continuous (lbf)	Peak N	Peak (lbf)
IL06-030	30.3	6.81	120	27.0
IL06-050	49.7	11.2	200	45.0
IL06-075	67.6	15.2	300	67.4
IL06-100	82.8	18.6	400	89.9
IL12-030	62.1	14.0	240	54.0
IL12-050	88.4	19.9	400	89.9
IL12-075	119	26.8	600	135
IL12-100	148	33.3	800	180
IL18-030	92.1	20.7	360	80.9
IL18-050	131	29.4	600	135
IL18-075	173	38.9	900	202
IL18-100	211	47.4	1200	270
IL24-030	109	24.5	480	108
IL24-050	155	34.8	800	180
IL24-075	211	47.4	1200	270
IL24-100	262	58.9	1600	360

ICD Linear Motors



Motor Type	Max. Force (N) Continuous N	Continuous (lbf)	Peak N	Peak (lbf)
ICD05-030	57.0	12.8	165	37.1
ICD05-050	87.0	19.6	295	66.3
ICD05-075	125	28.1	441	99.1
ICD05-100	157	35.3	588	132
ICD10-030	104	23.4	330	74.2
ICD10-050	171	38.4	550	124
ICD10-075	246	55.3	824	185
ICD10-100	315	70.8	1099	247

Note: Performance data summarized here represents motor data only. For system performance data with Kollmorgen drives use the Motioneering Application Engine sizing software. See page 219 for more information about Motioneering.

Note: See the DDL Selection Guide for more detailed motor data and dimension drawings.

Direct Drive Rotary (DDR™) Motors

Kollmorgen offers a comprehensive selection of direct drive motors in different sizes and performance ranges. Direct drive motors are characterized by their high precision, reliability, and above all being maintenance-free. Mechanical components for power transmission such as belts or gearheads are not necessary – you just need the motor and bolts for mounting.

The Cartridge and Housed DDR motors combine the performance advantages of direct drives with the simple installation and the handling advantages of conventionally housed motors. By contrast the KBM™ and TBM series direct drive motors, with no housing, can be perfectly tailored to the application thanks to a unique construction kit principle.

All drives can be combined with AKD® or AKD® PDMM series servo drives, and the powerful Kollmorgen Automation Suite™ development environment is available for application programming.

Regardless which drive technology you decide on, Kollmorgen provides right solution and optimum support during the development phase.

The Advantages of Rotary Direct Drives

• Superb performance data	• Maximum torque density thanks to innovative, electromagnetic design minimizes the motor's spatial requirements. • Extremely quiet running with low cogging values and low harmonic distortion (THD) • Wide speed range and high acceleration values
• Reliable and safe operation through careful construction	• Doubly secured magnet mounting on the rotor of the high-speed models through bonding and additional Kevlar® tape overlay • 155°C-approved internal winding temperature and thermistor overtemperature protection guarantee safe continuous operation in demanding applications • Insulation materials with UL approval facilitate the certification of higher-level assemblies • All materials are RoHS-compliant
• Configurable design reduces the time-to-solution to a minimum	• KBM series offers 14 frame sizes with several design lengths • TBM series offers 3 frames sizes with 3 stack lengths per frame • Cartridge DDR series offers 5 frame sizes with several design lengths • Housed DDR series offers 4 frame sizes • Standard sensor feedback with hall effect sensors • Insulation types for high and low voltage • Several winding options with customer-specific windings upon request • Changes to the mechanical connection are easy to perform

Cartridge Direct Drive Rotary (DDR®) Motor

The Cartridge DDR® Motor is the first in the industry to combine the space-saving and performance advantages of frameless DDR technology with the ease of installation of a full-frame motor. Cartridge DDR motors also feature an advanced electromagnetic design that provides up to 50% more torque density than comparably sized conventional servo motors.

Consisting of a rotor, stator, factory-aligned high-resolution feedback device, the Cartridge DDR motor uses the machine's bearings to support the rotor. An innovative compression coupling secures the Cartridge DDR's rotor to the machine shaft, and the Cartridge DDR's housing is bolted to the machine frame with a bolt circle and pilot – just like a conventional servo motor. Also, mechanical transmission components are eliminated, saving space and design time while simplifying the overall system.

Advantages of the Cartridge DDR Motors

- Quick assembly within 5 minutes
- Direct power transmission without mechanical components reduces operating and maintenance costs
- Low cogging and thus smooth running at low speeds
- The backlash-free design improves the system's response characteristics

Performance Overview

- 5 frame sizes from 108 to 350 mm
- 17 different lengths and 52 standard windings
- Continuous torques of 4.57 Nm to 510 Nm
- Speeds up to 2500 rpm
- Integrated, high-resolution sinus encoder (optional)

The Cartridge DDR™ Advantage – Press Feed Machine

Consider how Cartridge DDR technology improves a Press Feed machine:

Reduced Assembly Time

The assembly time for the original mechanical transmission system was 4 hours. In contrast, the Cartridge DDR motor is installed in less than 5 minutes, resulting in a significant cost savings in labor.

Reduced Parts Count

The original mechanical transmission system comprises 2 bracket pieces, 12 bolts, 2 pulleys, 2 set screws, 2 keys, a timing belt, a housing to protect operators from the timing belt, a tension system for the timing belt, and motor/gearbox. With the Cartridge DDR system, this is all replaced by the motor and 4 mounting bolts, resulting in fewer parts to maintain and cost savings.

Improved Accuracy

The best planetary gearboxes have a backlash between 1 and 2 arc-minutes. Over the life of the gearbox, the backlash will increase. The Cartridge DDR system has an absolute accuracy of 26 arc-seconds and a repeatability of 0.7 arc-seconds. The Press Feed machine with the Cartridge DDR has a feed accuracy of +/- 0.0005 inch where the Press Feed machine with the mechanical transmission has a feed accuracy of 0.002 inch. Therefore, there was an overall four times improvement in machine accuracy with the Cartridge DDR system.

Increased Throughput

The cycle rate of the Cartridge DDR system is two times better than the mechanical transmission. This results in an increase in throughput of 100 percent.

Improved Reliability and Simplified Maintenance

The Cartridge DDR system eliminates parts that wear, change over time, or fail. Gearboxes are prone to wear, and backlash increases over time. Belts and pulleys stretch and require maintenance to maintain proper belt tension. By eliminating these components, the Cartridge DDR system delivers greater system reliability.

Press Feed Example

Gearboxes have a finite life span, especially in a demanding cyclic application such as a Press Feed. On this machine, the gearbox must be replaced every 10,000 hours and the belt must be tensioned every 2,000 hours. By contrast, the Cartridge DDR motor has no wear components and requires no maintenance thus simplifying the maintenance schedule for the machine and reducing operating costs.

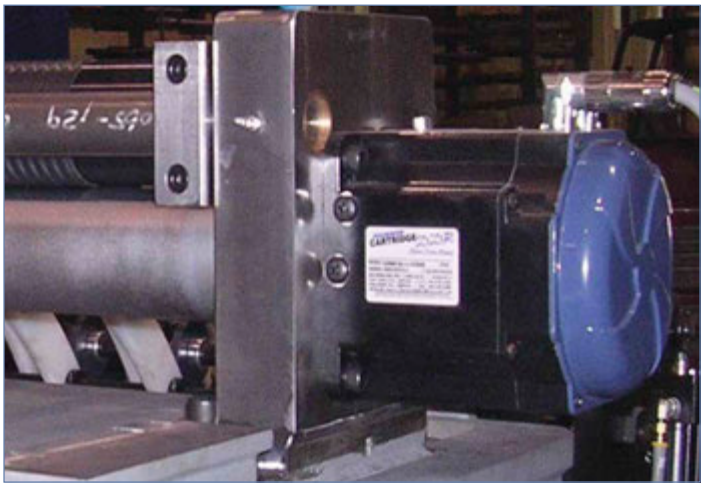
Reduced Audible Noise

The Cartridge DDR system has as much as a 20 dB reduction in noise compared to a mechanical transmission servo system. This can dramatically reduce the overall noise level of the machine. A quieter machine gives the perception of quality. This is rightfully so as the noise emitted by gears and belts is caused by the wearing of the parts.

Total Reduced Cost

A Cartridge DDR motor typically costs 20 percent more than a comparable motor/gearbox combination. However, the elimination of parts and assembly time typically results in a lower total cost for the Cartridge DDR solution.

Press feed machine built with a conventional servo motor, gearbox, belt and pulleys.



Same machine with a Cartridge DDR motor installed. Here, the shaft of the driven roll is extended into the Cartridge DDR motor and the motor applies torque directly to the driven roll.

Cartridge Direct Drive Rotary Motor (DDR)

240 Vac Performance Data

Cartridge DDR Motor	Servo Drive	Frame Size	Continuous Torque	Peak Torque	Maximum Speed	Weight	Inertia (Jm)
		mm (in)	Nm (lb-in)	Nm (lb-in)	RPM	kg (lb)	kg-cm^2 (lb-in-s^2 x10^{-3})
C041A	AKD-X00306	108 (4.25)	4.57 (40.4)	12.3 (109)	1750	4.08 (9.00)	5.86 (5.19)
C041B	AKD-X00606	108 (4.25)	4.52 (40.0)	12.2 (108)	2500	4.08 (9.00)	5.86 (5.19)
C042A	AKD-X00606	108 (4.25)	8.25 (73.0)	22.2 (196)	1700	5.67 (12.5)	8.87 (7.85)
C042B	AKD-X01206	108 (4.25)	8.45 (74.8)	22.8 (202)	2500	5.67 (12.5)	8.87 (7.85)
C043A	AKD-X00606	108 (4.25)	11.1 (98.2)	30.0 (265)	1250	7.26 (16.0)	11.9 (10.5)
C043B	AKD-X01206	108 (4.25)	11.2 (99.1)	30.2 (267)	2500	7.26 (16.0)	11.9 (10.5)
C044A	AKD-X00606	108 (4.25)	13.9 (123)	37.4 (331)	1050	8.84 (19.5)	14.9 (13.2)
C044B	AKD-X01206	108 (4.25)	14.1 (125)	37.9 (335)	2150	8.84 (19.5)	14.9 (13.2)
C051A	AKD-X00606	138 (5.43)	11.7 (104)	30.2 (267)	1200	8.39 (18.5)	27.4 (24.2)
C051B	AKD-X01206	138 (5.43)	11.9 (105)	30.6 (271)	2450	8.39 (18.5)	27.4 (24.2)
C052C	AKD-X00606	138 (5.43)	16.9 (150)	43.1 (381)	950	10.7 (23.5)	35.9 (31.8)
C052D	AKD-X01206	138 (5.43)	16.5 (146)	42.3 (374)	2050	10.7 (23.5)	35.9 (31.8)
C053A	AKD-X01206	138 (5.43)	21.0 (186)	54.1 (479)	1350	13.2 (29.0)	44.3 (39.2)
C053B	AKD-X02406	138 (5.43)	20.2 (179)	50.1 (443)	2500	13.2 (29.0)	44.3 (39.2)
C054A	AKD-X01206	138 (5.43)	24.9 (220)	63.8 (565)	1200	15.4 (34.0)	52.8 (46.7)
C054B	AKD-X02406	138 (5.43)	23.8 (211)	61.2 (542)	2500	15.4 (34.0)	52.8 (46.7)
C061A	AKD-X01206	188 (7.40)	33.8 (299)	86.8 (768)	900	18.6 (41.0)	94.1 (83.2)
C061B	AKD-X02406	188 (7.40)	32.6 (288)	75.6 (669)	1950	18.6 (41.0)	94.1 (83.2)
C062C	AKD-X01206	188 (7.40)	48.4 (428)	117 (1040)	700	23.6 (52.0)	126 (112)
C062B	AKD-X02406	188 (7.40)	44.6 (395)	102 (900)	1400	23.6 (52.0)	126 (112)
C063C	AKD-X01206	188 (7.40)	61.8 (547)	157 (1380)	550	29.0 (63.0)	157 (139)
C063B	AKD-X02406	188 (7.40)	59.0 (522)	136 (1200)	1050	29.0 (63.0)	157 (139)
C091A	AKD-X02406	246 (9.68)	50.2 (444)	120 (1060)	600	27.7 (61.0)	280 (248)
C092C	AKD-X02406	246 (9.68)	102 (900)	231 (2050)	450	41.3 (91.0)	470 (416)
C093C	AKD-X02406	246 (9.68)	139 (1230)	317 (2800)	350	54.4 (120)	660 (584)
C131C	AKD-X02406	350 (13.8)	189 (1670)	395 (3500)	250	63.5 (140)	1240 (1100)
C132C	AKD-X02406	350 (13.8)	362 (3200)	818 (7240)	120	101 (223)	2250 (1990)
C133C	AKD-X02406	350 (13.8)	499 (4410)	1070 (9890)	100	132 (292)	3020 (2670)

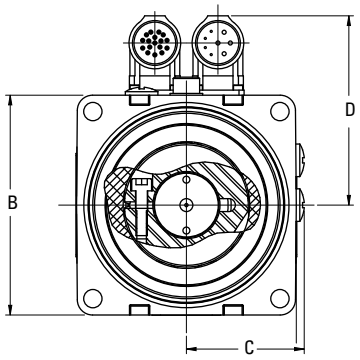
400/480 Vac Systems Performance Data

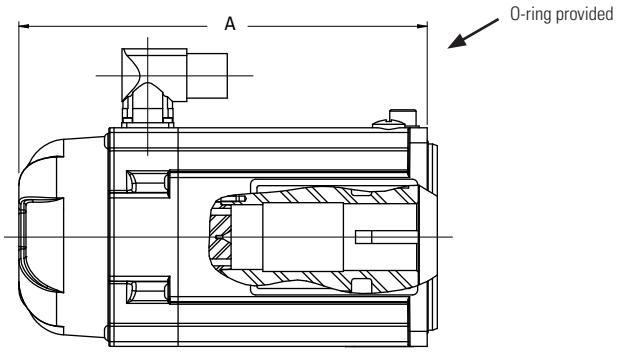
Cartridge DDR Motor	Servo Drive	Frame Size	Continuous Torque	Peak Torque	Maximum Speed		Weight	Inertia (Jm)
					RPM			
		mm (in)	Nm (lb-in)	Nm (lb-in)	400 Vac	480 Vac	kg (lb)	kg-cm^2 (lb-in-s^2 x10^{-3})
CH041A	AKD-X00307	108 (4.25)	4.56 (40.4)	11.3 (100)	2500	2500	4.08 (9.00)	5.86 (5.19)
CH042A	AKD-X00607	108 (4.25)	8.26 (73.1)	19.0 (168)	2500	2500	5.67 (12.5)	8.87 (7.85)
CH043A	AKD-X00607	108 (4.25)	11.1 (98.2)	25.3 (224)	2250	2500	7.26 (16.0)	11.9 (10.5)
CH044A	AKD-X00607	108 (4.25)	13.9 (123)	31.6 (280)	1850	2250	8.84 (19.5)	14.9 (13.2)
CH051A	AKD-X00607	138 (5.43)	11.7 (104)	28.0 (248)	2100	2500	8.39 (18.5)	27.4 (24.2)
CH052C	AKD-X00607	138 (5.43)	16.9 (150)	43.1 (381)	1750	2100	10.7 (23.5)	35.9 (31.8)
CH053A	AKD-X01207	138 (5.43)	21.0 (186)	54.1 (479)	2350	2500	13.2 (29.0)	44.3 (39.2)
CH054A	AKD-X01207	138 (5.43)	24.9 (220)	63.8 (565)	2100	2500	15.4 (34.0)	52.8 (46.7)
CH061A	AKD-X01207	188 (7.40)	33.8 (299)	86.8 (768)	1600	1900	18.6 (41.0)	94.1 (83.2)
CH062C	AKD-X01207	188 (7.40)	48.4 (428)	117 (1040)	1250	1550	23.6 (52.0)	126 (112)
CH063C	AKD-X01207	188 (7.40)	61.8 (547)	157 (1380)	950	1150	29.0 (63.0)	157 (139)
CH063B	AKD-X02407	188 (7.40)	59.0 (522)	136 (1200)	1850	2200	29.0 (63.0)	157 (139)
CH091A	AKD-X02407	246 (9.68)	50.2 (444)	120 (1060)	1200	1500	27.7 (61.0)	280 (248)
CH092C	AKD-X02407	246 (9.68)	102 (900)	231 (2050)	800	1000	41.3 (91.0)	470 (416)
CH093C	AKD-X02407	246 (9.68)	139 (1230)	317 (2800)	700	800	54.4 (120)	660 (584)
CH131C	AKD-X02407	350 (13.8)	189 (1670)	395 (3500)	500	600	63.5 (140)	1240 (1100)
CH131B	AKD-X04807	350 (13.8)	190 (1680)	396 (3500)	800	1000	63.5 (140)	1240 (1100)
CH132C	AKD-X02407	350 (13.8)	362 (3200)	818 (7240)	250	300	101 (223)	2250 (1990)
CH132B	AKD-X04807	350 (13.8)	361 (3190)	759 (6720)	400	500	101 (223)	2250 (1990)
CH133C	AKD-X02407	350 (13.8)	499 (4410)	1070 (9480)	200	250	132 (292)	3020 (2670)
CH133B	AKD-X04807	350 (13.8)	510 (4510)	1016 (9042)	350	400	132 (292)	3020 (2670)

Note 1: For complete AKD and CDDR model nomenclature, refer to pages 192 and 199 respectively.

Cartridge DDR C04, C05 and C06 Dimensions

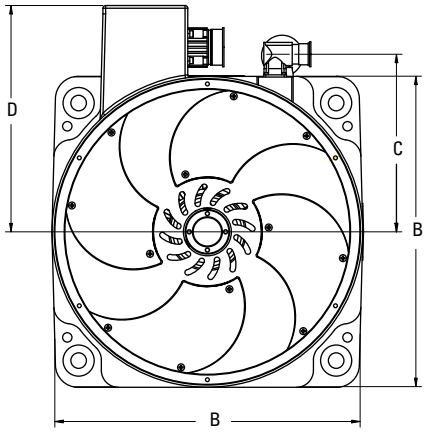
Cartridge DDR Motor	A mm (in)	B mm (in)	C mm (in)	D mm (in)
C(H)041	171 (6.73)	108 (4.25)	59 (2.31)	93 (3.67)
C(H)042	202 (7.95)	108 (4.25)	59 (2.31)	93 (3.67)
C(H)043	233 (9.17)	108 (4.25)	59 (2.31)	93 (3.67)
C(H)044	264 (10.4)	108 (4.25)	59 (2.31)	93 (3.67)
C(H)051	195 (7.68)	138 (5.43)	76 (3.00)	108 (4.25)
C(H)052	220 (8.66)	138 (5.43)	76 (3.00)	108 (4.25)
C(H)053	245 (9.65)	138 (5.43)	76 (3.00)	108 (4.25)
C(H)054	270 (10.6)	138 (5.43)	76 (3.00)	108 (4.25)
C(H)061	226 (8.90)	188 (7.40)	99 (3.88)	133 (5.25)
C(H)062	260 (10.2)	188 (7.40)	99 (3.88)	133 (5.25)
C(H)063	294 (11.6)	188 (7.40)	99 (3.88)	133 (5.25)

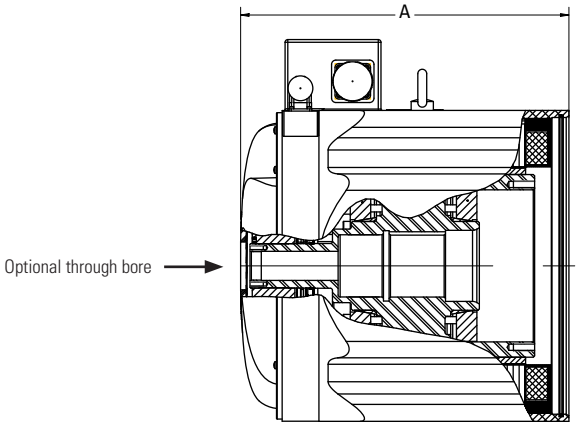




Cartridge DDR C09 and C13 Dimensions

Cartridge DDR Motor	A mm (in)	B mm (in)	C mm (in)	D mm (in)
C(H)091	204 (8.03)	246 (9.68)	149 (5.88)	182 (7.18)
C(H)092	253 (9.96)	246 (9.68)	149 (5.88)	182 (7.18)
C(H)093	302 (11.9)	246 (9.68)	149 (5.88)	182 (7.18)
C(H)131	231 (9.09)	350 (13.8)	200 (7.87)	256 (10.1)
C(H)132	301 (11.9)	350 (13.8)	200 (7.87)	256 (10.1)
C(H)133	370 (14.6)	350 (13.8)	200 (7.87)	256 (10.1)





Housed Direct Drive Rotary (DDR) Motor

Housed DDR motors are multi-pole (16 to 32) hollow shaft motors with their own bearings and high-resolution encoder system. They are coupled directly to the load and enable very precise and repeatable systems. Housed DDR motors are maintenance free and run more quietly and with better dynamics than systems that use gears, belts, cams or other mechanical transmission components.

Housed DDR Features

- 4 frame sizes
- Robust cross-roller bearing
- Dual bearing option
- IP67 option
- Continuous torque range: 5.8 Nm (4.3 lb-ft) to 339 Nm (250 lb-ft)
- Optimized torque output with high-pole count efficient electromagnetic design
- Integrated high-resolution sine-encoder
- 134,217,728 counts per rev resolution, 27 bits
- Feedback accuracy: +/- 26 arc-sec
- Repeatability better than 1 arc second

Housed DDR Motor Advantage

Consider how a Housed DDR motor improved a medical manufacturing machine.

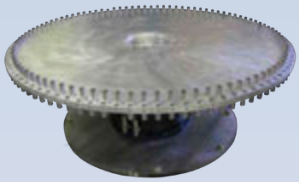
Product is located at the steel pins on the outside of the machine's turret as shown. The 115 kg load wheel has an inertia of 20 kg-m^2. There are 96 steel pins for an index angle of 3.5 degrees to move. **The move is accomplished in less than 100 ms.**

Housed DDR Benefits

- Transmission elements such as couplings, toothed belts, spindles, and other fitted components can be eliminated
- Mechanical design is made much simpler
- Power transmission without backlash
- More compact machinery assemblies
- Increased performance for the entire system

Realized Housed DDR Motor Benefits

The Direct Drive Advantage



The following improvements were observed compared to the previous design that used a mechanical indexer:

Improved Repeatability

The Housed DDR motor demonstrated a repeatability better than 1 arc-second which was substantially better than the mechanical indexer.

No Degradation

Direct drive system performance, accuracy and repeatability do not degrade over time as they do with a mechanical indexer. With a mechanical indexer, as parts wear over time, the accuracy and repeatability degrade.

Immediate Stop

The direct drive system can immediately stop if there is a process error. The mechanical indexer required several cycles to stop which could cause tooling and machine damage.

Greatly Reduced Audible Noise

With the mechanical indexer, the noise was at a level such that two people would have to yell to hear each other. By contrast, if you turned your back to the Housed DDR motor, you could barely detect that it was running.

Easy Profile Change

Motion parameters such as index angle, speed, acceleration, and dwell are very simple to change with the Housed DDR motor. The mechanical indexer does not support flexible motion profiles.

Better Value

The Housed DDR motor is attractively priced compared to the mechanical indexer it replaced. When the other advantages listed above are also considered, the Housed DDR motor was the obvious choice.

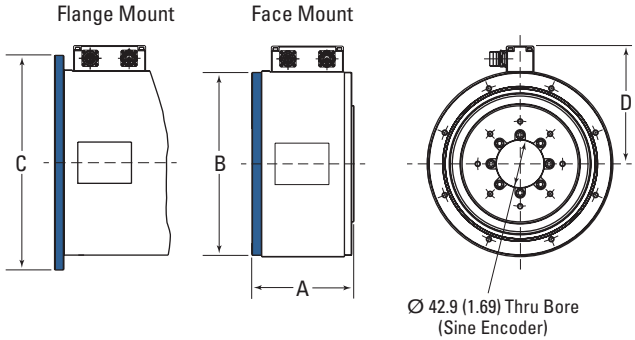
Housed DDR Performance Data and Dimensions

240 Vac Performance Data

Housed DDR Motor	AKD Servo Drive	Frame Size mm [in]	Continuous Torque Nm [lb-in]	Peak Torque Nm [lb-in]	Maximum Speed [RPM]	Weight kg [lb]	Inertia (Jm) cm^2 [lb-in-s^2 x10-^{3}]
D061	AKD-X00606	175 [6.90]	5.3 [46.9]	16.9 [150]	500	9.4 [20.7]	61 [54.0]
D062	AKD-X00606	175 [6.90]	9.8 [86.7]	33.5 [296]	500	11.3 [24.9]	71 [62.8]
D063	AKD-X00606	175 [6.90]	17.7 [157]	64.4 [570]	500	13.8 [30.4]	86 [76.1]
D081	AKD-X00606	217 [8.55]	15.9 [141]	45.0 [398]	500	17.9 [39.4]	144 [127]
D082	AKD-X00606	217 [8.55]	25.9 [229]	92.2 [816]	300	21.5 [47.3]	194 [172]
D083	AKD-X00606	217 [8.55]	50.4 [446]	160 [1420]	250	28.8 [63.4]	301 [266]
D101	AKD-X00606	280 [11.0]	34.6 [306]	129 [1140]	300	31.5 [69.3]	693 [613]
D102	AKD-X00606	280 [11.0]	63.4 [561]	227 [2010]	200	43.8 [96.4]	992 [878]
D103	AKD-X01206	280 [11.0]	115 [1020]	501 [4430]	120	60.8 [134]	1750 [1550]
D141	AKD-X01206	362 [14.2]	108 [956]	367 [3250]	200	59.4 [131]	1630 [1440]
D142	AKD-X01206	362 [14.2]	183 [1620]	519 [4590]	120	86.6 [191]	2740 [2430]
D143	AKD-X02406	362 [14.2]	339 [3000]	1340 [11,900]	60	146 [321]	5420 [4800]

400/480 Vac Performance Data

Housed DDR Motor	AKD Servo Drive	Frame Size mm [in]	Continuous Torque Nm [lb-in]	Peak Torque Nm [lb-in]	Maximum Speed RPM	Weight kg [lb]	Inertia (Jm) cm^2 [lb-in-s^2 x10-^{3}]
DH061	AKD-X00607	175 [6.90]	5.3 [46.9]	16.9 [150]	800	9.4 [20.7]	61 [54.0]
DH062	AKD-X00607	175 [6.90]	9.8 [86.7]	33.5 [296]	800	11.3 [24.9]	71 [62.8]
DH063	AKD-X00607	175 [6.90]	17.7 [157]	64.4 [570]	800	13.8 [30.4]	86 [76.1]
DH081	AKD-X00607	217 [8.55]	15.9 [141]	45.0 [398]	500	17.9 [39.4]	144 [127]
DH082	AKD-X00607	217 [8.55]	25.9 [229]	92.2 [816]	500	21.5 [47.3]	194 [172]
DH083	AKD-X00607	217 [8.55]	50.4 [446]	160 [1420]	500	28.8 [63.4]	301 [266]
DH101	AKD-X00607	280 [11.0]	34.6 [306]	129 [1140]	300	31.5 [69.3]	693 [613]
DH102	AKD-X00607	280 [11.0]	63.4 [561]	227 [2010]	300	43.8 [96.4]	992 [878]
DH103	AKD-X01207	280 [11.0]	115 [1020]	501 [4430]	250	60.8 [134]	1750 [1550]
DH141	AKD-X01207	362 [14.2]	108 [956]	367 [3250]	300	59.4 [131]	1630 [1440]
DH142	AKD-X01207	362 [14.2]	183 [1620]	519 [4590]	300	86.6 [191]	2740 [2430]
DH143	AKD-X02407	362 [14.2]	339 [3000]	1340 [11,900]	120	146.0 [321]	5420 [4800]



Dimensions

DDR	A mm [in]	B mm [in]	C mm [in]	D mm [in]
D[H]061	130 [5.12]	175 [6.90]	220 [8.66]	126 [4.95]
D[H]062	140 [5.55]	175 [6.90]	220 [8.66]	126 [4.95]
D[H]063	164 [6.46]	175 [6.90]	220 [8.66]	126 [4.95]
D[H]081	145 [5.71]	217 [8.55]	260 [10.2]	147 [5.80]
D[H]082	165 [6.50]	217 [8.55]	260 [10.2]	147 [5.80]
D[H]083	206 [8.11]	217 [8.55]	260 [10.2]	147 [5.80]
D[H]101	153 [6.02]	280 [11.0]	330 [13.0]	181 [7.11]
D[H]102	185 [7.28]	280 [11.0]	330 [13.0]	181 [7.11]
D[H]103	248 [9.76]	280 [11.0]	330 [13.0]	181 [7.11]
D[H]141	153 [6.02]	362 [14.2]	406 [16.0]	218 [8.59]
D[H]142	217 [8.52]	362 [14.2]	406 [16.0]	218 [8.59]
D[H]143	344 [13.50]	362 [14.2]	406 [16.0]	218 [8.59]

Note 1: Refer to page 177 for matching cables.
Note 2: For complete AKD and Housed DDR motor model nomenclature, refer to pages 192 and 200 respectively.

KBM Series Frameless Brushless Motor

The KBM frameless motor series direct drive technology

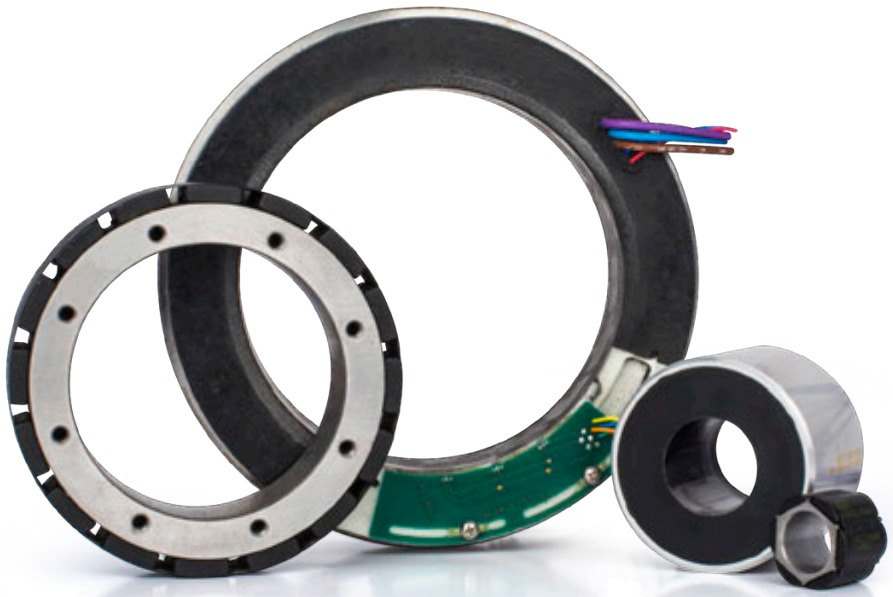
KBM frameless brushless motor models are engineered to provide the high-performance, long life and simple installation that today's design engineers demand. Optional latching digital Hall effect sensors are pre-aligned and factory installed with added axial rotor length to achieve proper triggering. Choice of insulation allows operation over a wide range of line input voltage. Our detailed selection guide provides a variety of pre-engineered options and configurations that are currently available.

Custom Application Solutions

For customized features, contact Kollmorgen to help us understand exactly what you need and how we can further optimize any KBM or engineer a new custom motor solution for the unique requirements of your application. We are experts in providing optimized solutions such as special winding configurations, tailored mounting features, diameter and stack length dimensional adjustments, or material variations.

The Benefits of KBM Frameless Motors

• Industry-Leading Frameless Motor Performance	• Advanced electromagnetic designs deliver maximum torque density which minimizes required motor space envelope • Extremely smooth rotation with minimal cogging and low total harmonic distortion (THD) • Broad operating speed range and rapid acceleration
• Quality Construction Ensures Reliability and Safe Operation	• Redundant magnet attachment to rotor on high-speed models – adhesive bonding and high-strength banding • 155°C motor winding temperature rating with integral thermistor allows continuous safe operation for demanding applications • Designed with UL-recommended insulation systems to simplify system regulatory approval • RoHS compliant material selection • Compliant with Harmonized Type C Standards EN60034-1:2004 - Rotating Electrical Machines and where appropriate in accordance to the Low Voltage Directive 2006-95-EC
• Highly Configurable Design Minimizes Time to Solution	• 14 frame sizes with multiple stack lengths • Standard sensor feedback using Hall effect sensors • Standard high and low voltage insulation • Multiple standard windings with custom windings available upon request • Mechanical interface changes easily accommodated



KBM Series Overview

Kollmorgen, the global leader in direct drive motor technology, is pleased to offer KBM series frameless brushless motors. With a wide variety of sizes and torque ranges available, KBM models are engineered to provide the high-performance, long life and simple installation that today's design engineers demand.

Quality Construction

- Fully encapsulated stator windings
- 155°C internal winding temperature continuous capability
- PTC thermistor (avalanche-type) overload protection
- High performance magnets
- Fail-safe bands over rotor magnets*
- RoHS compliant

Available Options (No engineering fees apply)

Sensor Feedback (KBMS models)

Latching digital hall effect sensors are pre-aligned and factory installed on the lead end of the stator. Wiring instructions and electrical timing diagrams are included in this selection guide. KBMS models include added axial rotor length to achieve proper sensor triggering.

Choice of Insulation System

S (standard) – acceptable for applications up to 240 Vac drive amplifier supply.
H (high voltage) – required for applications >240 Vac and up to 480 Vac drive amplifier supply.

Allowed Modifications (Engineering fees apply.
Consult Kollmorgen Customer Support for guidance or to obtain a quotation. Unit price increase may apply, depending upon extent of modification.)

Special Windings

Motor windings may be optimized to provide desired speed and torque performance according to the unique voltage and current requirements of a customer's application. Kollmorgen engineers must confirm electrical feasibility and manufacturability of each special winding arrangement prior to quotation.

Special Rotor Hub Dimensions

Rotor hubs may be provided with special customer-designated hole patterns, mounting features or smaller inner bore diameters. Standard KBM(S) models shown within this selection guide include the largest available inner rotor bore diameter.

Rotor Hub Material

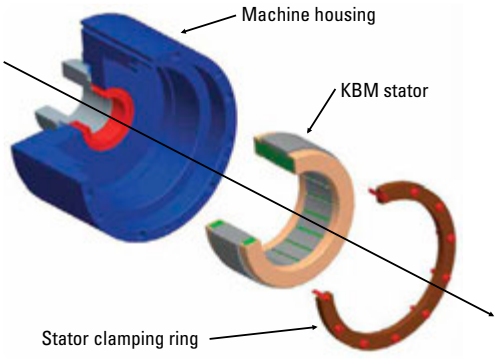
Standard configuration KBM(S) rotor hubs are constructed from non-plated cold rolled steel. If special plating, coating, cleaning or alternate material is desired, Kollmorgen engineers must confirm feasibility and pricing adjustment prior to quotation.

Stator Sleeve Material

Standard configuration KBM(S)-10, 14, 17, 25, 35, 45, 163 and 260 size stators are designed with uncoated aluminum sleeves around the stator lamination stack. If special coating or plating is desired for the aluminum stator sleeve, Kollmorgen engineers must confirm feasibility and pricing adjustment prior to quotation. Stator sleeves are only utilized for the sizes listed above.

Agency UL Information

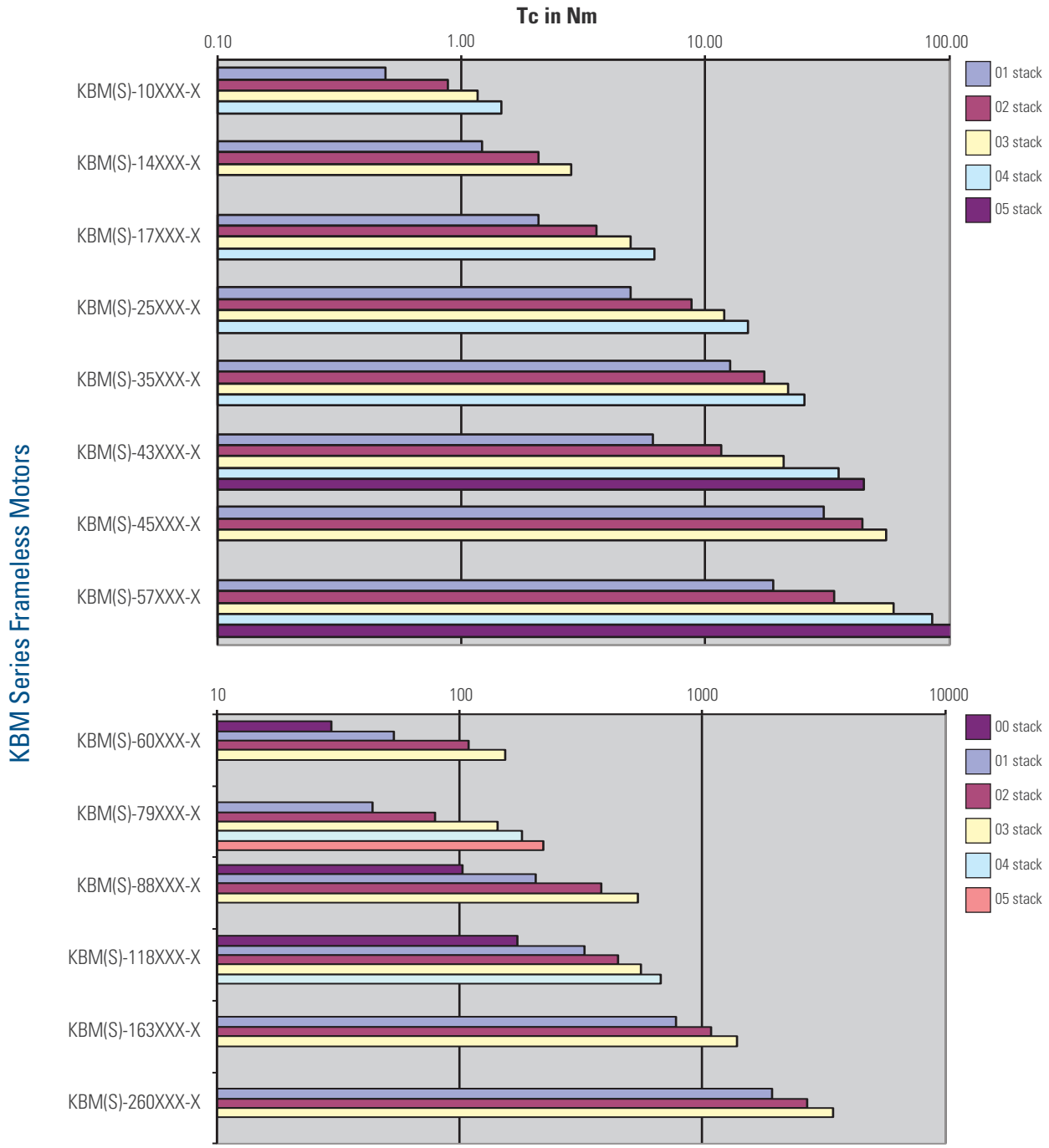
KBM(S) motors are designed to facilitate UL certification in the customer's higher-level assembly. Stator insulation systems are constructed entirely from agency-approved materials and are designed in full compliance with agency creepage and clearance dimensional guidelines. Dielectric strength between winding circuit and grounded metal stator surface is tested at agency-specified voltage level. Because a frameless motor's compliance with agency requirements is dependent upon correct installation and proper design of the surrounding enclosure by the user, KBM(S) series products are not formally labeled or agency-approved at the frameless motor level.



* Does not apply to KBM 163 and KBM 260.

KBM(S) Continuous Torque Overview

Select from our wide variety of sizes and torque ranges to suit your application needs.



For more detailed information please visit: http://www.kollmorgen.com/en-us/products/motors/direct-drive/kbm-series-frameless/

TBM Series Frameless Motors

The TBM frameless motor is a series of direct drive torque motors designed for applications that require high power in a small, compact form factor with minimized weight and inertia.

Typical applications include robotic joints, weapon stations, sensor gimbals, sight systems, UAV propulsion and guidance, as well as many others.

TBM(S) Product Features

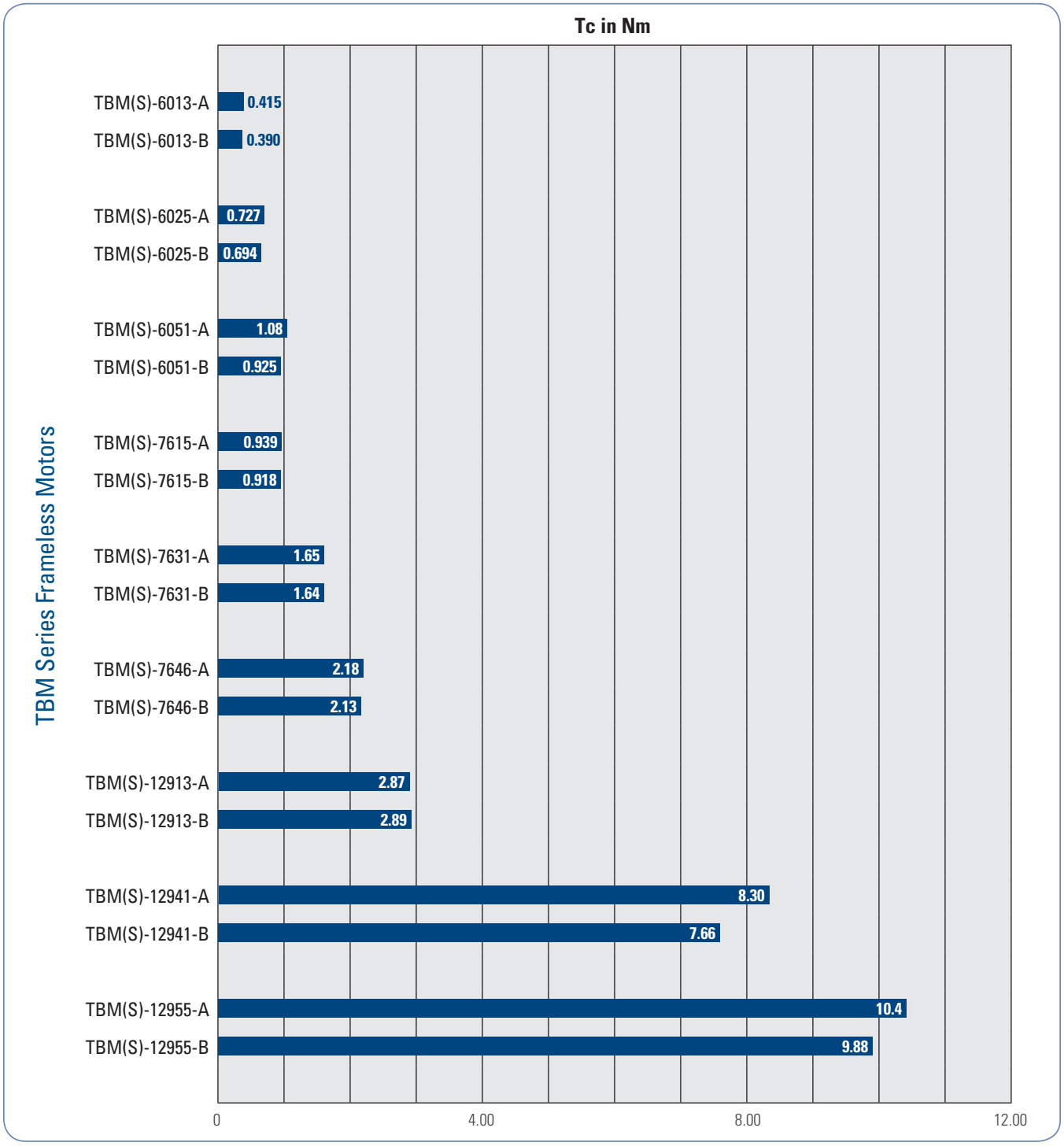
- 3 frame sizes ranging from 60mm (2.36 inches) up to 129mm (5.08 inches)
- 3 stacks lengths per frame
- 2 standard winding options per frame
- Latching Hall Effects (pre-aligned / factory installed)
- Low Cogging designs
- Stainless Steel Yokes for maximum corrosion protection
- RoHS Compliant
- Banded Rotors
- Laser Marked Armatures

For non-standard requests Kollmorgen provides a variety of standard options and configurations.

If higher levels of customization are required, contact Kollmorgen to help us understand exactly what you need.

TBM(S) Continuous Torque Overview

Select from our wide variety of sizes and torque ranges to suit your application needs.



For more detailed information please visit: http://www.kollmorgen.com/en-us/products/motors/direct-drive/tbm-series/

Stepper Drives and Motors

Our stepper motors, drives and controllers, which accommodate a wide range of power requirements, provide a high-performance, yet very cost-effective solution when you need precise motion control.

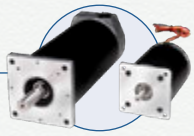
Our hybrid stepper motors are some of the highest torque-density motors in the industry. Available in several NEMA frame sizes, these 2 phase stepper motors inherently move in small, precise 0.9 or 1.8 degree increments (400 or 200 steps/revolution). This stepping action is simple to control and does not require complicated, expensive feedback devices. Our stepper motors are excellent alternatives to pneumatic, hydraulic and servo motor systems.

Kollmorgen's stepper drives are designed with versatility, ease-of-use, and cost-effectiveness in mind. Choose from a broad range of advanced drives and controls including full, half, and microstepping models in both modular and packaged designs.

Kollmorgen's stepper drives and motors are designed with versatility, ease–of–use, and cost-effectiveness in mind. The motors provide high torque in a small package and come in a wide range of standard sizes, constructions, windings and options. They are available with custom leads, shafts and connectors are routinely provided to effectively solve your application needs. Several models feature the addition of our innovative SIGMAX® technology for higher torque and acceleration rates.

P-Series Stepper Drives

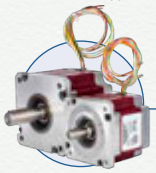
PMX Series Stepper



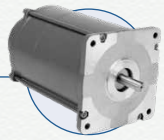
EH Series Stepper

MP Series Stepper

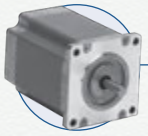
MX Explosion-Proof Series



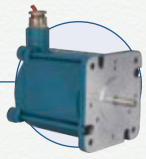
KN Series Stepper



MH172 Stepper

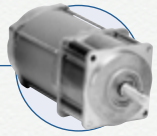


KS06 Synchronous



X Series Synchronous

SS Series Synchronous



SS Gearbox Synchronous

Best-in-Class Components

P-Series Stepper Drives work seamlessly with Kollmorgen stepper and synchronous motors for quality, reliability, and performance.

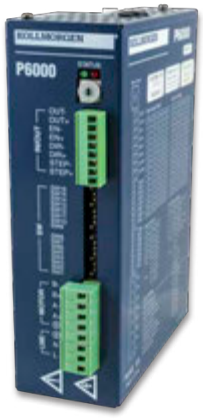
P-Series Drive Features and Benefits

P5000

Value DC Input Stepper Drive

- Wave matching for Kollmorgen motors to provide optimal performance
- All inputs and outputs are optically isolated
- Step and direction inputs or internal velocity controlled oscillator (VCO) dip switch selectable
- DIP switch selectable micro-stepping resolution settings
- Idle current reduction, DIP switch selectable
- Compensation for mid-range instability
- RoHS & CE certified
- UL pending

P6000



Full Featured AC Input Stepper Drive

- No programming required
- Covers full power range of Kollmorgen steppers
- Switch selectable current from 0.2-5.7 Arms, 8.0 A peak
- Switch selectable for many Kollmorgen motor parings
- All inputs and outputs are optically isolated
- Single-ended and differential step and direction
- Enable input
- Switch selectable micro-stepping resolution
- Anti-resonance based on load inertia
- RoHS & CE certified

P7000

Full Featured AC or DC Input Stepper Drives with Intelligent Indexing Option (-PN)

- AC and DC input versions
- Covers full power range of Kollmorgen steppers
- Drives can be configured by either dip switches or P7000 software
- Intelligent indexing option (-PN) provides ability to link motion tasks.
- All inputs and outputs are optically isolated
- Single-ended and differential step and direction
- Enable input
- Switch selectable micro-stepping resolution
- Anti-resonance based on load inertia
- RoHS, CE and UL certified

Budget/Value → Full–Featured

STEPPER DRIVE PRODUCT OVERVIEW

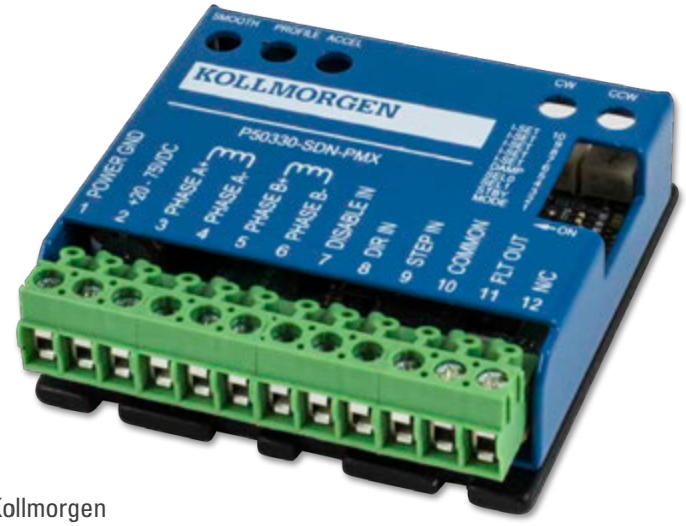
Stepper Drive Model	Modes of Operation*	Input voltage (Vdc)	Input Voltage (Vac)	Output current (Adc) Continuous (Peak)
P5000	S, V	20 - 75	n/a	0.7 - 2.0 (3.5)
P6000	S	n/a	110-240 +/-10%	0.3 - 5.7 (8.0)
P70530	S, M	20 - 75	n/a	0 - 5.0 (7.1)
P70360	S, M	n/a	120/240	0 - 2.5 (3.5)

Modes of Operation: S - Step and Direction; V - Velocity Controlled Oscillator (VCO);
M - Motion Node Indexing

P5000 Stepper Drive-Controller

Big Performance, Micro Package.

The P5000 is a compact micro-stepping stepper drive optimized for high system performance with Kollmorgen's industry leading POWERMAX II stepper motors. It is an impressive yet simple addition to the Kollmorgen stepper drive family.



P5000 Stepper Drive
(Shown Actual Size)

Optimized. Smooth. Compact.

Pairing a stepper system doesn't get any easier! The P5000 and Kollmorgen stepper motors are meant to be together. With Kollmorgen motor windings optimized for the P5000, all you have to do is set the dip switches for the motor you are paired with and you have a smooth operating system that fully utilizes the potential of your Kollmorgen motor and drive combination!

Features

- Current output from 0.7-3.5 Arms peak; DIP switch selectable in 0.2 Amp increments
- Bus Voltage 20-75 Vdc
- Wave matching for Kollmorgen motors to provide optimal performance for the Kollmorgen Stepper Motor Families.
- All Inputs and Outputs are Optically Isolated
- Command Source from External Step and Direction Inputs or Internal Velocity Controlled Oscillator (VCO); DIP switch selectable
- External Single-Ended Step and Direction Command
  - Disable or Fault Reset Input
  - Fault or Enable Output
- Pulse Multiplier smooths micro-stepping*
- Idle Current Reduction; DIP switch selectable
- Compensation for mid-range instability*
- VCO Mode
  - CW Limit Input
  - CCW Limit Input
  - Run/Stop Input
  - Run/Stop Output
  - CW Speed trimpot
  - CCW Speed trimpot
  - Accel/Decel trimpot
- DIP switch selectable micro-stepping-resolution settings
- RoHS & CE certified
- UL pending

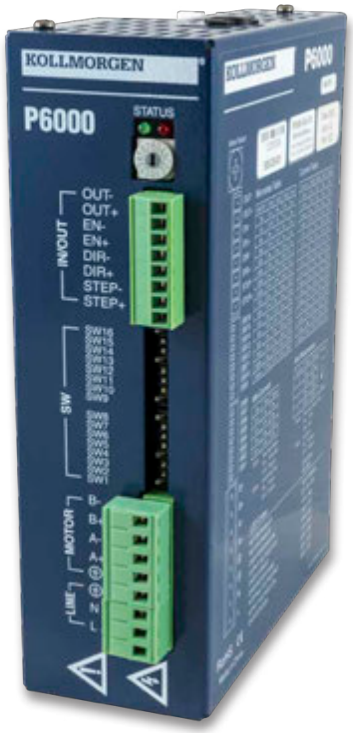
*Patents Pending

Note: For complete P-Series model nomenclature, refer to page 204.

P6000 Stepper Drive-Controller

Powerful, Yet Simple.

The P6000 is an AC input micro-stepping drive optimized for pairing with POWERPAC and POWERMAX stepper motors. With the simplicity of dip switches and the optimized performance from the complete system, this stepper solution brings increased machine performance without the associated complexity.



P6000 Stepper Drive

Powerful. Simple. Optimized.

The P6000 and Kollmorgen POWERPAC and POWERMAX stepper motors are designed to provide the best system solution when paired with one another. The easy dip switch selection matches the P6000 settings with the optimal Kollmorgen stepper motor requirements to provide the best performance and most efficient solution for nearly any application.

Features

- No programming required!
- Covers full power range of Kollmorgen Stepper Motors
- Switch Selectable Current Output from 0.2-5.7 Arms, 8.0 A peak
- 120/240 VAC Input (160/320 Vdc Bus)
- Kollmorgen Stepper Motor Pairing; Switch Selectable
- All Inputs and Outputs are Optically Isolated
- Single-Ended and Differential Step and Direction or CW/CCW Command; Switch Selectable
- Enable Input
- Fault Output (Sinking or Sourcing)
- Status LEDs for easy troubleshooting
- Switch Selectable Micro-Stepping-Resolution Settings
- Step Smoothing Filter; Switch Selectable
- Idle Current Reduction; Switch Selectable
- Anti-Resonance Based On Load Inertia; Switch Selectable
- Self-Test Conducts Spin Test to Confirm Proper Connection; Switch Selectable
- RoHS & CE Certified

Note: For complete P-Series model nomenclature, refer to page 204.

P7000 Stepper Drive-Controller

P7000 stepper drives offer a unique level of system functionality, smoothness, high-speed performance and innovation unmatched in the industry.

The compact P7000 is designed to power Kollmorgen step motors ranging from NEMA size 17 up to NEMA size 42. Two power configurations are available for operation directly from AC power, or from a DC power supply.

There are two levels of control offered. The basic drive accepts step and direction inputs. P7000 drives are also available with an integrated position controller (-PN option). The drives are configured by either on-board dip switches, or with the P7000 tools software.

Advanced P7000 Features Make it the Best Choice to Meet Your Application Requirements

Multistepping™

Also known as auto-smoothing. The P7000 drive accepts full step pulse commands from the indexer and inserts fine micro-steps to smooth coarse low speed motion. This allows you to significantly upgrade machine performance without having to redesign machine control architecture.

Auto-Tuning

Advanced current auto-tuning techniques provide outstanding low-speed smoothness. The P7000 senses the motor's characteristics and automatically fine tunes itself to meet your high-performance needs. This reduces installation and set-up time.

Mid-Band Anti-Resonance Control

Reduces negative effects of mechanical resonance, allowing you to get more out of a smaller motor and virtually eliminating nuisance stalls and machine downtime.

Idle Current Reduction

If you do not require the motor's full torque to hold a load at rest, you can select the right amount of current (torque) to reduce motor heating and power consumption. This increases the life of the system.

Dynamic Smoothing

Quasi-S-curve algorithm reduces jerk, especially upon acceleration. Increases mechanical life of the machine and reduces energy consumption.

Intelligent Indexing Option (-PN)

Wizard-like P7000 helps you to develop and link motion tasks such as homing and conditional and unconditional indexing. You can be up-and-running quickly.

Modbus RTU Compatible

The intelligent indexing option (-PN) supports Modbus RTU to control motion with an external interface device. External interfaces make controlling motion simple for machine operators.

P7000 Tools

The position node option allows you to configure up to 63 absolute or relative moves. You can specify the moves' distance, acceleration, velocity, and deceleration rates, or simply specify the distance and total time for the move – P7000 will perform the calculations automatically.

Specifications	Units	P70530	P70360
Input voltage range	Volts	20 - 75 Vdc	120 or 240 Vac
Continuous current	Amps rms	5	2.5
Microstep peak current	Amps peak	7.1	3.5

Note: For complete P-Series model nomenclature, refer to page 204.

Stepper Motor Overview

Kollmorgen offers a comprehensive range of stepper motor products including continuous torque, high torque and hybrid options to meet a wide range of application requirements. For other Kollmorgen stepper products or information not included in this catalog go to www.kollmorgen.com.

		Product Family	NEMA	Step	Stacks	Holding Torque (oz-in)
Economy, Push		PMX08	08	1.8°	2	4.0
		PMX11	11	1.8°	3	16.8
		PMX14	14	1.8°	3	26.4
		PMX17	17	0.9° 1.8°	5	107.0
		PMX23	23	0.9° 1.8°	4	378.0
		PMX34	34	1.8°	4	1739
Economy		CTP1	17	1.8°	3	80
		CTP2 CTM2	23	1.8°	3	360 470
Flagship Products		P2 M2	23	1.8°	3	214 253
		T2	23	1.8°	4	380
		N3 K3	34	1.8°	4	2180 2790
		N4 K4	42	1.8°	3	4370 5660
Conventional Round Flange		H2 E2	23	1.8°	3	158 225
		H3 E3	34	1.8°	3	916 1300
		H4 E4	42	1.8°	3	2650 3960
		MH172	66	1.8°	1	6139
Special Purpose		MX9	34	1.8°	3	550
		MX11	42	1.8°	2	1390

Holding Torque (oz-in): 400, 1200, 2000, 2800, 3600, 4400, 5200, 6000

Standard Stepper Motor Construction

Step motor utilizing SIGMAX® Technology

Product Family	NEMA	Features: UL Recognized	Features: CE Mark	Features: RoHS	Features: SIGMAX® Technology	Standard Options (○ available option): Integral Connectoin	Leadwire	4-Lead Bipolar	6-Lead Unipolar	8-Lead	Terminal Box	MS Connector	IP Sealing	Encoders	Front Shaft: Normal	Front Shaft: Flat	Front Shaft: Keyway	Rear Shaft	Low Inertia	Family Features
PMX08	08		•	•			•	•					30		○	•		•		• NEMA Sizes 8, 11, 14, 17, 23, 34 • CE, RoHS, and REACH Compliant • Unipolar or Bipolar windings • Options: shaft flats, rear shaft with encoder mounting holes, IP Sealing • Special Options readily available: spur and planetary gearboxes, encoders, special shafts
PMX11	11		•	•			•	•					30		○	•		•		
PMX14	14		•	•			•	•					30		○	•		•		
PMX17	17		•	•		•	•	•	○				30		○	•		•		
PMX23	23		•	•		•	•	•	○				30		○	•		•		
PMX34	34		•	•			•	•					30		○	•	○	•		
CTP1	17	•	•	•			•	•	•				40		•			•		• High torque standard CTP models • Enhanced CTM SIGMAX models produce up to 25% more torque in same package • Large bearings provide high thrust and radial loads
CTP2 CTM2	23	• •	• •	• •	• •		• •	• •	• •				40		•	○		• •		
P2 M2	23	• •	• •		• •	• •	• •			• •			40 40	• •	• •	○ ○		• •	• •	• High torque standard hybrid stepper motor • Enhanced M and K SIGMAX models provide up to 25% more torque in same package • Low detent torque for smoother microstepping • Bipolar and unipolar winding • Large array of options
T2	23	•	•				•	•	•		•	•	40	•	•	○		•		
K3 N3	34	• •	• •		• •		• •	• •	• •	• •	• •	• •	65[1] 65[1]	• •			• •	• •		
K4 N4	42	• •	• •		• •		• •	• •	• •	• •	• •	• •	65[1] 65[1]	• •			• •	• •		
H2 E2	23	• •	• •		• •		• •	• •	• •	• •		• •	40 40	• •	• •	○ ○		• •	• •	• High efficiency, low loss hybrid designs in a conventional round frame • Enhanced E SIGMAX models provide up to 25% more torque in the same package • Torque produced over a wide speed range • Large array of options • E2, H2 offer high axial loading
H3 E3	34	• •	• •		• •		• •	• •	• •	• •		• •	65[1] 65[1]	• •	• •	○ ○		• •		
H4 E4	42	• •	• •		• •		• •	• •	• •	• •		• •	65[2] 65[2]	• •			• •	• •		
MH172	66										•		40	•			•	•		
MX9	34	•											40		•			•		• Standard hybrid stepper motor • Meets Explosion proof UL Class 1, Division 1 Group D requirements • Up to 150% rated torque reserve capacity (MX9) and 200% for {MX11}
MX11	42	•											40			•		•		

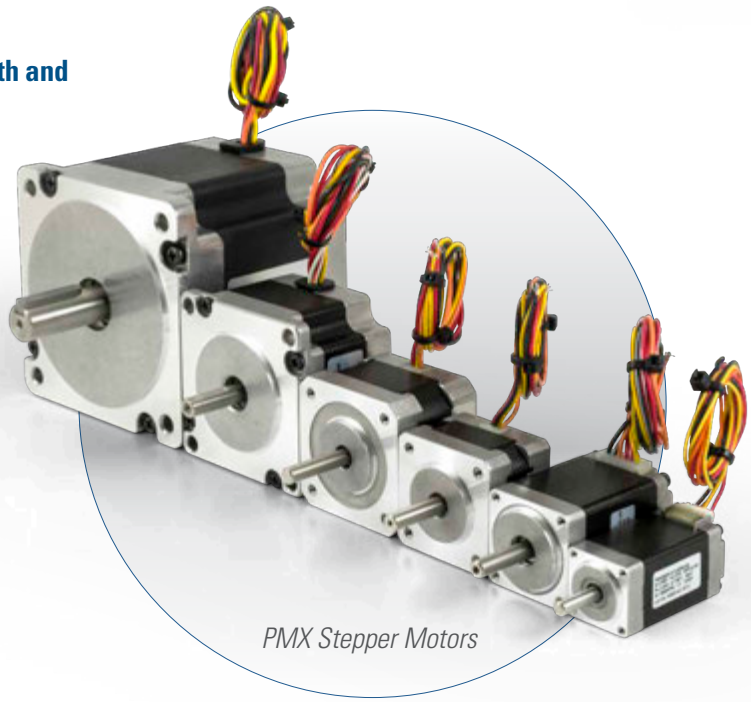
Notes: 1. Requires shaft seal and connection option other than leaded (Meets IP40 otherwise)
2. Requires shaft seal option (Meets IP40 otherwise)

Hybrid PMX Step Motor

Kollmorgen's PMX™ stepper motor line delivers breadth and design flexibility at competitive lead times.

Kollmorgen is excited to continue its winning heritage in hybrid stepper motors with the PMX family. Leveraging the best practices from customer preferred products in the POWERMAX and POWERPAC families, the PMX lines will deliver breadth and design flexibility at a very competitive lead time. Look no further for that hybrid stepper motor family with local support that gives you the flexibility you need to succeed.

PMX Series motors include smaller Nema 08, 11, and 14 frame sizes in addition to the traditional Nema 17, 23, and 34 frame sizes. Each frame size is built with high quality construction in an affordable, market competitive solution. Numerous co-engineering options are also available including: customizing shafts, encoders, and mounted spur and planetary gearboxes.



PMX Stepper Motors

- **Increased Design Flexibility** – six frame sizes (08, 11, 14, 17, 23, 34) each with several stack length and winding options available
- **Minimal Drive Adjustments** – options for 1.8 and 0.9 degree step angles
- **Lower Unit Cost** – PMX motors are priced competitively in today's current stepper market and are the lowest of all Kollmorgen stepper products
- **Quality Construction** translates to reliability in the field and a long service life
- **Localized Support** gives you the delivery terms and immediate technical support you need, meaning quicker time to market and less downtime
- **Flexible Manufacturing** enables Kollmorgen to immediately evaluate modifications and co-engineered solutions for rapid prototyping
- **Easy to Apply Worldwide** – CE, RoHS, REACH

Many Applications

PMX motors allow Kollmorgen customers to fulfill their automation needs at an affordable cost, enabling higher throughput in a wide variety of equipment. In addition, leveraging Kollmorgen's technical expertise and flexible engineering, the PMX is ready for seamless special and co-engineering options, allowing for swifter and easier integration into both new and existing applications.

PMX Stepper Motor General Specifications

Series		Stacks	Holding Torque (Motor Mounted) Bipolar oz-in	Holding Torque (Motor Mounted) Bipolar Nm	Length in	Length mm	Features
Size 08 PMX Series		2 Phase, 1.8° Step Motors. Frame size: 0.8 inch, 20 mm					
		PMX081	1	2.50	0.018	1.18	30.0	• Front shaft flat option • Rear shaft option
		PMX082	2	4.00	0.028	1.65	42.0	
Size 11 PMX Series		2 Phase, 1.8° Step Motors. Frame size: 1.1 inch, 28 mm					
		PMX111	1	10.1	0.071	1.26	32.0	• Front shaft flat option • Rear shaft option • Integral connector option
		PMX112	2	16.1	0.114	1.77	45.0	
		PMX113	3	16.8	0.119	2.01	51.0	
Size 14 PMX Series		2 Phase, 1.8° Step Motors. Frame size: 1.4 inch, 35 mm					
		PMX141	1	14.7	0.104	1.02	26.0	• Front shaft flat option • Rear shaft option • Rear encoder mounting holes
		PMX142	2	20.1	0.142	1.10	28.0	
		PMX143	3	26.4	0.186	1.42	36.0	
Size 17 PMX Series		2 Phase, 0.9° or 1.8° Step Motors. Frame size: 1.7 inch, 42 mm					
		PMX171 (1.8)	1	28.4	0.201	1.02	26.0	• Front shaft flat option • Rear shaft option • Integral connector option • Bipolar or Unipolar winding available • Rear encoder mounting holes
		PMX172 (1.8)	2	40	0.281	1.32	33.5	
		PMX173 (1.8)	3	61	0.427	1.56	39.5	
		PMX174 (1.8)	4	78	0.551	1.87	47.5	
		PMX171 (1.8)	5	107	0.756	2.36	60.0	
Size 23 PMX Series		2 Phase, 0.9° or 1.8° Step Motors. Frame size: 2.2 inch, 57 mm					
		PMX231 (1.8)	1	102	0.722	1.61	41.0	• Front shaft flat option • Bipolar or Unipolar winding available • Rear shaft option • Integral connector option • Rear encoder mounting holes
		PMX232 (1.8)	2	208	1.47	2.20	56.0	
		PMX233 (1.8)	3	337	2.38	2.99	76.0	
		PMX234 (1.8)	4	378	2.67	3.35	85.0	
Size 34 PMX Series		2 Phase, 1.8° Step Motors. Frame size: 3.4 inch, 86 mm					
		PMX341	1	490	3.46	2.56	65.0	• Front shaft flat option • Rear shaft option
		PMX342	2	704	4.97	3.15	80.0	
		PMX343	3	1285	9.07	4.65	118.0	
		PM344	4	1739	12.28	6.14	156.0	

Note: For complete PMX series model nomenclature, refer to page 204.

Hybrid CT and N/K Series Step Motors

CT Series

CT Series motors include the most popular sizes, options and value suitable for most commercial and industrial applications. Enhanced motors provide the maximum performance available. This patented technology boosts torque an additional 25% to 40% across the entire speed range, and allows machines to be designed that are smaller and move faster.

CT Series Benefits

- Smaller drives result in a lower system cost
- More torque allows for smaller, faster machines
- Higher efficiency enables lower operating costs

Size 17 CT Series

2 Phase, 1.8° Step Motors. Frame size: 1.7 inch, 43 mm
(CTP High Torque Performance Series)

Series	Construction		Holding Torque (Motor Mounted)		Length		
	Style	Stacks	Bipolar		in	mm	
			oz-in	Nm			
CTP10	Un-Enhanced	Short	43	0.30	1.37	34.7	• Inch or metric mounting • Rear shaft option
CTP11		1	62	0.44	1.61	40.9	
CTP12		2	80	0.56	1.92	48.8	

Size 22 CT Series

2 Phase, 1.8° Step Motors. Frame size: 2.2 inch, 57 mm
(CTM Enhanced-Max Torque and Efficiency, CTP High Torque Performance Series)

Series	Construction		Holding Torque (Motor Mounted)		Length		
	Style	Stacks	Bipolar		in	mm	
			oz-in	Nm			
CTM21	Enhanced	1	260	1.84	2.13	54.1	• Captured heavy duty bearings • High voltage insulation system • Rear shaft option
CTM22		2	470	3.32	3.32	84.3	
CTP20	Un-Enhanced	Short	100	0.71	1.62	41.2	
CTP21		1	200	1.41	2.13	54.1	
CTP22		2	360	2.54	3.32	84.3	

Note: For complete CT series model nomenclature, refer to page 205.

N/K Series

The N/K Series are larger step motors with the power, rugged construction, and options that make these motors ideal for heavy industrial applications. Options include: IP56, terminal boxes and MS connectors. Enhanced versions provide the maximum performance torque available. This patented technology boosts torque an additional 25% to 40%. Custom motors are available to meet specific application needs including: modified shafts, connectors, lead-screws, and components mounted to the shaft.

N/K Series Benefits

- More torque to drive heavy loads
- Smaller drives result in a lower system cost
- Higher efficiency enables lower operating costs

Size 34 N/K

2 Phase, 1.8° Step Motors. Frame size: 3.4 inch, 87 mm

Series	Construction		Holding Torque (Motor Mounted)		Length	
	Style	Stacks	Bipolar		in	mm
			oz-in	Nm		
K31	Enhanced	1	830	5.9	3.7	94
K32		2	1530	10.8	5.22	133
K33		3	2200	15.6	6.74	171
K34		4	2770	19.6	8.25	210
N31	Un-Enhanced	1	650	4.6	3.7	94
N32		2	1220	8.6	5.22	133
N33		3	1760	12.4	6.74	171
N34		4	2170	15.3	8.25	210

- Captured heavy duty bearings
- High voltage insulation system
- Options: Terminal box
  MS connectors
  Rear shaft
  Encoder
  Front shaft seal

Size 42 N/K

2 Phase, 1.8° Step Motors. Frame size: 3.4 inch, 87 mm

Series	Construction		Holding Torque (Motor Mounted)		Length	
	Style	Stacks	Bipolar		in	mm
			oz-in	Nm		
K41	Enhanced	1	2090	14.8	3.89	99
K42		2	4000	28.2	5.91	150
K43		3	5650	39.9	7.92	201
N41	Un-Enhanced	1	1630	11.5	3.89	99
N42		2	3140	22.2	5.91	150
N43		3	4340	30.6	7.92	201

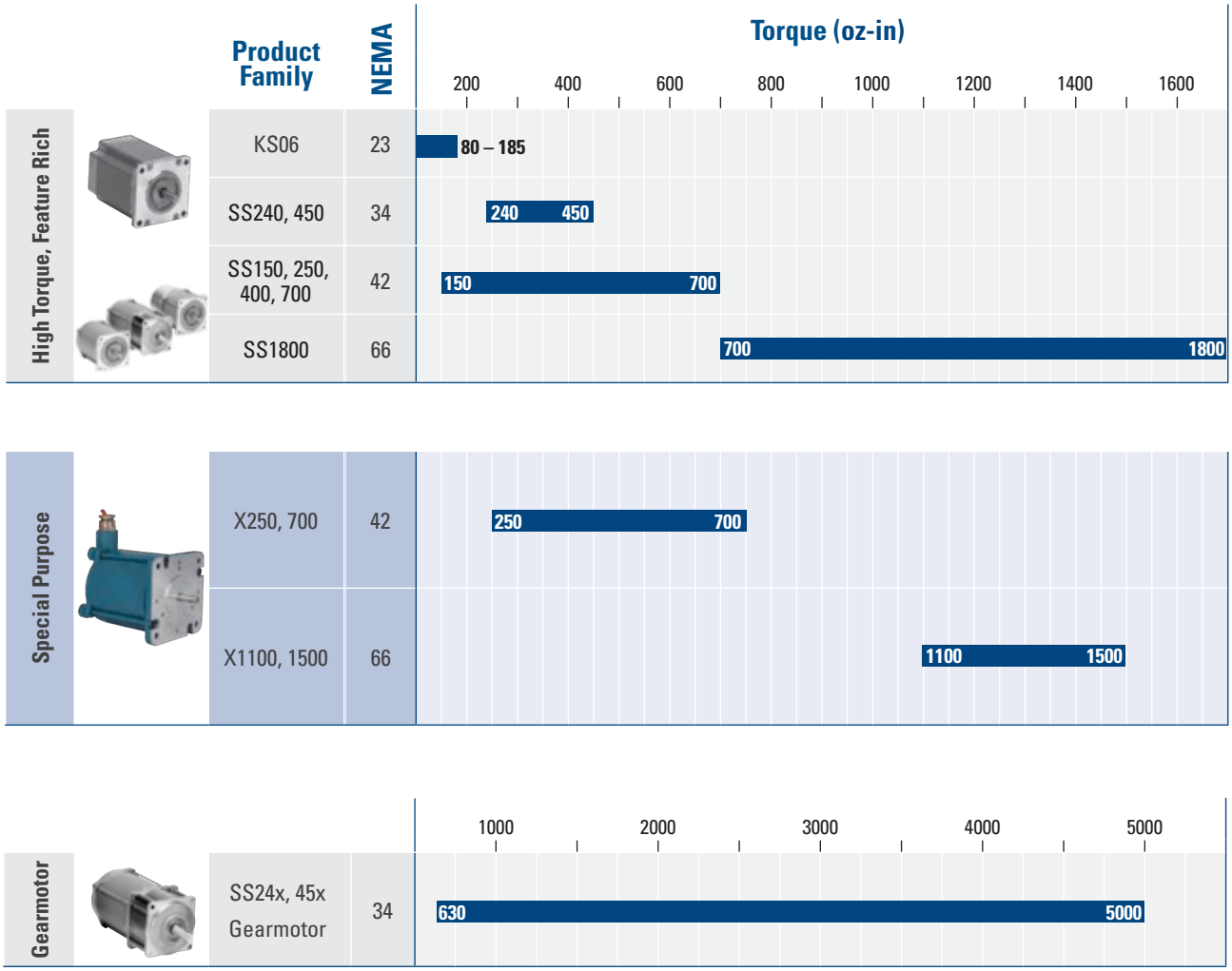
- Captured heavy duty bearings
- High voltage insulation system
- Options: Terminal box
  MS connectors
  Rear shaft
  Encoder
  Front shaft seal

Note: For complete N/K series model nomenclature, refer to page 208.

AC Synchronous Motor Overview

Kollmorgen offers a comprehensive range of AC synchronous motor products including continous torque, high torque and hybrid options to meet a wide range of application requirements. For products not included in this catalog go to www.kollmorgen.com for information about other Kollmorgen synchronous motor products.

Flagship Products



Product Family	NEMA	Phases	Options: Leaded	Options: Terminal Box	Options: Rear Shaft	Family Features
KS06	23	1Ø	•	•	•	• 1Ø and 3Ø (SS240, 450 models only) • 72 rpm motor speed (with 60 Hz voltage) • 60 rpm motor speed (with 50 Hz voltage) • 120 volt or 240 volt AC models • Torques: 80 – 1800 oz-in (0.56 – 12.7 Nm) • Fast starting, stopping, or reversing • Can be stalled indefinitely without overheating
SS240, 450	34	3Ø	•	•	•	
SS150, 250,400, 700	42	1Ø	•	•	•	
SS1800	66	1Ø	•	•	•	
X250, 700	42	1Ø	•		•	• 1Ø models • X models meet UL Class 1, Group D requirements • X models meet ATEX, Exd IIC T5 Gb rqmt. • 60 and 50 Hz models (72 and 60 rpm respectively) • 120 volt or 240 volt AC models • Torques: 250 – 1500 oz-in (1.77 – 10.6 Nm) • Fast starting, stopping, or reversing • Can be stalled indefinitely without overheating
X1100, 1500	66	1Ø	•		•	
SS240, 450 Gearmotor	34	3Ø	•	•	•	• All the features of the SS240, 450 series • Gear reducers with ratios up to 125:1 • Torques: 634 - 5000 oz-in (4.48 – 35.3 Nm)

Micron® Quick Selection Guide

Micron® Gearbox①	Product Prefix	Maximum Backlash [arc/min] (for the product life) ②	Relative Price	In-line / Right Angle Frame Sizes [mm]	In-line / Right Angle Ratio Availability③	Maximum input speed [RPM] ④	Relative Torque Capacity	Expected Noise Level [db]	Modification Costs	Efficiency [%]	Housing Material
UltraTRUE 	UT UTR	4/5	1.2 ×	60 - 220 60 - 140	4:1 - 100:1 1:1 - 50:1	6000	2.8 ×	66	Very Low	95	Stainless and Aluminum
ValueTRUE 	VT VTR	4/5	0.7 ×	60 - 220 60 - 140	4:1 - 100:1 1:1 - 50:1	6000	2.6 ×	66	Low	95	Stainless and Aluminum
EverTRUE 	ET	4/5	1.5 ×	100 - 180	4:1 - 100:1	6000	2.8 ×	68	Low	95	Stainless and Aluminum
DuraTRUE 	DT DTR	8/9	1.0 ×	60 - 140 60 - 140	3:1 - 100:1 1:1 - 500:1	6000	1.0 ×	68	Very Low	93	Anondized Aluminum
NemaTRUE 	NT NTR	13/15	0.5 ×	60 - 15 (23 - 42) 60 - 115 (23 - 42)	3:1 - 100:1 1:1 - 500:1	6000	0.7 ×	68	Very Low	93	Anondized Aluminum
XTRUE 	XT XTA	13/15	0.4 ×	40 - 160	3:1 - 100:1	6000	1.1 ×	68	Low	93	Anondized Aluminum

① All products are dimensional drop in replacement. The catalog should be reviewed for length and width details.
② Backlash is measured at the output shaft, with the input fixed, using 2% of the rated torque in both directions.
③ Other ratios available, contact customer support for more information.
④ Speeds greater than 6000 RPM need to be reviewed by application engineering.

	Product Prefix	Lower Backlash Option ⑤	Double Stage Available	True Planetary Gearing	Helical Crowned Gearing	Lubricated for Life	Dual and Hollow Shafts Available	3D CAD Models on Micron Motioneering	One Piece Output Shaft/Carrier	Internal Gear Machined into Housing	ROHS Compliant ⑥	Case Hardened Gears (HRC60)	Gearbox Express ⑦	Low Temperature Grease Available	Food Grade Grease Available	NSF Certified	RediMount Compliant
UltraTRUE	UT UTR		•	•	•	•		•	•	•	•	•	•	•	•		•
ValueTRUE	VT VTR		•	•	•	•		•	•	•	•	•	•	•	•		•
EverTRUE	ET		•	•		•		•	•	•	•	•	•	•	•		•
DuraTRUE	DT DTR		•	•		•	•	•	•		•	•	•	•	•		•
NemaTRUE	NT NTR	•	•	•		•		•	•		•	•	•	•	•		•
XTRUE	XT XTA	•	•	•		•		•	•		•	•		•	•	•	

⑤ Lower backlash, high precision available (8/9 arc-min).
⑥ ROHS on right angle product is still being confirmed.
⑦ Geahead express not available in frame sizes larger than 140 mm or dual and hollow shafts.

6 Reasons to Choose Micron® Gearboxes

1 RediMount™ – Fast and Error Free Motor Mounting
The unique RediMount system will mount any Micron gearhead to any motor in just three simple steps in less than five minutes!

2 Superior Technology
All Micron gears are case hardened to HRC60 for longer life. Our UltraTRUE and ValueTRUE models have a higher helix angle (15 °) than our competitors' helical gearheads resulting in less backlash, smoother and quieter operation and longer life.

3 Lubricated For Life
Micron gearheads require no maintenance and are grease filled. Unlike oil filled units, they can be mounted in any orientation and will never leak.

4 Unmatched Product Breadth
Micron has the largest selection of planetary gearheads in the world with over 3000 size and ratio combinations.

5 Unmatched Quality
All Micron gearheads are tested through our state of the art end of line tester, making our outgoing quality the best in the market.

6 Made in the USA
All Micron Gearheads are manufactured in the USA making us able to respond to emergencies quickly reducing down time for our customers.

Planetary Gearbox Technology

Helical gears are known for their quiet and smooth operation along with their ability to transmit higher loads than spur gears. Both of these features of helical gearing result from the improved contact ratio (effective teeth in mesh) over spur gears.

A high torque, whisper quiet helical gearbox has been designed by combining the positive attributes of gear crowning and helical gearing with the planetary construction to create the smoothest operating gearbox on the market.

- Broadest product range of gearboxes in the industry
- Innovative gear technology offers size and performance advantages
- RediMount™ system provides error-free and reliable installations

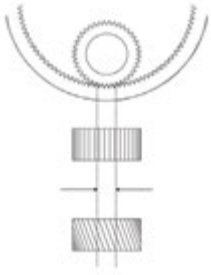
Helical Crowned TRUE Planetary™ Gearing

Features

- High torque capacity
- Low backlash
- Smooth operation
- Greater load sharing
- Whisper quiet

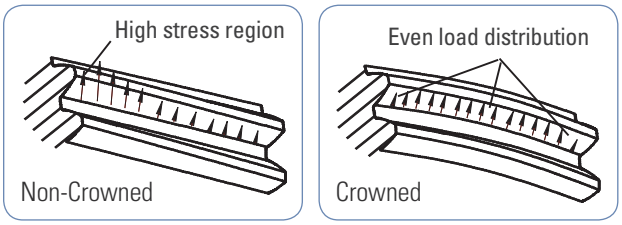
Spur vs. Helical Gearing

Typical contact ratio is 1.5 for spur gearing. Contact ratio for equivalent helical gear is 3.3 – more than double the contact ratio.



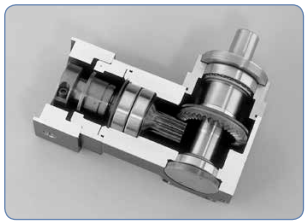
Crowned vs. Non-Crowned

Crowning optimizes the gear mesh alignment within a gear train to increase the torque capacity and reduce noise. It also enhances load distribution on the tooth flank to reduce high stress regions.



PowerTRUE™ Right Angle Gearboxes

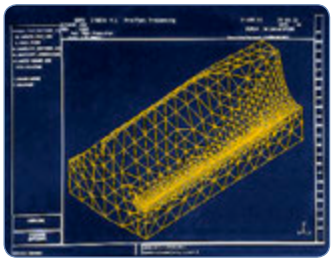
- Lower backlash from single axis mesh adjustment
- A compact design using face gear technology
- Whisper quiet operation due to high contact ratio
- Mesh ratios from 1:1 to 5:1
- Extremely efficient (98%)



PowerTRUE™ gear technology

Computerized mapping of gear tooth profile

All Micron right angle gearboxes use the PowerTRUE technology which increases the mesh ratio to 5:1 compared to a maximum of 3:1 typical in bevel gears.



Multiple teeth in the face gear simultaneously mesh with a standard involute pinion. The continuous tooth engagement yields a high contact ratio between the gear and the pinion, increasing torque and efficiency.

NEMA TRUE™

True planetary gearbox, flange mount design with anodized aluminum housing employing RediMount™ system.

Inline	Frame Size		Max T Peak (lb-in)		All Sizes	Gear Ratios Available	Efficiency	Backlash (arc-min)
	English	Metric	1 Stage	2 Stage				
Size 17	NEMA 17	42 mm	170	170	1 Stage	3, 4, 5, 7, 10	93%	13 (8)*
Size 23 / 60	NEMA 23	60 mm	250	275				
Size 34 / 90	NEMA 34	90 mm	700	850	2 Stage	15, 20, 25, 30, 40, 50, 70, 100	88%	15 (9)*
Size 42 / 115	NEMA 42	115 mm	1000	1600				

NEMA TRUE™

True planetary gearbox, flange mount design with anodized aluminum housing employing RediMount™ system.

Right Angle	Frame Size		Max T Peak (lb-in)			All Sizes	Gear Ratios Available	Efficiency	Backlash (arc-min)
	English	Metric	1 Stage	2 Stage	3 Stage				
Size 23 / 60	NEMA 23	60 mm	360	366	366	1 Stage	1, 2, 3, 4, 5P	98%	13
Size 34 / 90	NEMA 34	90 mm	1110	1110	1110	2 Stage	5T, 6, 9, 10, 12, 15, 20, 25, 30, 40, 50	93%	15
Size 42 / 115	NEMA 42	115 mm	2250	2250	2250	3 Stage	60, 75, 90, 100, 120, 125, 150, 200, 250, 300, 400, 500	88%	15

XTRUE™

The XTRUE Series is a new precision gearbox employing RediMount™ system that compliments our TRUE planetary gearbox line – already the largest selection of planetary gearboxes in the world.

Inline	Frame Size Metric	Max T Peak (lb-in)		All Sizes	Gear Ratios Available	Efficiency	Backlash (arc-min)
		1 Stage	2 Stage				
XT040	40 mm	162	299	1 Stage	3, 4, 5, 7, 8, 10	93%	13
XT060	60 mm	483	483				
XT080	80 mm	1460	1550				
XT120	120 mm	2640	2640				
XT160	160 mm	7750	7750				
XTA050	50 mm	162	299	2 Stage	15, 20, 25, 30, 40, 50, 70, 80, 100	88%	15
XTA070	70 mm	483	483				
XTA090	90 mm	1460	1552				
XTA120	120 mm	2639	2639				

EverTRUE™

EverTRUE, employing RediMount™ system, is specifically designed for 24/7 continuous running applications providing 3 times (30,000 hours) service life.

Inline	Frame Size Metric	Max T Peak (lb-in)		All Sizes	Gear Ratios Available	Efficiency	Backlash (arc-min)
		1 Stage	2 Stage				
ET010	101 mm	4093	4794	1 Stage	4, 5, 7, 10	95%	4
ET014	141 mm	9430	11,250	2 Stage	16, 20, 25, 28, 35, 40, 50, 70, 100	90%	5
ET018	182 mm	21,600	26,280				

Note 1: Torque capacity is maximum of frame size stage design, not all ratios have the same rated torque capacity.
Note 2: Torque capacity is the maximum allowable momentary torque for emergency stopping or heavy shock loading.
Note 3: Ratio 5P is designed using the compact PowerTrue face gearing technology.
Note 4: Ratio 5T is designed using a True planetary gear stage for increased torque capacity.
Note 5: For complete gearbox model nomenclature, refer to page 214.

Micron™ TRUE Planetary™ Gearbox

DuraTRUE™

True planetary gearbox, flange mount design with anodized aluminum housing employing RediMount™ system.

Inline	Frame Size Metric	Max T Peak (lb-in)		All Sizes	Gear Ratios Available	Efficiency	Backlash (arc-min)
		1 Stage	2 Stage				
DT60	60 mm	460	460	1 Stage	3, 4, 5, 7, 10	93%	8
DT90	90 mm	1480	1480				
DT115	115 mm	2513	2513	2 Stage	15, 20, 25, 30, 40, 50, 70, 100	88%	9
DT142	142 mm	7380	7380				

DuraTRUE™

True planetary right angle gearbox, flange mount design with anodized aluminum housing employing RediMount™ system.

Right Angle	Frame Size Metric	Max T Peak (lb-in)		All Sizes	Gear Ratios Available	Efficiency	Backlash (arc-min)
		1 Stage	2 Stage				
DTR60	60 mm	460	460	1 Stage	5, 6, 9, 10, 12, 15, 20, 25, 30, 40, 50	93%	8
DTR90	90 mm	1480	1480				
DTR115	115 mm	2513	2513	2 Stage	60, 75, 90, 100, 120, 125, 150, 200, 250, 300, 400, 500	88%	9
DTR142	142 mm	7380	7380				

Slimline

Slimline right angle gearbox, flange mount design with anodized aluminum housing employing RediMount™ system.
Face gear technology for compact right angle construction. Dual shaft output version also available.

Right Angle	Frame Size Metric	Max T Peak (lb-in)			All Sizes	Gear Ratios Available	Efficiency	Backlash (arc-min)
		1 Stage	2 Stage	3 Stage				
DTR60S	60 mm	400	407	407	1 Stage	1, 2, 3, 4, 5P	98%	8
DTR90S	90 mm	1237	1237	1237	2 Stage	5T, 6, 9, 10, 12, 15, 20, 25, 30, 40, 50	93%	9
DTR115S	115 mm	2265	2505	2505	3 Stage	60, 75, 90, 100, 120, 125, 150, 200, 250, 300, 400, 500	88%	9
DTR142S	142 mm	5500	6917	7450				

Hollow Shaft

Hollow shaft right angle gearbox, flange mount design with anodized aluminum housing employing RediMount™ system.
Large diameter/ bolt circle for direct mechanical interface. Face gear technology for compact right angle construction.

Right Angle	Frame Size Metric	Max T Peak (lb-in)			All Sizes	Gear Ratios Available	Efficiency	Backlash (arc-min)
		1 Stage	2 Stage	3 Stage				
DTR90H	90 mm	1237	1237	1237	1 Stage	1, 2, 3, 4, 5P	98%	8
DTR115H	115 mm	2505	2505	2505	2 Stage	5T, 6, 9, 10, 12, 15, 20, 25, 30, 40, 50	93%	9
DTR142H	142 mm	7660	7660	7660	3 Stage	60, 75, 90, 100, 120, 125, 150, 200, 250, 300, 400, 500	88%	9

Note 1: Torque Capacity is maximum of frame size stage design, not all ratios have the same rated torque capacity.
Note 2: Torque Capacity is the maximum allowable momentary torque for emergency stopping or heavy shock loading.
Note 3: Ratio 5P is designed using the compact PowerTrue face gearing technology.
Note 4: Ratio 5T is designed using a True planetary gear stage for increased torque capacity.
Note 5: For complete gearbox model nomenclature, refer to page 214.

CE ISO RoHS

ValueTRUE™

Helical True planetary gearbox, flange mount design with stainless steel housing employing RediMount™ system.

Inline	Frame Size Metric	Max T Peak (lb-in)		All Sizes	Gear Ratios Available	Efficiency	Backlash (arc-min)
		1 Stage	2 Stage				
VT006	61 mm	800	910	1 Stage	4, 5, 7, 10	95%	4
VT075	75 mm	1423	1632				
VT090	90 mm	1423	1632				
VT010	101 mm	4093	4794				
VT115	115 mm	4093	4794	2 Stage	16, 20, 25, 28, 35, 40, 50, 70, 100	90%	5
VT014	141 mm	9430	11,250				
VT018	182 mm	21,609	26,287				
VT022	220 mm	36,986	44,000				

ValueTRUE™

Helical True planetary gearbox, flange mount design with stainless steel housing employing RediMount™ system.

Right Angle	Frame Size Metric	Max T Peak (lb-in)	All Sizes*	Gear Ratios Available	Efficiency	Backlash (arc-min)
		1 Stage				
VTR006	61 mm	876	1 Stage	4, 5, 8, 10, 12, 14, 15, 16, 20, 25, 28, 30, 35, 40, 50	93%	5
VTR075	75 mm	1570				
VTR090	90 mm	1570				
VTR010	101 mm	4580				
VTR115	115 mm	4580				
VTR014	141 mm	10,673				
VTR018	182 mm	24,780				

* 4 and 5:1 ratios not available with VTR006-VTR090.

UltraTRUE™

Helical True planetary inline gearbox, flange mount design with anodized aluminum housing employing RediMount™ system. Stainless steel housing, gear-path hobbed into stainless steel housing.

Inline	Frame Size Metric	Max T Peak (lb-in)		All Sizes	Gear Ratios Available	Efficiency	Backlash (arc-min)
		1 Stage	2 Stage				
UT006	61 mm	890	1010	1 Stage	4, 5, 7, 10	95%	4
UT075	75 mm	1580	1813				
UT090	90 mm	1580	1813				
UT010	101 mm	4548	5327				
UT115	115 mm	4548	5327	2 Stage	16, 20, 25, 28, 35, 40, 50, 70, 100	90%	5
UT014	141 mm	10,480	12,500				
UT018	182 mm	24,010	29,200				
UT022	220 mm	41,096	48,890				

UltraTRUE™

Helical True planetary right angle gearbox, flange mount design with anodized aluminum housing employing RediMount™ system. Stainless steel housing, gear-path hobbed into stainless steel housing.

Right Angle	Frame Size Metric	Max T Peak (lb-in)		All Sizes	Gear Ratios Available	Efficiency	Backlash (arc-min)
		1 Stage	2 Stage				
UTR006	61 mm	456	975	1 Stage	1, 2, 3, 4, 5	98%	4
UTR075	75 mm	1410	1740				
UTR090	90 mm	1410	1740				
UTR010	101 mm	2856	5085	2 Stage	8, 10, 12, 14, 15, 16, 20, 25, 28, 30, 35, 40, 50	93%	5
UTR115	115 mm	2856	5085				
UTR014	141 mm	6270	11,860				
UTR018	182 mm	16,914	27,530				

Note 1: Torque capacity is maximum of frame size stage design, not all ratios have the same rated torque capacity.
Note 2: Torque capacity is the maximum allowable momentary torque for emergency stopping or heavy shock loading.
Note 3: Ratio 5P is designed using the compact PowerTrue face gearing technology.
Note 4: Ratio 5T is designed using a True planetary gear stage for increased torque capacity.
Note 5: For complete gearbox model nomenclature, refer to page 214.

CE ISO RoHS

Linear Actuation & Positioning Systems

Kollmorgen offers a comprehensive range of linear actuator products including electric cylinders, rodless actuators, and precision tables to meet a wide range of application requirements. For actuator products not included in this catalog go to www.kollmorgen.com for information about other Kollmorgen linear positioning products.

	Model	Product Family	General Information
	Electric Cylinders[1]	EC1 EC2 EC3 EC4 EC5 N2	• Highest Force (Thrust) • Clean, Hydraulic Replacement • Compact Cross Section • Extends into Work Area
	Rodless Actuators (screw drive)	R2A R3 R4	• High Force (Thrust) • High Repeatability • Long Travel • Load Carrying Capability
	Rodless Actuators (belt drive)	R2A R3 R4	• Very High Speed • Quiet Operation • Long Travel • Load Carrying Capability
	Precision Tables	DS4 DS6	• High Accuracy & Repeatability • Low Maintenance, Long Life • High Moment Loads

Electric Cylinders (EC)

Primarily designed to apply a force through an extendable rod, electric cylinders are a clean and efficient replacement for hydraulic actuators and pneumatic cylinders, and an alternative to many types of linear transmissions. A wide variety of mounting and coupling alternatives significantly increases their problem solving potential.

Rodless Actuators

Long travel, quiet operation, and high moment loading differentiates rodless actuators from other mechanical transmissions.

Precision Tables

Positioning tables are used when accurate and repeatable motion is critical (1 part per 10,000 or better). These tables offer a wide variety of single and multi-axis configurations, open and closed frame tables, ball or lead screw driven, and overhung and constant support for Kollmorgen geometry configurations.

Model	Max Speed [3] In/s (mm/s)	Max Thrust [2, 3] Lb (N)	Repeatability [4, 5] In (mm)	Max Payload Lb (kg)	Max Travel In (mm)
Electric Cylinders[1]	52.5 (1330)	5620 (25,000)	to 0.0005 (0.013)	Note 1	59.1 (1500)
Rodless Actuators (screw drive)	39 (1000)	700 (3110)	to 0.0005 (0.013)	300 (136)	108 (2743)
Rodless Actuators (belt drive)	118 (3000)	300 (1330)	to 0.004 (0.10)	300 (136)	108 (2743)
Precision Tables	32.5 (825)	440 (1960)	3 microns (commercial grade) / 1.3 microns (precision grade)	794 (360)	79 (2000)

Notes:
1. Electric cylinders are designed primarily for thrust application where loads are supported externally.
2. Thrust ratings are based on mechanical limits rather than motor limits unless indicated otherwise.
3. Max speed and max thrust ratings are not necessarily available simultaneously
4. Repeatability is dependent on feedback resolution, load, friction, and drive gain settings.
5. Repeatability is unidirectional unless otherwise specified

Electric Cylinders N2 / EC Series

Electric cylinders are thrust-producing devices that are best suited for applications requiring high axial force with the moment and side loads already properly supported.

Kollmorgen has combined the broad product offering of the N2 and EC Series electric cylinders with the industry-leading AKM servo motors and AKD servo drives. The N2 and EC Series of electric cylinders offer a wide range of available thrusts in standard units from 600 lb (N2) to 5620 lb (EC5) across 5 electric cylinder frame sizes.

- Speeds up to 52 in/sec are available and integrated geared options provide the ability to increase thrust capacity for lower speed applications, leveraging the speed capacity of servo systems.
- Multiple servo motor options are available for the product line ranging from NEMA 23 size to NEMA 42 size servos. The combination with the AKM servo motor enables the use of various feedback devices including sine-encoder and the low-cost but high-performance Smart Feedback Device (SFD) when used with the AKD servo drive.
- Windings and voltage operation are not differentiated in MOTIONEERING®. All systems are offered at all voltages (240, 400, 480).
- The AKM servo motor comes mounted on the electric cylinder as specified by the electric cylinder part number. This eliminates time to match the motor to the electric cylinder and eliminates potential mechanical incompatibility.

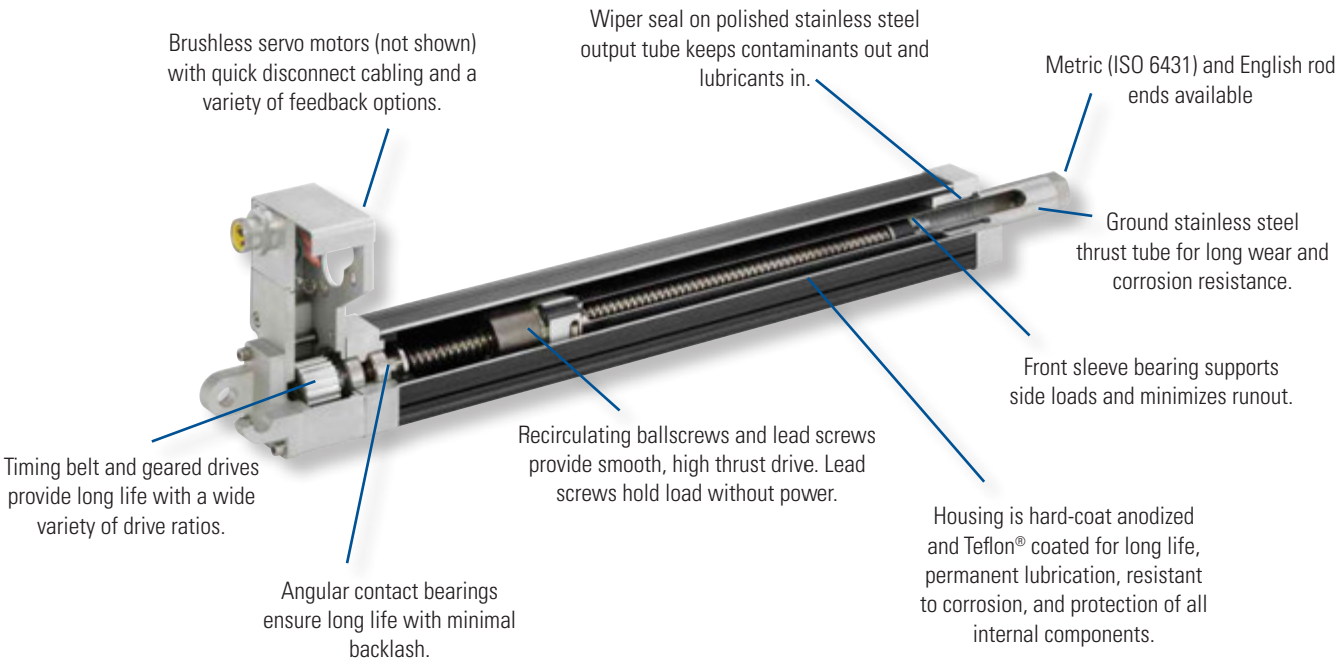
EC Servo Linear Actuators

- Designed for performance
- Highest quality precision rolled ballscrews and lead screws – for quiet, long-life operation
- Brushless Servo motor and Stepper motor options available
- Sealed for IP54 protection. IP65 option available.
- Thrust up to 25000 N [5620 lb]
- Speed up to 1.3 m/s [52.5 in/s]
- Metric design (ISO 6431)
- Available in 5 power ranges – EC1, 2, 3, 4 & 5

N2 Servo Linear Actuators

- Smallest Package Size
- Time-Proven Design
- Improved Durability Over Previous Designs
- Thrust up to 2670 N [600 lb]
- Speed up to 0.76 m/s [30 in/sec]
- English dimensions (to NFPA standards)
- Brushless Servo with encoder, resolver or SFD feedback
- Stepper motors also available

Typical Construction (EC2 cut-away shown)



Kollmorgen offers electric cylinder drive mechanisms designed around either lead screws or ballscrews. Ballscrews, being the more efficient of the two, utilize ballnuts riding on recirculating ball bearings resulting in higher speeds, loads and cycle rates. However, the more efficient design of ballscrew technology lends it to being backdriven when power is removed if precautions are not taken (e.g., electric brakes or counter loading).

Lead screws are capable of holding the load in position when power is removed, but are less efficient in operation.

Kollmorgen's guide system prevents rotation of the ball / lead nut, thus eliminating any torque loading to machine linkage.

Electric Cylinders Are Preferred When:

- Positioning an externally guided and supported load.
- Moving a load that pivots.
- There is a high concentration of airborne contaminants (rodless actuators are inherently less well protected).
- Replacing a hydraulic or pneumatic cylinder with an electro-mechanical solution.

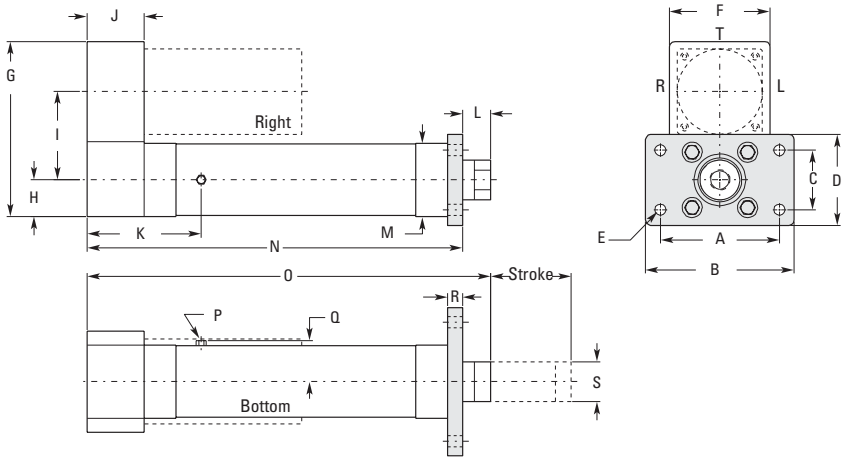
Specification Overview

Series	N2		EC1	EC2		EC3		EC4	EC5
Std. Maximum Stroke Length [in (mm)]	* 22.5 (571.5)		7.87 (200)	29.53 (750)		39.37 (1000)		59.06 (1500)	59.06 (1500)
Type of Screw	Lead	Ball	Ball	Lead	Ball	Lead	Ball	Ball	Ball
Lead	0.2 in, 0.5 in	0.2 in, 0.5 in	3 mm	4 mm	16, 5 mm	4 mm	16, 10, 5 mm	25, 10 mm	32, 10 mm
Nom. Lead Screw Diameter	0.625 in	0.625 in	10 mm	16 mm	16 mm	20 mm	20 mm	25 mm	32 mm
Backlash [in (mm)]	0.016 (0.40)	0.015 (0.38)	0.015 (0.38)	0.016 (0.40)	0.010 (0.25)	0.016 (0.40)	0.010 (0.25)	0.12 (0.30)	0.12 (0.30)
Dimension Std.	English NFPA Std.		Metric ISO6431 Std.						
Bore size			30 mm	50 mm		63 mm		80 mm	100 mm
Brushless Servo Motor	AKM23		AKM1x	AKM23		AKM23, AKM42, AKM52		AKM42, AKM52	AKM42, AKM52
Stepper Motor	T22		CTP12	T22, T31		T22, T31		T31, T32, T41	T31,T32,T41
Max. Thrust [lb (N)]	600 (2670)		150 (667)	810 (3600)		1620 (7200)		2700 (12,000)	5620 (25,000)
Max. Velocity [in/sec (m/s)]	12 (0.3)	30 (0.76)	13 (0.33)	9.2 (0.23)	50 (1.27)	8.0 (0.20)	50 (1.28)	52.5 (1.33)	52.5 (1.33)
Max. Rated Duty Cycle (load, speed dependent) [%]	50	100	100	50	100	50	100	100	100
Limit Switches	Optional								
Std. Operating Temperature Range [C (F)]	0 to 60 (32 to 140)		-30 to 70 (-22 to 158)						
Moisture/ Contaminants	Humid, but Not Direct Contact		IP54 Std. IP65 Opt.						

*Note: Requires dual rod-end bearing option for length over 12"

Electric Cylinders N2 / EC Series

Electric Cylinder EC Series General Outline Drawing



MF1 Front Flange
Parallel

Flange dimensions in accordance with ISO 6431 for:	
Type	Bore Size
EC1	30 mm
EC2	50 mm
EC3	63 mm
EC4	80 mm
EC5	100 mm

	A mm (in)	B mm (in)	C mm (in)	D mm (in)	E mm (in)	F mm (in)	G mm (in)	H mm (in)	I mm (in)	J mm (in)	K mm (in)
EC1	60.0 (2.36)	74.0 (2.91)	28.0 (1.10)	40.0 (1.57)	6.60 (0.26)	48.0 (1.89)	82.6 (3.25)	19.0 (0.75)	41.8 (1.65)	31.3 (1.23)	-
EC2	90.0 (3.54)	114.3 (4.50)	45.0 (1.77)	63.5 (2.50)	9.0 (0.35)	79.8 (3.14)	144.0 (5.7)	28.4 (1.12)	74.7 (2.94)	41.7 (1.64)	88.6 (3.49)
EC3	100.0 (3.94)	127.0 (5.00)	50.0 (1.97)	69.1 (2.72)	9.0 (0.35)	95.5 (3.76)	169.7 (6.7)	34.8 (1.37)	*87.6/89.7 (*3.45/3.53)	49.3 (1.94)	94.2 (3.71)
EC4 (-MF1E)	127.0 (5.00)	152.4 (6.00)	69.9 (2.75)	96.3 (3.79)	13.5 (0.53)	127.0 (5.00)	221.0 (8.7)	46.1 (1.81)	111.1 (4.37)	71.9 (2.83)	150.9 (5.94)
EC5	150.0 (5.91)	186.9 (7.36)	75.0 (2.95)	114.3 (4.50)	14.2 (0.56)	127.0 (5.00)	221.0 (8.7)	46.1 (1.81)	111.1 (4.37)	71.9 (2.83)	150.9 (5.94)

	L mm (in)	M mm (in)	N Cyl Length mm (in)	O Retract length mm (in)	P Breather port Hex type	P Breather port Hex mm (in)	Q mm (in)	R mm (in)	S mm (in)
EC1	10.2 (0.40)	38.1 (1.50)	113.8 + S (4.48 + S)	124.0 + S (4.88 + S)	-	-	-	10.0 (0.39)	22.2 (0.88)
EC2	25.0 (0.98)	56.9 (2.24)	218.5 + S (8.6 + S)	243.4 + S (9.58 + S)	1/8 NPT	11.1 (0.44)	34.8 (1.37)	9.5 (0.37)	28.0 (1.10)
EC3	25.0 (0.98)	69.6 (2.74)	246.3 + S (9.7 + S)	271.1 + S (10.67 + S)	1/8 NPT	11.1 (0.44)	41.1 (1.62)	12.7 (0.50)	35.0 (1.38)
EC4 (-MF1E)	41.4 (1.63)	92.2 (3.63)	365.8 + S (14.4 + S)	406.9 + S (16.02 + S)	1/4 NPT	14.0 (0.55)	52.8 (2.08)	12.7 (0.50)	50.0 (1.97)
EC5	35.0 (1.38)	92.2 (3.63)	365.8 + S (14.4 + S)	406.9 + S (16.02 + S)	1/4 NPT	14.0 (0.55)	52.8 (2.08)	19.1 (0.75)	50.0 (1.97)

240 Vac Performance Data

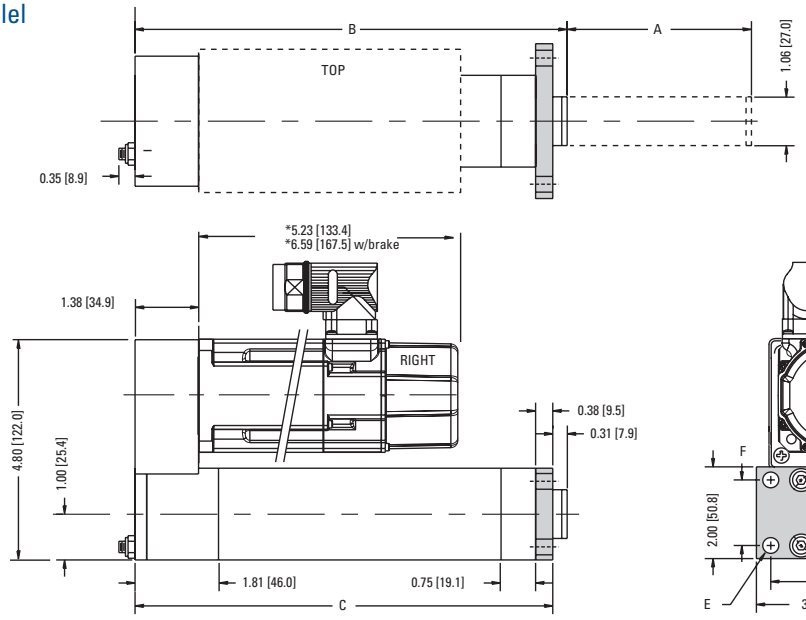
Sys	#	Electric Cylinder - AKM Servo motor	AKD Servo Drive	Cont. Thrust @ Speed (lb @ in/sec)		Peak Thrust @ Speed (lb @ in/sec)		Max Thrust (lb)	Max System Speed (in/sec)	**Max Stroke for Max Speed (mm)
EC1	1	EC1-AKM11B-■■■-10-03B *	AKD-X00306	50	13.0	75	13.0	75	13.0	200
	2	EC1-AKM11B-■■■-20-03B	AKD-X00306	100	6.0	125	6.0	125	6.0	200
	3	EC1-AKM11B-■■■-40-03B	AKD-X00306	150	3.0	150	3.0	150	3.0	200
	4	EC1-AKM13C-■■■-10-03B*	AKD-X00306	75	11.5	75	13.0	75	13.0	200
	5	EC1-AKM13C-■■■-20-03B	AKD-X00306	125	5.9	125	6.0	126	6.0	200

Note 1: Refer to the Kollmorgen Electric Cylinder Catalog catalog, or contact customer support for matching cables.
Note 2: For complete AKD, EC, and N2 Series model nomenclature, refer to pages 192, 215 and 216, respectively.
* In-line type with 1-to-1 gear ratio (-10L) provide 10% additional thrust (not to exceed the max thrust).
** Based on critical speed of screw specification.

Electric Cylinder N2 Series General Outline Drawing

MF1 Front Rectangular Flange Mount

Parallel



	English Option MF1 (inches)	Metric Option MF1M (mm)
D	2.75	72*
E	0.34	9*
F	1.43	36*

* Meets ISO 40mm bore standard

A	Standard Stroke Lengths Available						
inch	2.0	4.0	6.0	8.0	12.0	18.0	24.0
mm	50.8	101.6	152.4	203.2	304.8	457.2	609.6

* AKM23 with motor mounted connectors.

B	Retract Length	C	Mounting length
inch	5.37 + S	inch	5.06 + S
mm	136.4 + S	mm	128.5 + S

S = stroke

240 Vac Performance Data

Sys	#	Electric Cylinder - AKM Servo motor	AKD Servo Drive	Cont. Thrust @ Speed (lb @ in/sec)		Peak Thrust @ Speed (lb @ in/sec)		Max Thrust (lb)	Max System Speed (in/sec)	**Max Stroke for Max Speed (mm)
N2	1	N2-AKM23D-■■■-10-5B *	AKD-X00306	190	12.0	600	11.5	600	12.0	18.0
	2	N2-AKM23D-■■■-15-5B	AKD-X00306	287	8.0	600	8.0	600	8.0	18.0
	3	N2-AKM23D-■■■-20-5B	AKD-X00306	382	6.0	600	6.0	600	6.0	18.0
	4	N2-AKM23D-■■■-25-5B	AKD-X00306	370	4.8	600	4.8	600	4.8	18.0
	5	N2-AKM23D-■■■-120-5B	AKD-X00306	600	1.0	600	1.0	600	1.0	18.0
	6	N2-AKM23D-■■■-10-2B *	AKD-X00306	75	30.0	275	24.5	280	30.0	18.0
	7	N2-AKM23D-■■■-15-2B	AKD-X00306	115	20.0	412	16.4	421	20.0	18.0
	8	N2-AKM23D-■■■-20-2B	AKD-X00306	152	15.0	545	12.3	545	15.0	18.0
	9	N2-AKM23D-■■■-25-2B	AKD-X00306	146	12.0	534	9.8	545	12.0	18.0
	10	N2-AKM23D-■■■-120-2B	AKD-X00306	600	2.5	600	2.5	600	2.5	18.0
	11	N2-AKM23D-■■■-10-5A	AKD-X00306	86	12.0	305	9.8	312	12.0	18.0
	12	N2-AKM23D-■■■-15-5A	AKD-X00306	128	8.0	458	6.5	467	8.0	18.0
	13	N2-AKM23D-■■■-20-5A	AKD-X00306	169	6.0	600	4.9	600	6.0	18.0
	14	N2-AKM23D-■■■-25-5A	AKD-X00306	165	4.8	593	3.9	600	4.8	18.0
	15	N2-AKM23D-■■■-120-5A	AKD-X00306	600	1.0	600	1.0	600	1.0	18.0

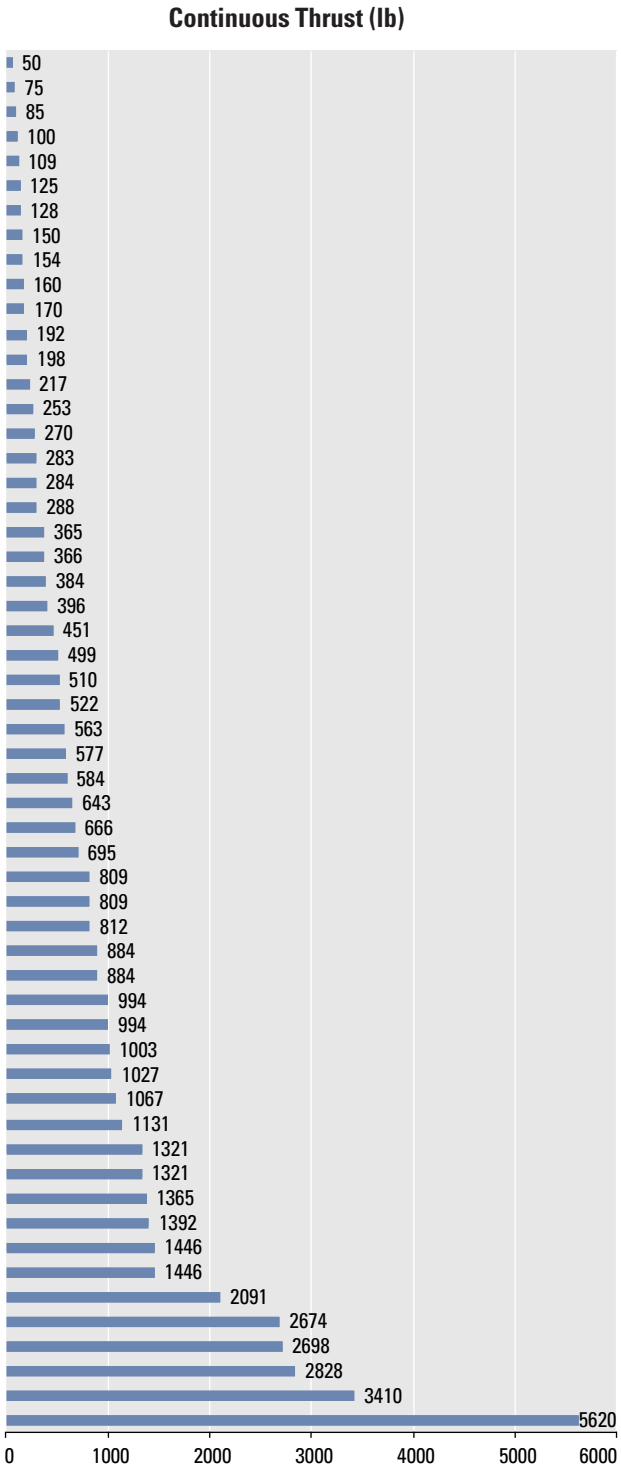
Note 1: Refer to the Kollmorgen Electric Cylinder Catalog, or contact customer support for matching cables.
Note 2: For complete AKD, EC, and N2 Series model nomenclature, refer to pages 192, 215 and 216, respectively.
* In-line type with 1-to-1 gear ratio (-10L) provide 10% additional thrust (not to exceed the max thrust).
** Based on critical speed of screw specification.

Electric Cylinders N2 / EC Series

Low Speed Servo Performance

System	AKD Cont Amps	Cont Thrust @ Speed		Peak Thrust @ Speed		Max Thrust
		lb	in/s	lb	in/s	lb
EC1-AKM11B-xxx-10-03M	3 A	50	13.0	75	13.0	75
EC1-AKM13C-xxx-10-03M	3 A	75	13.0	75	13.0	75
N2-AKM23D-xxx-10-5A	3 A	85	12.0	260	12.0	312
EC1-AKM11B-xxx-20-03M	3 A	100	6.0	125	6.0	125
EC2-AKM23D-xxx-10-04A	3 A	109	9.2	337	9.2	396
EC1-AKM13C-xxx-20-03M	3 A	125	6.0	125	6.0	125
N2-AKM23D-xxx-15-5A	3 A	128	8.0	392	8.0	467
EC1-AKM11B-xxx-40-03M	3 A	150	3.0	150	3.0	150
N2-AKM23D-xxx-20-2B	3 A	154	15.0	468	15.0	561
EC2-AKM23D-xxx-15-04A	3 A	160	6.2	499	6.2	582
N2-AKM23D-xxx-20-5A	3 A	170	6.0	517	6.0	600
N2-AKM23D-xxx-10-5B	3 A	192	12.0	585	12.0	600
EC3-AKM23D-xxx-10-05B	3 A	198	10.2	708	9.4	712
EC2-AKM23D-xxx-20-04A	3 A	217	4.6	455	4.6	790
EC3-AKM23D-xxx-50-16B	3 A	253	6.2	885	6.2	909
EC2-AKM23D-xxx-15-05B	3 A	270	13.2	809	8.0	809
EC3-AKM23D-xxx-15-05B	3 A	283	10.2	1060	6.3	1070
EC5-AKM42G-xxx-10-10B	6 A	284	15.2	1503	15.2	1005
N2-AKM23D-xxx-15-5B	3 A	288	8.0	600	8.0	600
EC3-AKM23D-xxx-20-05B	3 A	365	9.5	1372	5.0	1469
EC2-AKM23D-xxx-20-05B	3 A	366	9.7	770	8.0	809
N2-AKM23D-xxx-20-5B	3 A	384	6.0	600	6.0	600
EC5-AKM42G-xxx-15-10B	6 A	396	15.2	1503	9.4	1508
EC5-AKM42G-xxx-50-32B	6 A	451	6.6	1530	6.6	1530
EC4-AKM42G-xxx-20-10B	6 A	499	14.0	2005	7.1	2005
EC5-AKM42G-xxx-20-10B	6 A	510	13.2	2005	7.1	2010
EC2-AKM23D-xxx-50-04A	3 A	522	1.8	809	1.8	809
EC3-AKM23D-xxx-70-10B	3 A	563	2.81	1620	2.81	1620
EC4-AKM42G-xxx-50-25B	6 A	577	5.1	1959	5.1	1959
EC2-AKM23D-xxx-100-16B	3 A	584	3.67	809	3.67	809
EC5-AKM52H-xxx-10-10B	6 A	643	14.5	1137	13.0	1974
EC4-AKM52H-xxx-10-10B	6 A	666	14.0	1137	13.0	1974
EC3-AKM42G-xxx-50-16B	6 A	695	6.25	1620	6.25	1620
EC2-AKM23D-xxx-100-04A	3 A	809	0.91	809	0.91	809
EC2-AKM23D-xxx-50-05B	3 A	809	2.3	809	2.3	809
EC3-AKM23D-xxx-50-05B	3 A	812	1.9	1619	1.9	1619
EC5-AKM42G-xxx-100-32B	6 A	884	3.3	2997	3.3	3000
EC5-AKM52L-xxx-15-10B	12 A	884	15.0	1891	15.0	2695
EC4-AKM52H-xxx-15-10B	6 A	994	9.5	2067	8.0	2698
EC5-AKM52H-xxx-15-10B	6 A	994	9.5	2067	8.0	2962
EC4-AKM52L-xxx-20-10B	12 A	1003	14.4	1907	13.5	2698
EC5-AKM52L-xxx-20-10B	12 A	1027	14.0	1966	13.0	3501
EC5-AKM52H-xxx-50-32B	6 A	1067	6.5	1851	6.5	1851
EC4-AKM42G-xxx-100-25B	6 A	1131	2.6	2698	2.6	2698
EC4-AKM52H-xxx-20-10B	6 A	1321	7.2	2187	6.6	2698
EC5-AKM52H-xxx-20-10B	6 A	1321	7.2	2193	6.5	3501
EC4-AKM52H-xxx-50-25B	6 A	1365	5.1	2365	5.1	2365
EC4-AKM52L-xxx-50-25B	12 A	1392	5.1	2369	5.1	2369
EC4-AKM42G-xxx-50-10B	6 A	1446	2.0	2698	2.0	2698
EC5-AKM42G-xxx-50-10B	6 A	1446	2.0	4898	2.0	4898
EC5-AKM52H-xxx-100-32B	6 A	2091	3.3	3624	3.3	3624
EC4-AKM52H-xxx-100-25B	6 A	2674	2.6	2698	2.6	2698
EC4-AKM42G-xxx-100-10B	6 A	2698	1.04	2698	1.04	2698
EC5-AKM42G-xxx-100-10B	6 A	2828	1.04	5620	1.04	5620
EC5-AKM52H-xxx-50-10B	6 A	3410	2.05	5620	2.05	5620
EC5-AKM52H-xxx-100-10B	6 A	5620	1.04	5620	1.04	5620

Ratings are based on the AKM servo motor and the matching AKD Drive.
Specifications are based on 230 Vac, 3 phase voltage supply.

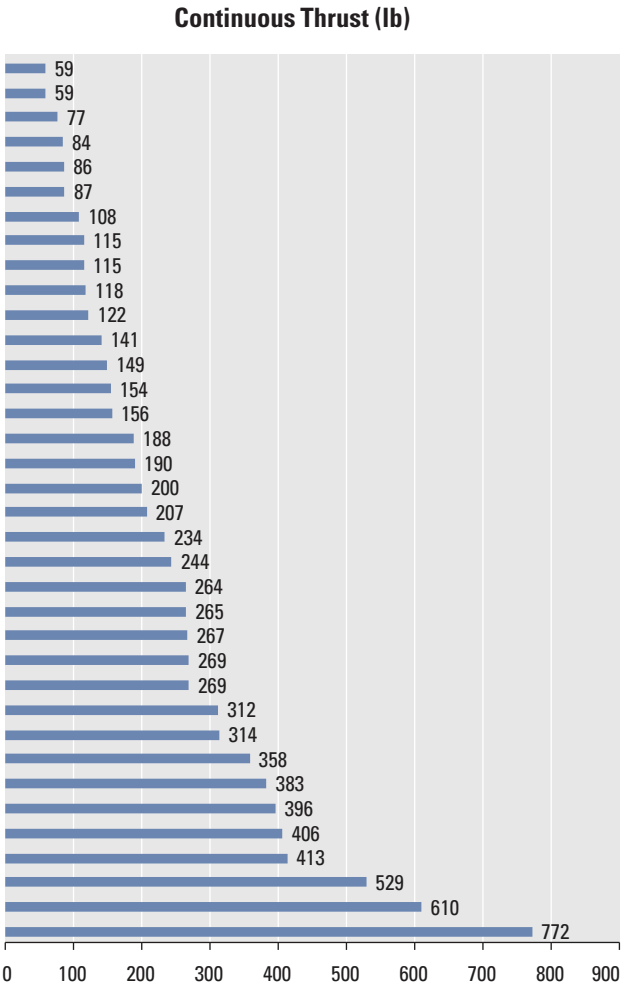


Plotted value is continuous thrust (lb), refer to chart for the associated rated speed value.

High Speed Servo Performance

System	AKD Cont Amps	Cont Thrust @ Speed		Peak Thrust @ Speed		Max Thrust
		lb	in/s	lb	in/s	lb
EC2-AKM23D-xxx-10-16B	3 A	59	50.0	221	30.0	222
EC3-AKM23D-xxx-10-16B	3 A	59	50.0	221	30.0	222
N2-AKM23D-xxx-10-2B	3 A	77	30.0	233	30.0	280
EC2-AKM23D-xxx-15-16B	3 A	84	42.0	293	23.0	327
EC3-AKM23D-xxx-15-16B	3 A	86	41.0	332	20.0	334
EC5-AKM42G-xxx-10-32B	6 A	87	52.5	313	45.0	313
EC4-AKM42G-xxx-10-25B	6 A	108	52.0	400	35.0	402
EC2-AKM23D-xxx-20-16B	3 A	115	31.0	223	26.0	445
N2-AKM23D-xxx-15-2B	3 A	115	20.0	350	20.0	420
EC3-AKM23D-xxx-20-16B	3 A	118	30.0	457	12.5	459
EC5-AKM42G-xxx-15-32B	6 A	122	52.5	470	30.0	470
EC3-AKM23D-xxx-15-10B	3 A	141	21.0	520	13.0	534
EC4-AKM42G-xxx-15-25B	6 A	149	47.0	595	24.0	603
EC3-AKM42G-xxx-10-16B	6 A	154	45.2	598	24.0	628
EC5-AKM42G-xxx-20-32B	6 A	156	45.0	626	22.5	628
EC2-AKM23D-xxx-10-05B	3 A	188	16.0	385	16.0	712
EC3-AKM23D-xxx-20-10B	3 A	190	18.0	686	10.0	735
EC4-AKM42G-xxx-20-25B	6 A	200	35.0	802	17.5	804
EC5-AKM52H-xxx-10-32B	6 A	207	46.0	351	42.0	617
EC3-AKM42G-xxx-15-16B	6 A	234	30.0	495	25.0	888
EC4-AKM52L-xxx-10-25B	12 A	244	52.5	422	52.5	719
EC4-AKM52H-xxx-10-25B	6 A	264	36.0	441	33.0	790
EC5-AKM52L-xxx-15-32B	12 A	265	52.0	584	52.0	842
EC4-AKM52L-xxx-15-25B	12 A	267	48.5	699	43.0	1078
EC3-AKM42G-xxx-10-10B	6 A	269	20.9	958	15.0	1010
EC4-AKM42G-xxx-10-10B	6 A	269	21.0	1002	14.2	1005
EC5-AKM52H-xxx-15-32B	6 A	312	30.0	626	26.0	925
EC5-AKM52L-xxx-20-32B	12 A	314	46.0	614	42.0	1094
EC3-AKM42G-xxx-15-10B	6 A	358	18.9	820	15.0	1420
EC4-AKM42G-xxx-15-10B	6 A	383	17.5	1501	9.5	1508
EC4-AKM52H-xxx-15-25B	6 A	396	24.0	827	20.0	1185
EC4-AKM52L-xxx-20-25B	12 A	406	35.5	785	33.0	1400
EC5-AKM52H-xxx-20-32B	6 A	413	23.0	684	21.0	1094
EC4-AKM52H-xxx-20-25B	6 A	529	18.0	879	16.0	1400
EC4-AKM52L-xxx-10-10B	12 A	610	21.0	1055	21.0	1797
EC4-AKM52L-xxx-15-10B	12 A	772	18.6	1825	17.0	2695

Ratings are based on the AKM servo motor and the matching AKD Drive.
Specifications are based on 230 Vac, 3 phase voltage supply.



Plotted value is continuous thrust (lb), refer to chart for the associated rated speed value.

Rodless Actuators R-Series

The name rodless actuator comes from this technology's close relationship to electric cylinders, sharing many of the same components. Rather than having a rod, rodless actuators incorporate a carriage supported by linear bearings. Where electric cylinders are designed to extend in and out of the work area delivering force or thrust, rodless actuators are designed to be load carrying mechanisms (up to 300 lb) incorporating ballscrews, leadscrews, or belt drive transmissions with optional integrated gearboxes.

Rodless actuators also share many of the fundamental design characteristics of precision positioning tables. Precision tables are designed to carry larger payloads and deliver superior repeatability and accuracy. Rodless actuators offer longer travels and higher speeds at a lower price. Screw driven rodless actuators are also thrust-producing devices that are best for axial force applications where the space is limited and a payload must also be supported or carried. As individual components, rodless actuators are not well suited for moment loading; however, they can be effectively combined into complete Cartesian systems for some multi-axis applications. For higher speed, lower thrust applications, rodless actuators can be repeatability-driven with a timing belt instead of a screw.

Kollmorgen has combined the broad product offering of the R-Series rodless actuators with the industry-leading AKM servo motors and AKD servo drives. The R-Series of rodless actuators offer a wide range of available thrusts in standard units with three basic frame sizes (R2A, R3, R4).

Rodless actuators offer longer travels (up to 108") and higher speeds (belt drives up to a maximum speed of 120 in/sec). Integrated geared options provide the ability to increase thrust capacity for lower speed applications leveraging the speed capacity of servo systems.

Multiple servo motor options are available for the product line, ranging from NEMA 23 size to NEMA 42 size servos. The combination with the AKM servo motor enables the use of various feedback devices including sine-encoder and the low-cost but high-performance Smart Feedback Device (SFD) when used with the AKD servo drive.

The AKM servo motor comes mounted on the rodless actuators as specified by the rodless actuator part number. This eliminates time to match the motor to the electric cylinder and eliminates potential mechanical incompatibility.

The operation of rodless actuators is similar to the electric cylinders described earlier. However, instead of an extending rod, a rodless unit features a moving carriage supported by linear bearings within an extruded aluminum chassis. This gives the rodless actuator the ability to guide and support a load, as well as position it.

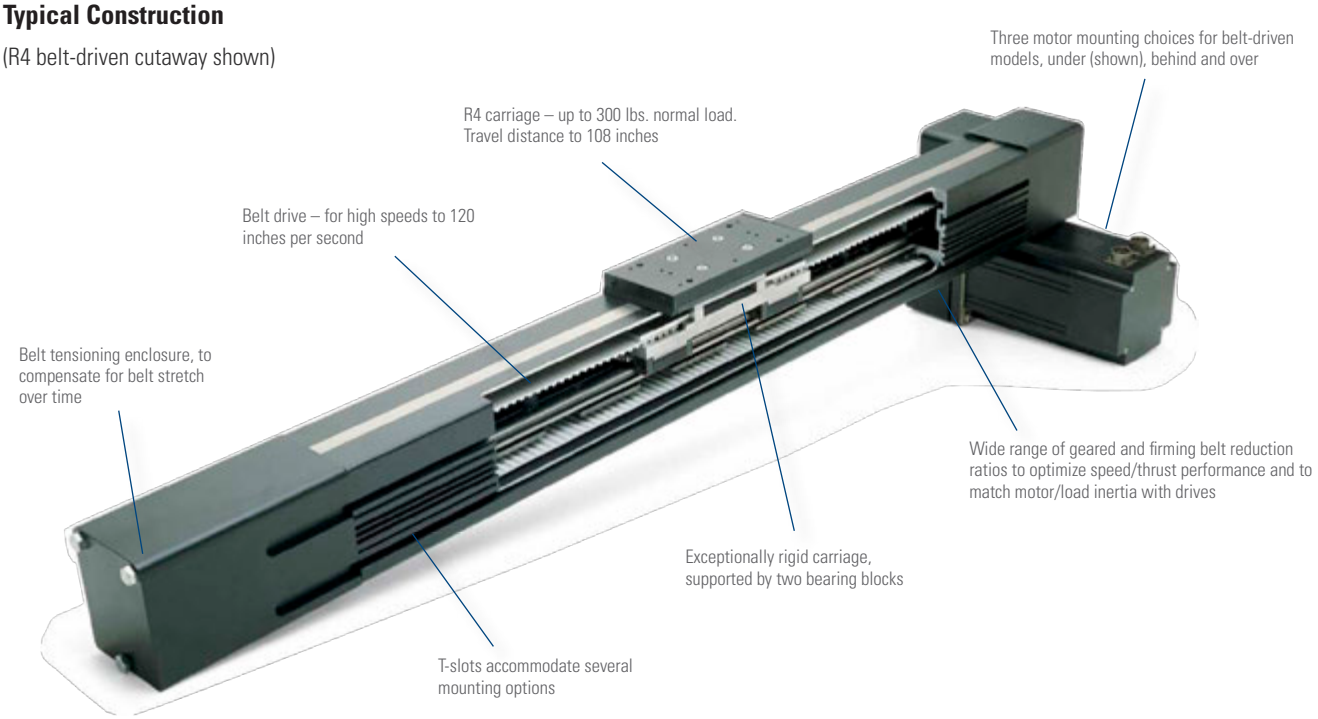
Kollmorgen rodless actuators are designed for outstanding overall performance, value, flexibility and reliability in industrial applications.

Rodless Actuators Are Preferred When:

- A low cost system is needed to both position and guide a load
- It is desired to eliminate external guides and ways
- The shortest overall work envelope (extended length equals retracted length) is required
- Multiple units will be combined into Cartesian systems
- There is a need for a compact cross-sectional linear positioning system

Typical Construction

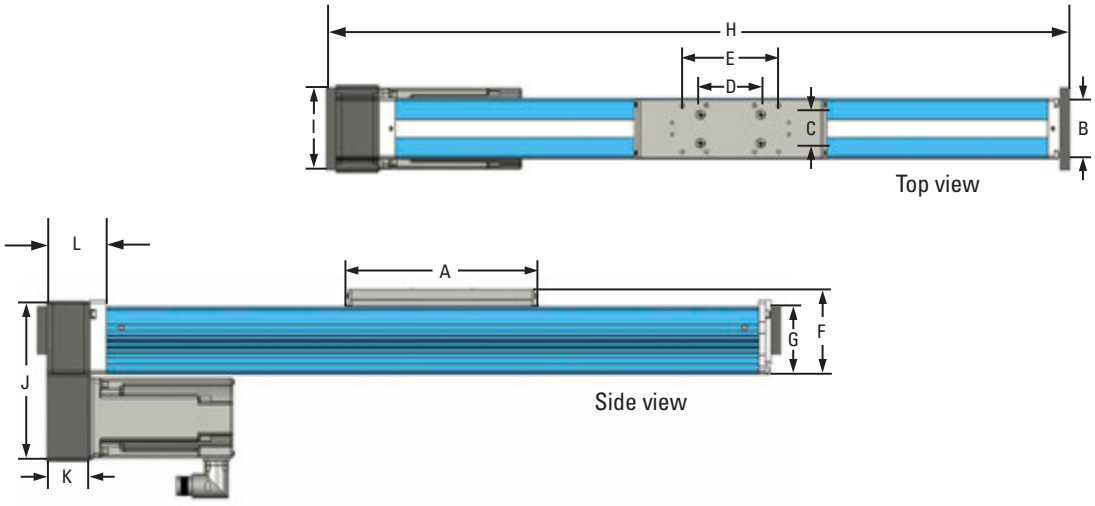
(R4 belt-driven cutaway shown)



Rodless Actuators R-Series

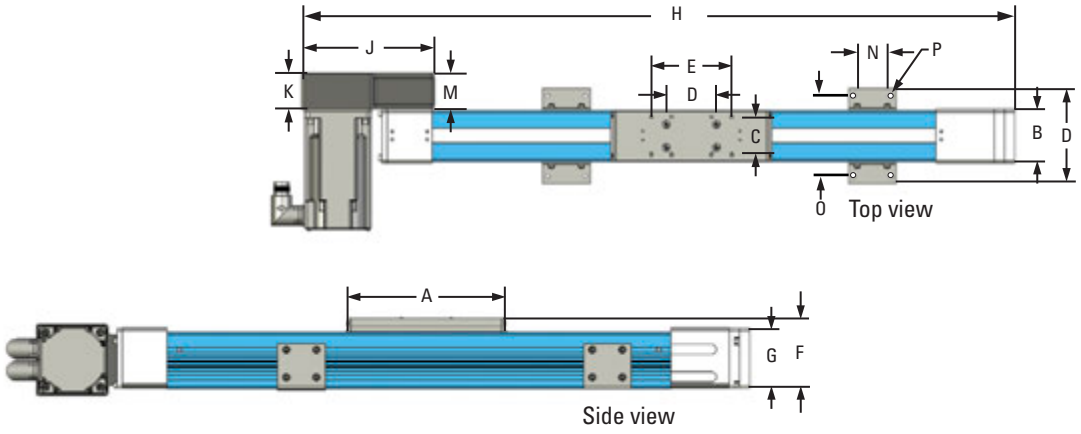
R3 Screw Drive

R3 screw drive with AKM42, parallel below motor orientation and flange mounting shown.



R3 Belt Drive

R3 belt drive with AKM42, behind left motor orientation and angle bracket feet shown.



Carriage Mounting Features

	Metric Version (mm)	English Version (inch)
RA2	8 x M5 x 0.8 x 8.0 deep	8 x 10-32 UNF x 0.31 deep
R3	8 x M5 x 0.8 x 9.6 deep	8 x 10-32 UNF x 0.38 deep
R4	4 x M6 x 1 x 12 deep	4 x 1/4-20 x 0.50 deep

Dimension Data

	A	B	C	D	E
	mm (in)	mm (in)	mm (in)	mm (in)	mm (in)
RA2	210 (8.25)	50.8 (2.00)	31.8 (1.25)	50.8 (2.00)	101.6 (4.00)
R3	197 (7.76)	63.5 (2.50)	47.6 (1.88)	50.8 (2.00)	101.6 (4.00)
R4	197 (7.76)	92.2 (3.63)	63.5 (2.50)	NA	127.0 (5.00)

	F	G	H (Screw)	H (Belt)
	mm (in)	mm (in)	mm (in)	mm (in)
RA2	71.9 (2.83)	50.8 (2.00)	"S" + 345.3 (13.59)	"S" + 378.3 (14.89)
R3	88.8 (3.50)	71.5 (2.82)	"S" + 326.4 (12.85)	"S" + 522.0 (20.55)
R4	71.9 (2.83)	108.0 (4.25)	"S" + 411.8 (16.21)	"S" + 578.6 (22.78)

S = stroke

	I	J	K	L
	mm (in)	mm (in)	mm (in)	mm (in)
RA2	72.1 (2.84)	123.2 (4.85)	43.0 (1.69)	90.7 (3.57)
R3	91.4 (3.60)	168.9 (6.65)	45.5 (1.79)	88.1 (3.47)
R4	127.0 (5.00)	220.7 (8.69)	71.9 (2.83)	147.8 (5.82)

	M	N	O	P
	mm (in)	mm (in)	mm (in)	mm (in)
RA2	50.1 (1.97)	NA	88.8 (3.50)	8.7 (0.34) thru
R3	45.5 (1.79)	47.6 (1.88)	101.6 (4.00)	5.5 (0.22) thru
R4	71.9 (2.83)	63.5 (2.50)	127.0 (5.00)	7.0 (0.28) thru

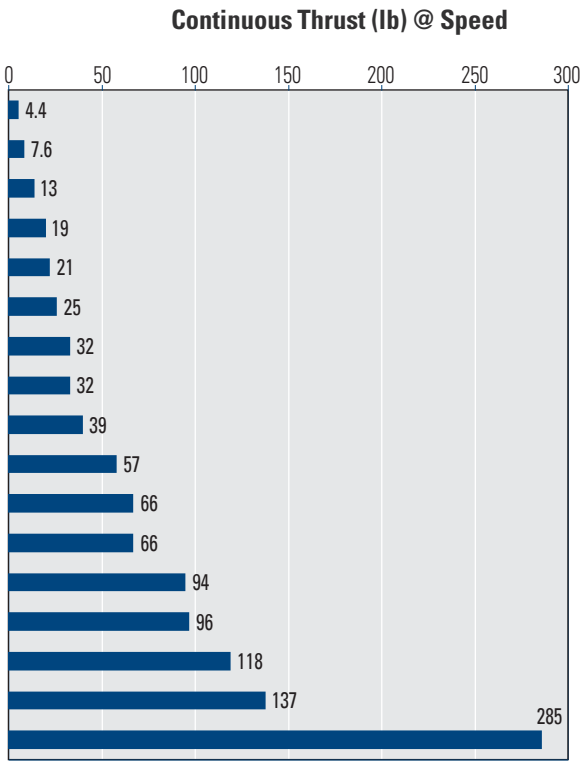
Rodless Actuators R-Series

General Specifications

Series	R2A			R3			R4	
Std max stroke length (in)	72			108			108	
Cross section (in)	2 x 2			2.5 x 2.8			3.6 x 4.25	
Guide type	Roller Guides			Profile Rail			Profile Rail	
Drive type	Ballscrew	Lead Screw	Belt	Ballscrew	Lead Screw	Belt	Ballscrew	Belt
Screw leads (in/rev)	0.5, 0.2	0.2, 0.125	n/a	0.5, 0.2	0.2, 0.125	n/a	1, 0.25	n/a
Nominal screw diameter (in)	0.625	0.625	n/a	0.625	0.625	n/a	1	n/a
Brushless servo motor	AKM23, NEMA 23			AKM23, NEMA 23, AKM42, NEMA 34			n/a	
Max thrust (lb)	100		72	300		200	700	300
Max velocity (in/sec)	30		80	30		120	40	120
Max carriage load								
Normal (lb)	50			100			300	
Roll moment (lb-in)	50			300			600	
Pitch moment (lb-in)	100			500			1000	
Repeatability (in)	+/-0.001		+/-0.010	+/-0.001		+/-0.010	+/-0.001	+/-0.010
Max duty cycle (speed, load dependent)	100%	60%	100%	100%	60%	100%	100%	100%
Limit sensors	Optional							
Std operating temperature range	-20 deg F to 140 deg F (-28 deg C to 60 deg C)							
Moisture/contamination	IP 44 rated: Splash-proof, protected against ingress of solid particles greater than 0.040 [1 mm] diameter.*							

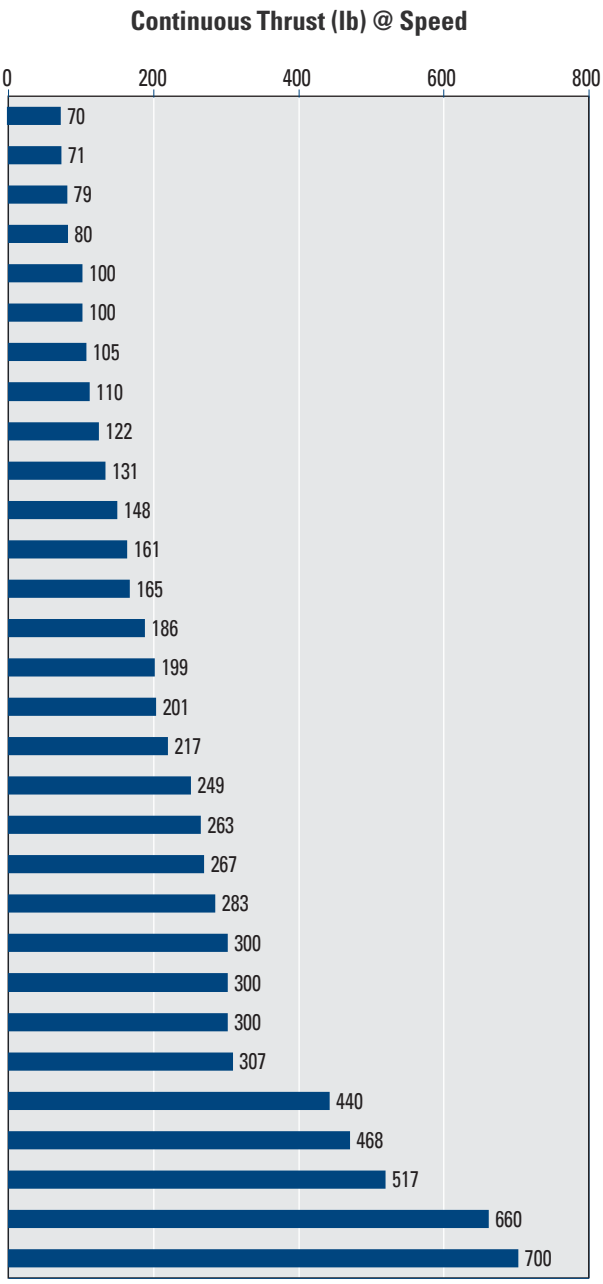
Belt Based Systems

Belt Based System	AKD® Cont. Amps	Cont. Thrust @ speed		Peak Thrust @ speed		Max Thrust
		lb	in/s	lb	in/s	lb
R3-AKM23D-xxx-15T	3 A	4.4	118	29	118	29
R3-AKM23D-xxx-20T	3 A	7.6	118	41	118	41
R2A-AKM23D-xxx-15T	3 A	13	80	64	80	64
R2A-AKM23D-xxx-20T	3 A	19	80	78	80	87
R3-AKM23D-xxx-50T	3 A	21	71	76	71	92
R4-AKM42G-xxx-20T	6 A	25	118	100	118	100
R3-AKM23D-xxx-70T	3 A	32	51	108	51	131
R3-AKM42G-xxx-20T	6 A	32	118	117	118	126
R4-AKM42G-xxx-30T	6 A	39	100	139	100	153
R4-AKM42G-xxx-50T	6 A	57	59	200	59	219
R3-AKM42G-xxx-50T	6 A	66	72	138	72	200
R4-AKM52H-xxx-20T	6 A	66	118	200	90	202
R3-AKM42G-xxx-70T	6 A	94	51	197	51	200
R4-AKM52H-xxx-30T	6 A	96	92	300	60	300
R4-AKM42G-xxx-100T	6 A	118	30	300	30	300
R4-AKM52H-xxx-50T	6 A	137	54	300	44	300
R4-AKM52H-xxx-100T	6 A	285	27	300	27	300



Screw Based Systems

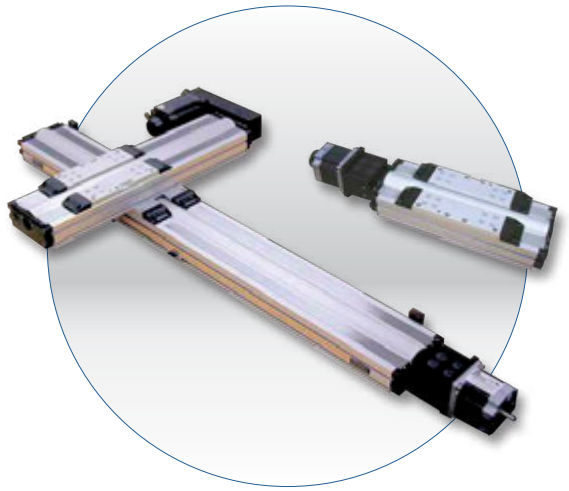
Screw Based System	AKD® Cont. Amps	Cont. Thrust @ speed		Peak Thrust @ speed		Max Thrust
		lb	in/s	lb	in/s	lb
R2A-AKM23D-xxx-102B-yy-P	3 A	70	30	100	30	100
R3-AKM23D-xxx-102B-yy-P	3 A	71	30	269	25	275
R2A-AKM23D-xxx-105A-yy-P	3 A	79	12	100	12	100
R3-AKM23D-xxx-105A-yy-P	3 A	80	12	255	12	300
R2A-AKM23D-xxx-152B-yy-P	3 A	100	20	100	20	100
R2A-AKM23D-xxx-155A-yy-P	3 A	100	8.0	100	8	100
R4-AKM42G-xxx-101B-yy-P	6 A	105	40	356	40	390
R3-AKM23D-xxx-152B-yy-P	3 A	110	20	300	20	300
R3-AKM23D-xxx-155A-yy-P	3 A	122	8.0	300	8.0	300
R3-AKM23D-xxx-108A-yy-P	3 A	131	7.5	300	7.5	300
R3-AKM23D-xxx-202B-yy-P	3 A	148	15	300	15	300
R4-AKM42G-xxx-151B-yy-P	6 A	161	27	540	27	588
R3-AKM23D-xxx-205A-yy-P	3 A	165	6.0	300	6.0	300
R3-AKM23D-xxx-105B-yy-P	3 A	186	12	300	12	300
R3-AKM23D-xxx-158A-yy-P	3 A	199	5.0	300	5.0	300
R3-AKM42G-xxx-102B-yy-P	6 A	201	30	300	30	300
R4-AKM42G-xxx-201B-yy-P	6 A	217	20	700	20	700
R3-AKM42G-xxx-105A-yy-P	6 A	249	12	300	12	300
R4-AKM52H-xxx-101B-yy-P	6 A	263	37	263	37	700
R3-AKM23D-xxx-208A-yy-P	3 A	267	3.8	300	3.8	300
R3-AKM23D-xxx-155B-yy-P	3 A	283	8.0	300	8.0	300
R3-AKM23D-xxx-505A-yy-P	3 A	300	2.4	300	2.4	300
R3-AKM42G-xxx-152B-yy-P	6 A	300	20	300	20	300
R3-AKM42G-xxx-155A-yy-P	6 A	300	8.0	300	8.0	300
R4-AKM52H-xxx-151B-yy-P	6 A	307	25	307	25	700
R4-AKM42G-xxx-104B-yy-P	6 A	440	10	700	10	700
R4-AKM42G-xxx-501B-yy-P	6 A	468	7.8	700	7.8	700
R4-AKM52H-xxx-201B-yy-P	6 A	517	18	600	18	700
R4-AKM42G-xxx-154B-yy-P	6 A	660	6.7	700	6.7	700
R4-AKM52H-xxx-104B-yy-P	6 A	700	9.4	700	9.4	700



Precision Tables DS4 / DS6 Series

Precision positioning tables are best suited for applications where the accuracy and repeatability requirements are more important than axial thrust of the drive train. Precision positioning tables can also be used in less precise applications where adequate moment load support is necessary, and are ideal building blocks for complete multi-axis positioning systems.

The DS4 and DS6 are Kollmorgen's most versatile and modular line of positioning tables.



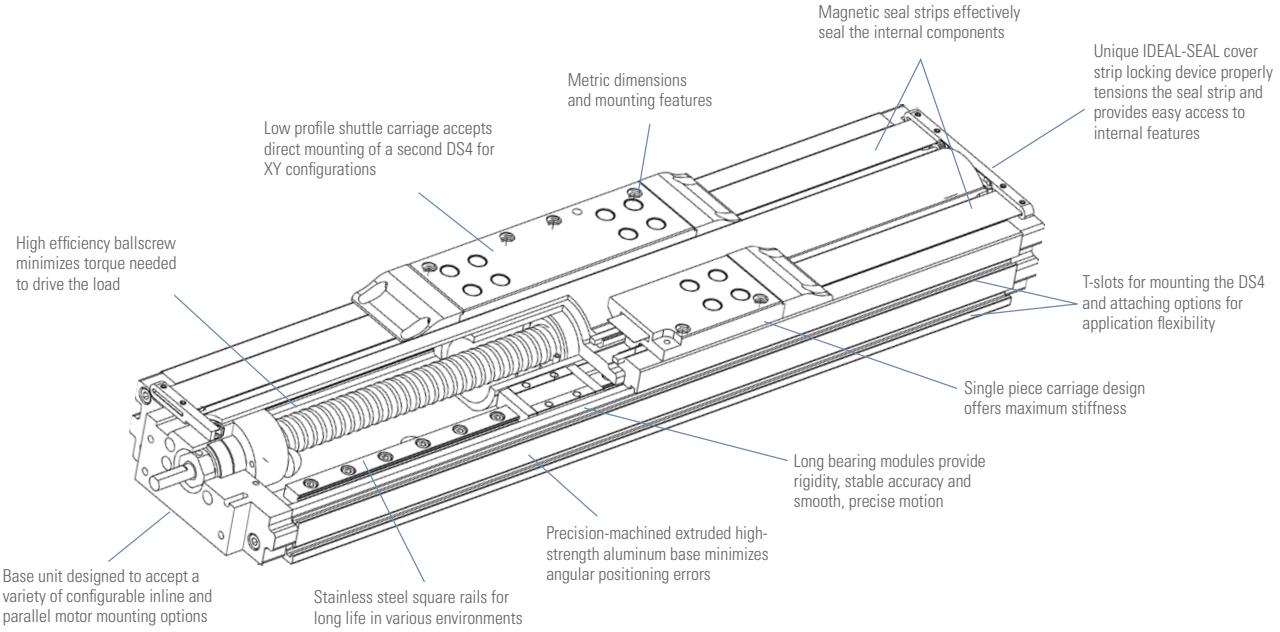
Combined with the AKD® Servo Drive and AKM® Servo Motors, DS4 and DS6 Systems Offer

- An optimized electromechanical solution suitable for demanding high precision positioning
- Performance and versatility in a compact package
- Outstanding industrial durability
- Tremendous configuration flexibility
- Industry-leading price vs. performance value

DS Series Design Features

Following are several features that make the DS Series the positioning table of choice for the most demanding applications:

- Travel lengths from 50 mm to 2 m cover a wide range of applications.
- Precision ballscrew drive, with 5 mm, 10 mm and 25 mm leads, offers high speed and efficiency, excellent repeatability and accuracy, and mechanical advantage.
- Proven magnetic stainless steel seal strip technology effectively seals the internal components of the DS Series, protecting the ballscrew and ways from contaminants. This feature also contains ballscrew and way lubrication within the DS Series.
- Easily configurable modular design and option set, including a variety of motor mounting orientations, motor sizes and type, ballscrew leads, coupling types and sizes, encoder feedback options, limit/home sensor types, and shaft brakes allow the DS Series to be customized to meet your specific requirements.



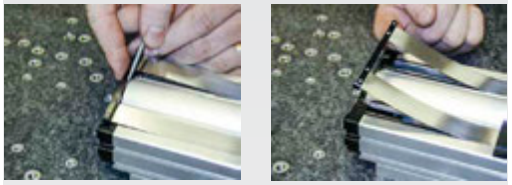
DS Series precision tables can be ordered in a variety of multi-axis configurations including XY, XZ, and XYZ or cartesian arrangements. Consult Kollmorgen applications engineering for standard and custom configurations.

A second option is to order standard multi-axis brackets and assemble the axes yourself.

All DS4 and DS6 tables will bolt directly together in a standard XY without modification.

Unique IDEAL-SEAL Magnetic Cover Strip Locking Device

- Entire length of lead screw and linear bearing system are protected, providing both operator safety and protection from contaminants.
- Seal strips are always properly tensioned, drastically decreasing wear that requires regular field repair.
- Allows easy access to interior of DS4 for mounting and maintenance.
- No small hardware or springs to lose, and no exposure to the sharp ends of the strips, which are problems for similar seal end-cap designs.



Seal Strips

Configurable Options

DS Series	
Servo motor options	AKM23D, AKM42G
Grades	Precision* (up to 600 mm), commercial
Motor orientations	In-line, parallel right/left/under
Couplings options** (inline configurations)	Bellows
Transmission ratio (parallel configurations)	1:1
Limit sensors	PNP (sinking) inductive proximity sensors, 5-30 Vdc
Home sensor	PNP (sinking) inductive proximity sensors, 5-30 Vdc
Shaft brake	Electromagnetic power of holding brake, 24 Vdc
Linear encoder options	1.0, 0.5 and 0.1 motion resolution, modular incremental type

* Additional lead time applies to precision grade. Contact customer support for details.
** Additional couplings available. Contact customer support for details.

Limit Sensor

Linear Encoder

Accessories

DS Series	
Toe clamps	Provide convenient external mounting to a base plate or to riser blocks
Narrow riser blocks	Raise unit for clearance of larger motor options, utilizing internal base mounting features on the side
Wide riser blocks	Allow rising of the unit, independent of base mounting features
Brackets and mounting plates	Facilitate multi-axis configurations
Cable sets	For connection to AKD and other drives

Toe Clamp

Precision Tables DS4 / DS6 Series

DS4 General Specifications

Travel (mm)	50	100	150	200	250	300	350	400	450	500	550	600
Overall height, less motor (mm)	47											
Width (mm)	95											
System length, Inline less motor (mm)	317	367	417	467	517	567	617	667	717	767	817	867
System length, parallel motor mounts (mm)	300	350	400	450	500	550	600	650	700	750	800	850
Positional accuracy (microns)												
Commercial grade	12	12	14	20	22	24	26	26	28	34	36	40
Precision grade	8	8	10	12	12	14	14	16	19	21	23	25
Straightness & flatness (microns)	6	6	9	12	12	14	18	21	23	23	25	25
Bi-directional repeatability, open loop												
Commercial grade (microns)	+/- 3											
Precision grade (microns)	+/- 1.3											
Load capacity, normal (kg) (max)	170											
Axial load capacity (kg)	90											
Acceleration (max) (m/sec^2)	20											
Moving mass (kg)	0.75											
Total mass (kg)	2.7	3	3.3	3.6	3.9	4.1	4.4	4.7	5	5.3	5.6	5.9
Ballscrew diameter (mm)	16											
Duty cycle (%)	100											
Ballscrew efficiency	90											
Max. breakaway torque (oz-in)	18											
Max. running torque (oz-in)	16											
Ballscrew lead available (mm)	5, 10											
Input inertia (10^{-5} kg-m^2)	1.17	1.24	1.67	1.93	2.18	2.43	2.68	2.93	3.19	3.44	3.69	3.94
Max. ballscrew speed (rev/sec)	80						60		55	50		

DS6 General Specifications

Travel (mm)	100	200	300	400	500	600	700	800	900	1000	1250	1500	1750	2000
Overall height (mm)	70													
Width (mm)	150													
System length, inline less motor (mm)	465	565	665	765	865	965	1065	1165	1265	1365	1615	1865	2115	2365
System length, parallel motor mounts (mm)	470	570	670	770	870	970	1070	1170	1270	1370	1620	1870	2120	2370
Positional accuracy (microns)														
Commercial grade	14	22	28	39	45	48	92	94	103	105	118	134	154	159
Precision grade	12	14	15	20	25	50	-	-	-	-	-	-	-	-
Straightness & flatness (microns)	10	14	17	23	30	33	40	46	50	55	76	95	115	135
Bi-directional repeatability, open loop														
Commercial grade (microns)	+/- 3						+/-5							
Precision grade (microns)	+/- 1.3						N/A							
Load capacity, normal (kg) (max)	630													
Axial load capacity (kg)														
Commercial grade	90						200							
Precision grade	90						N/A							
Acceleration (max) (m/sec^2)	20													
Moving mass (kg)	2.8													
Total mass (kg)	8.9	10.2	11.5	12.8	14.0	15.4	19.4	20.9	22.4	23.9	27.8	31.6	35.4	40.1
Ballscrew diameter (mm)	16						25							
Duty cycle (%)	100													
Ballscrew efficiency	90						80							
Max. breakaway torque (oz-in)	18						55							
Max. running torque (oz-in)	16						48							
Ballscrew lead available (mm)	5, 10						5, 10, 25							
Input inertia (10^{-5} kg-m^2)	3.8	4.4	5	5.5	6.1	6.7	37	40.4	43.9	47.3	56	64.5	73.2	81.9
Max. ballscrew speed (rev/sec)	80			60	50		60	50	40	35	24	16	13	11

*All performance specifications are based upon proper mounting procedures, with the DS table fully supported on a flat surface (flat within 0.008 mm/300 mm). Positional accuracy and repeatability specifications are for inline motor mount models only. Contact customer support for specifications of parallel mount configurations. Above specifications are measured 37.5 mm directly above the center of the carriage. Specifications are based upon operation at 20° C.

120 Vac Performance Data

	Sys #	Precision Table - AKM Servo Motor	AKD Servo Drive	Stroke Length Type	Cont. Thrust @ Speed (lb @ in/sec)		Peak Thrust @ Speed (lb @ in/sec)		Max Thrust (lb)	Max System Speed (in/sec)	Max Stroke for Max Speed (mm)
DS4	1	DS4-XXX-10G-AKM23D-■■■	AKD-X00306	≤ 600 mm	104	17.6	210	10.8	210	17.6	600
	2	DS4-XXX- 5G-AKM23D-■■■	AKD-X00306	≤ 600 mm	195	8.8	210	8.4	210	8.8	600
DS6	3	DS6-XXX-25G-AKM23D-■■■	AKD-X00306	≤ 600 mm	37	44.0	138	8.2	138	44.0	600
	4	DS6-XXX-10G-AKM23D-■■■	AKD-X00306	≤ 600 mm	104	17.6	210	12.4	210	17.6	600
	5	DS6-XXX- 5G-AKM23D-■■■	AKD-X00306	≤ 600 mm	195	8.8	210	8.6	210	8.8	600
DS6	6	DS6-XXX-25G-AKM23D-■■■	AKD-X00306	≥ 700 mm	41	44.0	138	8.2	154	44.0	800
	7	DS6-XXX-10G-AKM23D-■■■	AKD-X00306	≥ 700 mm	91	17.6	331	3.1	376	17.6	800
	8	DS6-XXX- 5G-AKM23D-■■■	AKD-X00306	≥ 700 mm	143	8.8	440	5.0	440	8.8	800

240 Vac Performance Data

	Sys #	Precision Table - AKM Servo Motor	AKD Servo Drive	Stroke Length Type	Cont. Thrust @ Speed (lb @ in/sec)		Peak Thrust @ Speed (lb @ in/sec)		Max Thrust (lb)	Max System Speed (in/sec)	Max Stroke for Max Speed (mm)
DS4	1	DS4-XXX-10G-AKM23D-■■■	AKD-X00306	≤ 600 mm	98	31.5	210	31.5	210	31.5	300
	2	DS4-XXX- 5G-AKM23D-■■■	AKD-X00306	≤ 600 mm	184	15.7	210	15.7	210	15.7	300
DS6	3	DS6-XXX-10G-AKM23D-■■■	AKD-X00306	≤ 600 mm	98	31.5	210	31.5	210	31.5	300
	4	DS6-XXX- 5G-AKM23D-■■■	AKD-X00306	≤ 600 mm	184	15.7	210	15.7	210	15.7	300
	5	DS6-XXX-25G-AKM23D-■■■	AKD-X00306	≥ 700 mm	40	59	154	47	154	59	700
	6	DS6-XXX-10G-AKM23D-■■■	AKD-X00306	≥ 700 mm	88	23.6	374	18	374	23.6	700
	7	DS6-XXX- 5G-AKM23D-■■■	AKD-X00306	≥ 700 mm	138	11.8	440	11.8	440	11.8	700
	8	DS6-XXX-10G-AKM42G-■■■	AKD-X00306	≤ 600 mm	210	28.4	210	28.4	210	28.4	300
	9	DS6-XXX- 5G-AKM42G-■■■	AKD-X00306	≤ 600 mm	210	14.5	210	14.5	210	14.5	300
	10	DS6-XXX-25G-AKM42G-■■■	AKD-X00306	≥ 700 mm	114	59	438	35.8	438	59	700
	11	DS6-XXX-10G-AKM42G-■■■	AKD-X00306	≥ 700 mm	272	23.6	440	23.6	440	23.6	700
	12	DS6-XXX- 5G-AKM42G-■■■	AKD-X00306	≥ 700 mm	440	11.8	440	11.8	440	11.8	700

Note 1: Performance based on in-line motor configuration.
Note 2: Contact customer support for matching cables.
Note 3: For complete AKD and DS4 / DS6 Series model nomenclature, refer to pages 192 and 218 respectively.

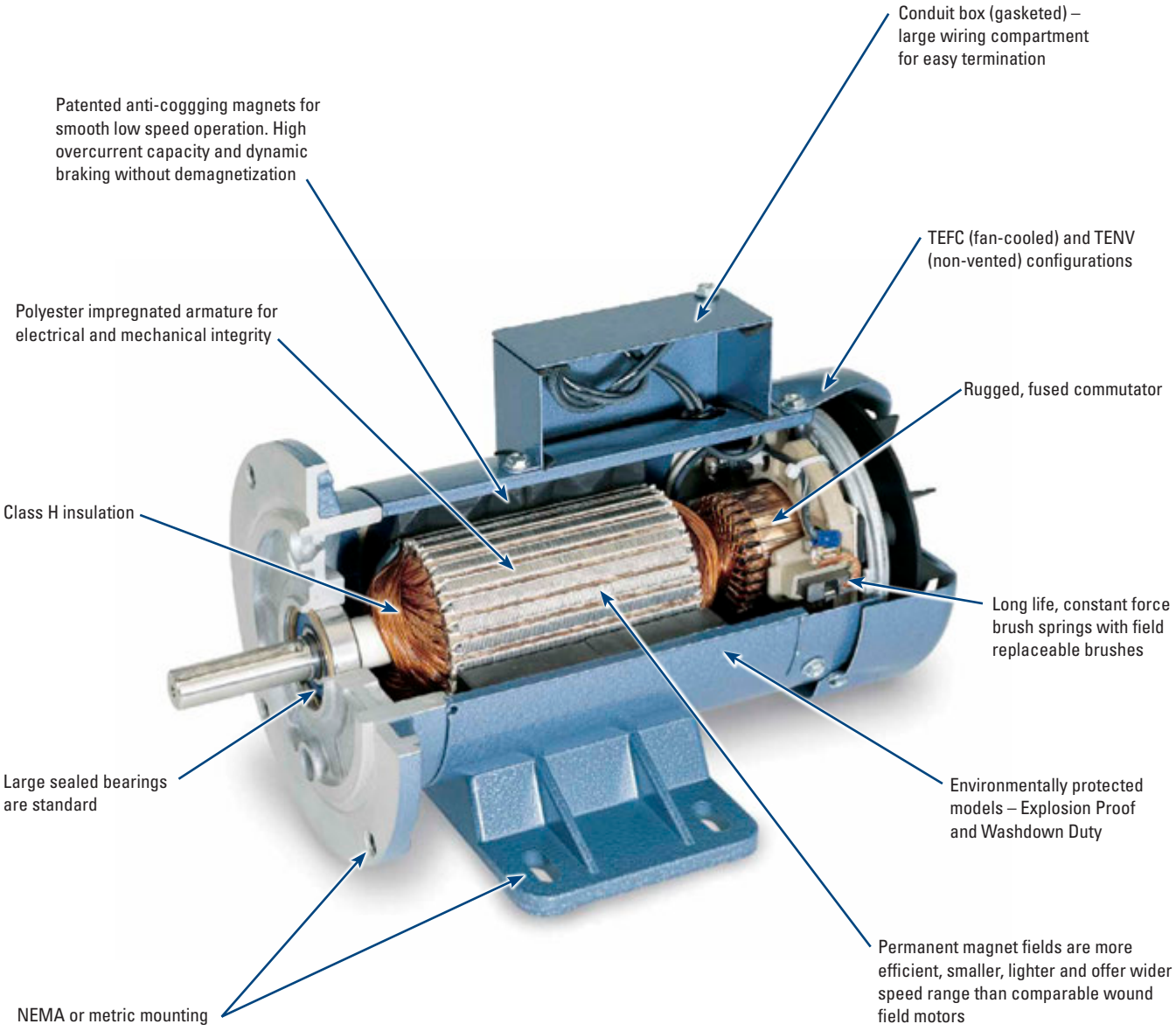
PMDC Permanent Magnet DC Motors

Why have design engineers depended on Kollmorgen permanent magnet DC motors for nearly 50 years? Value and Performance. Rugged, quality construction, backed by a 2 year warranty.

Plus, when you need something special, you know we've built thousands of custom-designed motors. Many more than we could ever show with these pages.

And if we don't have just what you need, we'll design a new one, even for a modest volume requirement.

Standard PMDC Motor Features



SR/SRF Series Continuous Duty Motors

General Specifications

SCR Rated NEMA Standards

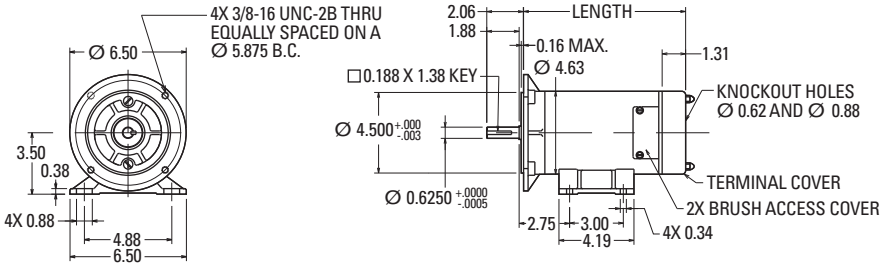
- NEMA C face with removable base – except the 180 V / 1.5 HP has a welded base
- Class H insulation
- UL Recognized (UL 1004, File E61960)
- CSA Certified (CSA Standard C22.2 No. 100, Class 421101, File LR43477)
- CE marked. Conforms to EN60034-1 and EN60034-5
- 1750 RPM

							Parameters										
	HP	Model Number	Product Code	NEMA	Enclosure	Continuous Current (A)	Continuous Torque (lb_f-in)	Peak Current (A)	Torque Constant (lb_f-in/A)	Resistance (Ω)	Inertia (lb_f-in)	Inductance (mH)	Configuration/Dimensions (facing page)	Length (in)	Weight (lbs)	Brush Replacement (order 2 per motor)
90 V	1/8	SR3616-8290-7-56BC-CU	FGS2430	56C	TENV	1.5	4.5	34.0	4.0	5.3	2.9	19.4	1	8.13	14	YP00565
	1/4	SR3624-8291-7-56BC-CU	FGS2431	56C	TENV	2.7	9.0	54.0	3.9	2.5	4.0	9.6	1	9.13	18	YP00565
	1/3	SR3632-8292-7-56BC-CU	FGS2432	56C	TENV	3.5	12.0	71.0	3.9	1.8	5.0	6.6	1	10.13	21	YP00565
	1/2	SR3642-4822-7-56BC-CU	FGS2434	56C	TENV	4.7	18.0	74.0	4.2	0.9	6.5	3.8	1	12.10	27	YP00565
	1/2	SRF3632-5227-84-5-56BC-CU	FGS2748	56C	TEFC	5.1	18.0	54.0	4.0	1.3	5.2	5.8	2	10.10	22	YP00565
	3/4	SRF3650-4823-84-5-56BC-CU	FGS2749	56C	TEFC	6.9	27.0	81.0	4.2	0.7	7.8	3.7	2	13.25	30	YP00565
	1.0	SRF3756-4996-84-5-56BC-CU	FGS2751	56C	TEFC	9.5	36.0	81.0	4.4	0.5	12.8	3.4	2	13.25	30	YP00565
180 V	1/4	SR3624-1032-7-56BC-CU	FGS2658	56C	TENV	1.4	9.0	28.0	7.4	9.6	4.0	42.8	1	9.13	18	YP00566
	1/2	SR3642-4982-7-56BC-CU	FGS2438	56C	TENV	2.6	18.0	40.0	7.6	3.3	6.3	16.2	1	12.13	27	YP00566
	1/2	SRF3632-5265-84-5-56BC-CU	FGS2735	56C	TEFC	2.4	18.0	27.0	8.1	5.3	5.2	29.5	2	10.10	21	YP00566
	3/4	SRF3736-4983-84-5-56BC-CU	FGS2750	56C	TEFC	3.2	27.0	26.0	8.8	3.6	8.9	28.8	2	11.25	23	YP00566
	1.0	SRF3752-4984-84-5-56BC-CU	FGS2752	56C	TEFC	4.6	36.0	41.0	8.2	1.8	12.0	15.6	2	13.25	29	YP00566
	1.5	SRF5348-4485-84-5-45BC-CU	FGS2753	145TC*	TEFC	7.8	54.0	62.0	7.9	1.2	26.2	13.5	3	16.00	64	YP00574
	2.0	SRF5360-4985-84-5-82BC-CU	FGS2754	145TC/182	TEFC	9.5	72.0	78.0	8.2	0.6	35.9	7.0	4	16.50	75	YP00559
	3.0	SRF5570-4986-84-5-82BC-CU	FGS2755	145TC/182	TEFC	14.0	108.0	78.0	9.3	0.6	40.1	7.2	5	19.75	87	YP00585

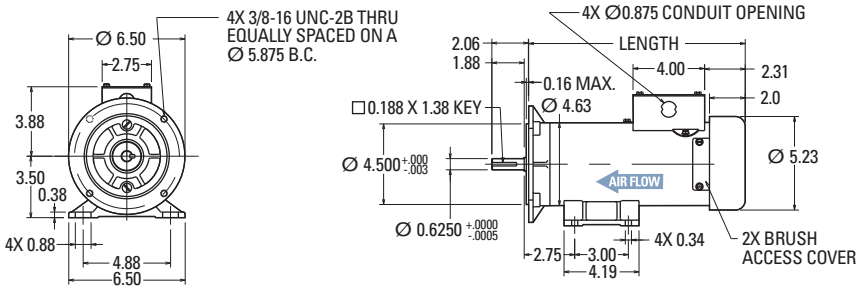
* Stamped steel, welded base, not removable

Configurations and Dimensions (inches)

1 – TENV



2 – TEFC



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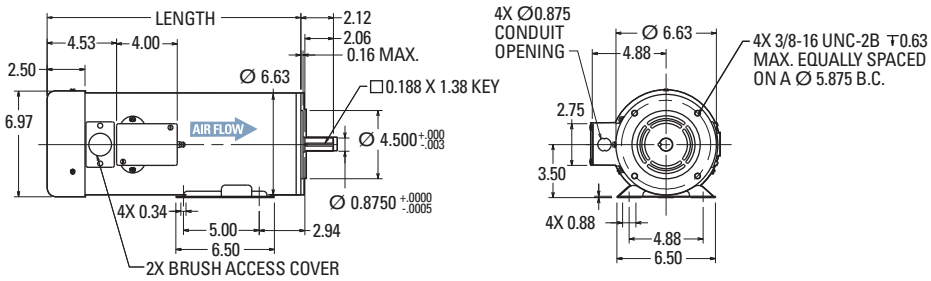

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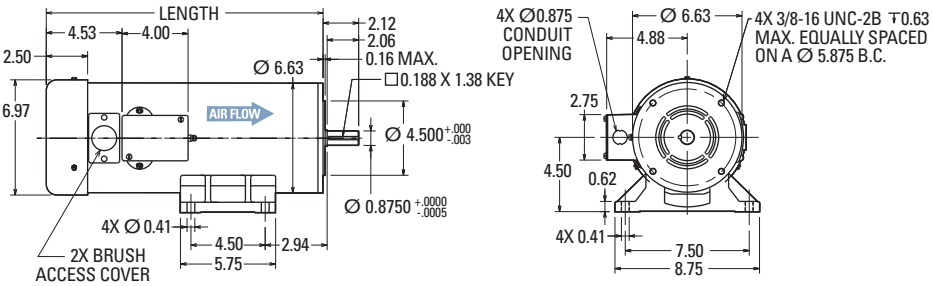
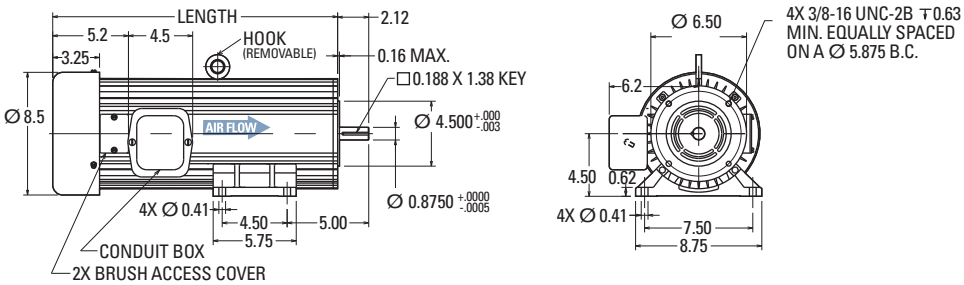


5 – TEFC



STF Series Washdown Motors

General Specifications

SCR Rated NEMA Standards – Washdown Duty

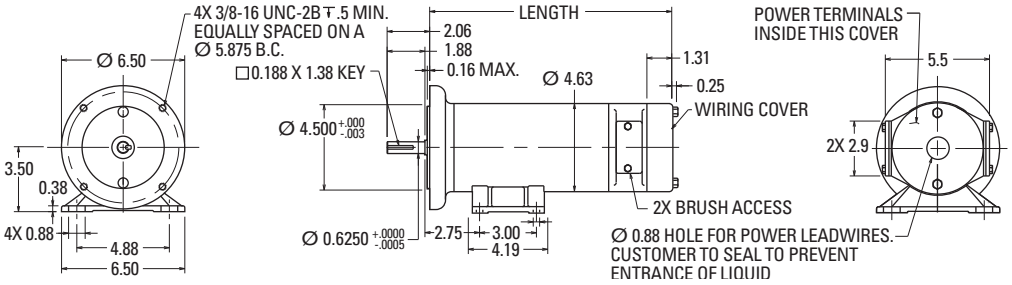
- NEMA C face with removable base – except the 1 and 1.5 HP motors have welded bases
- Class H insulation
- UL Recognized (UL 1004, File E61960)
- Complies with NEMA MG1-1.26.5 Waterproof designation and IP65
- Bakery Industry Sanitation Standards Committee (BISSC) certified per BISSC Standard 29 (Authorization No. 301)
- 1750 RPM

	HP	Model Number	Product Code	NEMA	Enclosure	Parameters: Continuous Current (A)	Continuous Torque (lb_f-in)	Peak Current (A)	Torque Constant (lb_f-in/A)	Resistance (Ω)	Inertia (lb_f-in)	Inductance (mH)	Configuration/Dimensions (facing page)	Length (in)	Weight (lbs)	Brush Replacement (order 2 per motor)
90 V	1/4	STF3624-4976-61-56BC	FGS2419	56C	TENV	2.9	9.0	54.0	3.89	2.51	4.0	9.61	1	11.20	22	YP00572
	1/2	STF3640-4977-61-56BC	FGS2420	56C	TENV	5.1	18.0	67.0	4.05	0.95	6.3	4.38	1	12.20	26	YP00572
	3/4	STF3758-5150-61-56BC	FGS2757	56C	TENV	7.3	27.0	126.0	4.05	0.72	8.7	3.50	2	15.20	41	YP00572
180 V	1/2	STF3648-5268-61-56BC	FGS2738	56C	TENV	2.4	18.0	37.0	8.30	3.59	6.4	19.60	1	11.80	27	YP00571
	1.0	STF5332-3748-61-56BC-CU	FGS2389	56C*	TENV	4.6	36.0	36.0	8.00	2.40	22.4	32.00	3	13.30	41	YP00574
	1.5	STF5356-3749-61-45BC-CU	FGS2390	145TC*	TENV	7.1	54.0	70.0	7.90	1.11	29.8	11.20	4	16.30	65	YP00574
	2.0	STF5372-3750-61-82BC-CU	FGS2342	145TC/182	TENV	9.3	72.0	93.0	7.90	0.77	39.3	6.80	5	18.30	84	YP00574

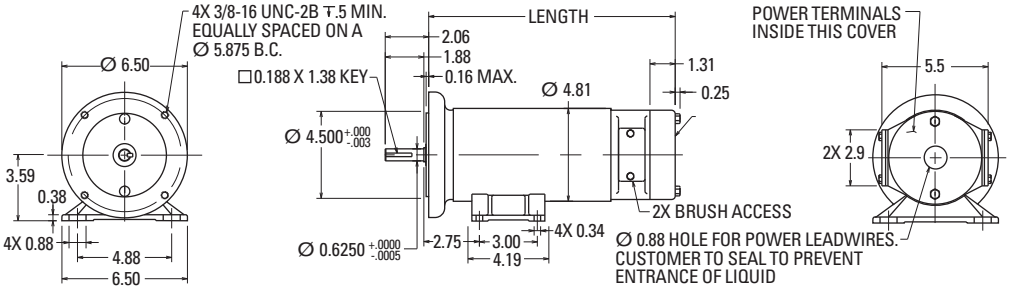
* Stamped steel, welded base, not removable

Configurations and Dimensions (inches)

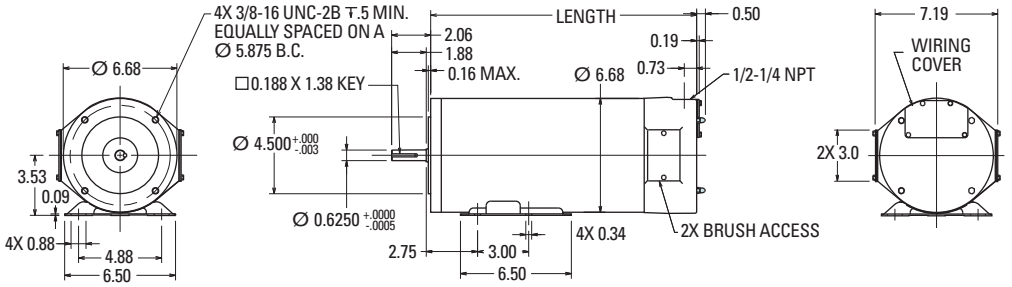
1 – TENV



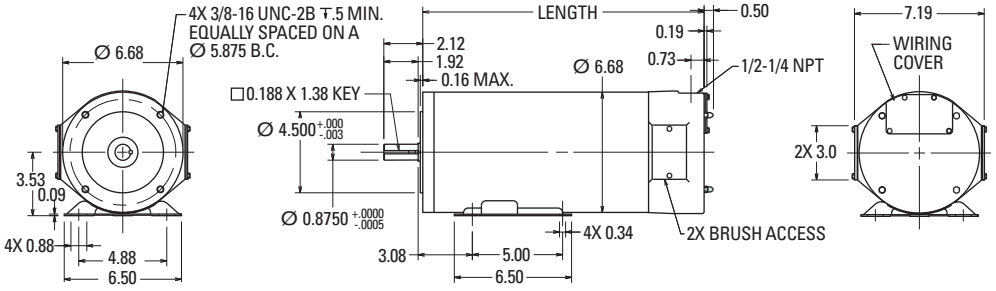
2 – TENV



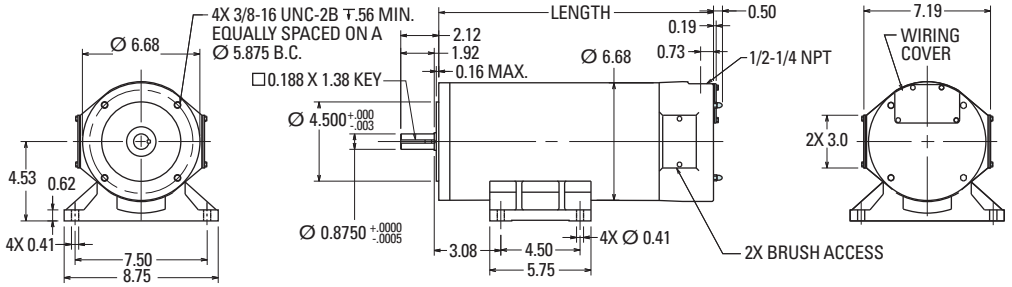
3 – TENV



4 – TENV



5 – TENV



EP Series Explosion Proof Motors

General Specifications

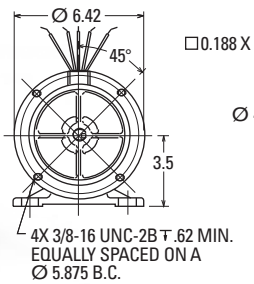
SCR Rated NEMA Standards – Explosion Proof

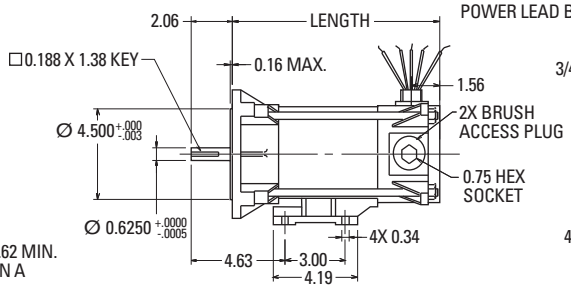
- NEMA C face with removable base
- Class H insulation
- UL Recognized (UL 674, File E56538), meets Division 1 & 2, Class 1 (Groups C & D), Class II (Groups F & G) and Class III
- CSA Listed Components per CSA Standard C22.2 No. 145, Class 428801 (File 213464).
- 1750 RPM

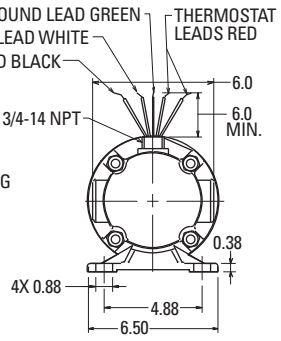
	HP	Model Number	Product Code	NEMA	Enclosure	Parameters: Continuous Current (A)	Continuous Torque (lb_f-in)	Peak Current (A)	Torque Constant (lb_f-in/A)	Resistance (Ω)	Inertia (lb_f-in)	Inductance (mH)	Configuration/Dimensions (facing page)	Length (in)	Weight (lbs)	Brush Replacement (order 2 per motor)
90 V	1/4	EP3624-1434-7-56BC-CU	FGE0212	56C	TENV	2.6	9.0	52.0	4.07	2.63	4.0	10.5	1	10.38	23	YP00565
	1/3	EP3632-1435-7-56BC-CU	FGE0242	56C	TENV	3.5	12.0	71.0	3.94	1.76	5.0	6.6	1	11.38	27	YP00565
	1/2	EP3640-1436-7-56BC-CU	FGE0213	56C	TENV	4.7	18.0	87.0	4.24	1.03	6.4	5.1	1	12.38	30	YP00565
	3/4	EP3758-5151-7-56BC-CU	FGE0248	56C	TENV	7.0	27.0	113.0	4.15	0.74	8.0	3.8	1	14.0	36	YP00565
180 V	1/4	EP3624-5269-7-56BC-CU	FGE0261	56C	TENV	1.3	9.0	26.0	8.10	10.50	4.0	51.80	1	10.38	23	YP00566
	1/2	EP3644-5214-7-56BC-CU	FGE0262	56C	TENV	2.3	18.0	34.0	8.10	4.00	6.7	24.20	1	12.38	30	YP00566
	3/4	EP3752-5215-7-56BC-CU	FGE0263	56C	TENV	3.3	27.0	38.0	8.10	3.10	11.4	17.40	1	14.38	34	YP00566
12 V	1/3	EP3620-1954-7-56BC-CU	FGE0243	56C	TENV	28.0	12.0	n/a	0.52	0.04	3.5	0.18	1	10.38	19	YP00583
24 V	1/3	EP3624-2757-7-56BC-CU	FGE0245	56C	TENV	13.4	12.0	n/a	1.02	0.16	4.0	0.66	1	10.38	24	YP00593
	3/4	EP3648-4952-7-56BC-CU	FGE0244	56C	TENV	28.2	27.0	n/a	1.02	0.06	7.1	0.22	1	13.38	33	YP00593

Configuration and Dimensions (inches)

1 – TENV







BA/BAF Series Low Voltage Motors

General Specifications

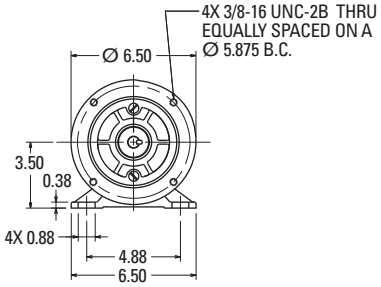
Low Voltage Rated NEMA Standards

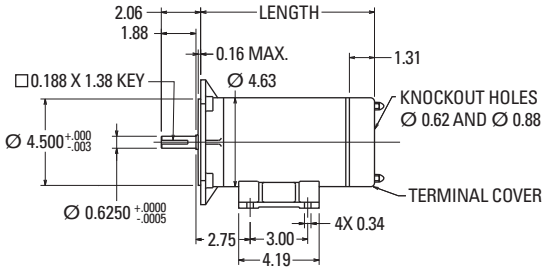
- NEMA C face with removable base
- Class H insulation
- UL Recognized (UL1004, File E61960)
- Designed for use with low voltage supplies (batteries).
- Highly efficient
- For constant speed, motors are operated directly from a battery with no motor control interface.
- For adjustable speeds, low voltage motor controls are readily available
- 1750 RPM

	HP	Model Number	Product Code	NEMA	Enclosure	Parameters: Continuous Current (A)	Continuous Torque (lb_f-in)	Peak Current (A)	Torque Constant (lb_f-in/A)	Resistance (Ω)	Inertia (lb_f-in)	Inductance (mH)	Configuration/Dimensions (facing page)	Length (in)	Weight (lbs)	Brush Replacement (order 2 per motor)
12 V	1/4	BA3614-4648-9-56BC	FGB2010	56C	TENV	21.1	9.0	n/a	0.51	0.07	2.9	0.27	1	8.13	15	YP00593
	1/3	BA3624-7005-9-56BC	FGB2002	56C	TENV	27.0	12.0	n/a	0.51	0.04	4.0	0.14	1	9.13	19	YP00602
	1/2	BA3638-4588-9-56BC	FGB2005	56C	TENV	39.8	18.0	n/a	0.49	0.02	5.5	0.07	1	11.13	25	YP00592
24 V	1/4	BA3618-7009-9-56BC	FGB1592	56C	TENV	10.3	9.0	n/a	1.04	0.14	3.2	0.57	1	9.13	18	YP00593
	1/3	BA3624-7024-9-56BC	FGB2285	56C	TENV	13.4	12.0	n/a	1.02	0.16	4.0	0.66	1	9.13	19	YP00593
	1/2	BA3628-7012-9-56BC	FGB1441	56C	TENV	19.5	18.0	n/a	1.01	0.10	4.4	0.38	1	10.13	21	YP00593
	3/4	BA3648-4650-9-56BC	FGB2006	56C	TENV	28.2	27.0	n/a	1.02	0.06	7.1	0.22	1	12.10	29	YP00592
	1.0	BAF3644-5081-56BC	FGB2335	56C	TEFC	38.4	36.0	n/a	1.00	0.05	6.6	0.21	2	12.25	28	YP00583

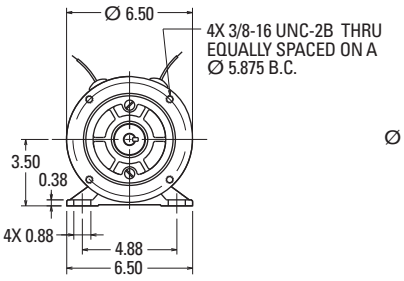
Configuration and Dimensions (inches)

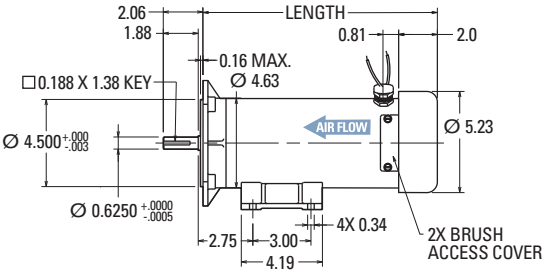
1 – TENV





2 – TEFC





Optimized Solutions

Applying Our Knowledge to Meet Your Motion Needs

Optimize the Package, Performance and Features

- We provide solutions that meet your needs, including the ability to get optimum performance for the smallest package size.
- Our products deliver superior quality, through-put, efficiency, and performance.

Reduce Waste and Costs

- We have thousands of proven designs upon which to build new solutions. Our application experience expedites the design cycle, which enables you to be fully operational sooner.
- Great value is delivered in the final product.

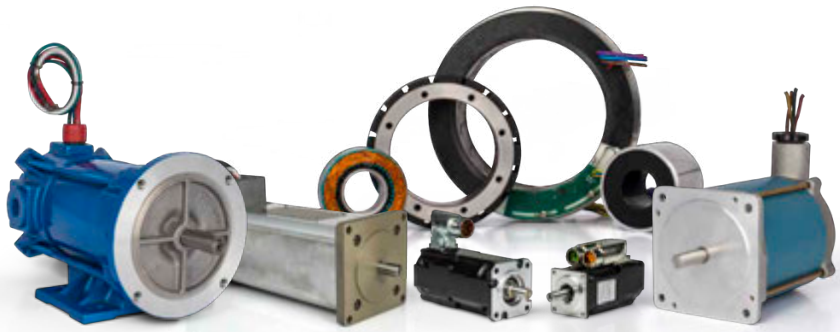
Meet the Most Challenging Requirements

- Designs are developed for manufacturability.
- Designing and manufacturing unique products are our core competency.
- We have the broadest capabilities in the industry.

Compete and Win

Kollmorgen can translate your needs, from design to installation, into a custom motion solution that makes your end product more competitive **– driving market share and profitability for your company.**

For flexible production runs, from high volume to one piece, Kollmorgen provides on optimized solution that fits your needs – perfectly.



Optimized Solutions

Whether it's modifying a product from our standard catalog or a white sheet design for a custom solution, you can rely on decades of Kollmorgen expertise to solve your motion challenges and help your machine stand out from the crowd.

Modified Standard

Because our application expertise runs deep and our product portfolio is so broad, we can take any standard product and modify it a lot or a little to suit many needs – in a very rapid time frame. This approach ensures quality, performance and reliability by leveraging our proven track record.

Kollmorgen application engineers have a great deal of experience helping OEM engineers achieve their objectives: Typical motor modifications include shaft, housing, winding and through-bore alterations; feedback type; mounting and connectors; ruggedization (high-shock-and-vibration), vacuum-duty, radiation-hardened, explosion-proof. Typical drive modifications include housing, mounting and heat-sinking; connector type; I/O type- and count; field buses and motion buses; special cabling; ruggedization (high-shock-and-vibration).

Custom Products

With motion as our core capability, we bring a significant history of innovation to today's engineering challenges. We leverage our design and engineering excellence and technical knowledge to deliver creative new solutions for virtually any need. Our vast experience also helps us deliver a custom product in a surprisingly short time. If you can conceive it, we can make it happen.

Project Management

We follow a structured development process from initial concept to volume production. This enables us to provide a complete solution from design to implementation.

Our skilled engineering team is assigned to each project and ensures a high quality product, designed and delivered on time, successfully taking the prototype to full production.

- Dedicated Resources & Equipment
- Real Time Customer Collaboration
- Validation of Performance, Cost & Manufacturability Before Volume Production

Customer Visibility Throughout the Entire Process

A communicative and proactive approach keeps you updated and aware of what is required throughout, what it will cost, and what to expect for design testing

This not only puts you in charge of approving any modifications before installation, but ensures the product is up and running quickly, with minimal development time and maximum value.

Engineering Excellence

What really sets us apart is our engineering expertise. With over 50 years of successfully designing custom motors, we are able to quickly assess, design and implement a solution that meets your needs.

Our engineers have an average tenure of 20 years, which means they have designed solutions for almost every unique and challenging situation. Their insightfulness and expertise will guide you through the development and implementation of an optimized motor solution.

We rely on the most advanced simulation tools to deliver the best products, designed to withstand the most unique and challenging environments:

- 3-D Modeling –ProE
- Finite Element Analysis
  - –Electromagnetics
  - –Structural (stress, vibration, fatigue)
  - –Thermal
- Speed
- Infolytica
- Ansys
- Magneto

Why You Should Partner with Kollmorgen

- Experienced application engineers help define a customer's needs and identify the optimal Kollmorgen products and technologies
- Products optimized or developed by cross-functional teams to meet customer needs
- Rapid prototyping
- Smooth transition from prototype designs to sustainable and cost effective manufacturing
- Industry-proven quality, performance, and delivery
- Proven technology building blocks mitigate risks of customization

Capabilities to Meet Your Needs

Kollmorgen offers 5-day lead-time on nearly 1,000,000 commercial off-the-shelf (COTS) products, all with best-in-class performance and quality.

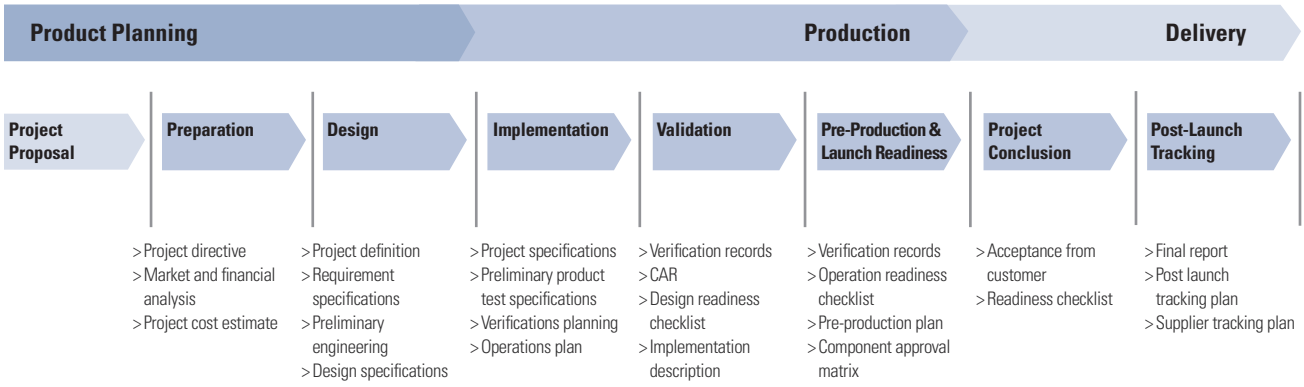
When COTS is not quite the best way to realize a totally optimized system, Kollmorgen can offer co-engineered solutions to meet your most difficult challenges and advance your competitive position. Drawing on a wealth of knowledge and expertise, our engineering support team will work alongside you to build a solution that differentiates your machine and improves your bottom line.

Here are just few examples of how Kollmorgen delivers real value to companies likes yours:

What You Need	Why Motion Matters	Kollmorgen Co-Engineering Results
30% Increase in Throughput	• Low inertia servo motors • High bandwidth servo loops • Simple, accurate, graphical programming tools	Using the Kollmorgen Automation Suite™ graphical camming design tool, Pipe Network™ and low-inertia AKM® servo motors, a major supplier of diabetic test labs increased throughput by more than 30% while improving accuracy and reducing scrap.
50% Increase in Accuracy and Quality	• Low cogging frameless servo motor • Advanced observers and bi-quad filters • Fast control loop update rates (.67µs)	Using our AKD® servo drive, a next-generation CT scanning manufacturer achieved more than 50% improvement in velocity ripple to produce the most accurate and detailed medical images possible while overcoming an extremely high moment of inertia.
25% Increase in Reliability (Overall Equipment Effectiveness)	• Innovative Cartridge Direct Drive Rotary® DDR motor • Eliminating parts on the machine • No additional wearing components	Using Kollmorgen's award-winning Cartridge DDR® servo motor technology, we eliminated more than 60 parts in a die-cutting machine and increased the OEE by 25% and throughput by 20%.
50% Reduction in Waste	• Superior motor/drive system bandwidth • DDR technology: – eliminates gearbox – 20X more accurate than geared solution	We helped a manufacturer of pharmaceutical packaging machines incorporate Housed DDR motors to increase the throughput by 35% and reduce scrap by more than 50% through more accurate alignment of the capsules.

Optimized Solutions Process

Comprehensive design, manufacture and test capabilities ensure the end product meets the customer performance specifications and quality requirements. Our skilled engineering team works directly with each customer throughout the process, quickly taking the prototype to full production.



Proven Design Capabilities

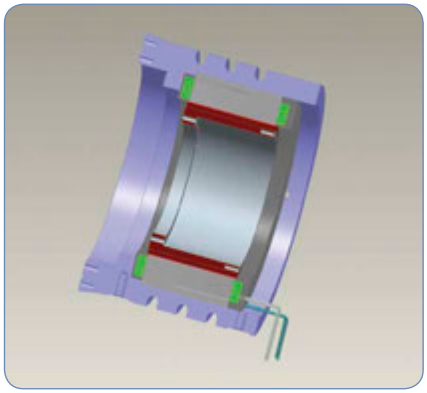
Motor Solutions

- Brushed, brushless and stepper motor building blocks used in frameless or housed configurations
- Designed for agency compliance (UL, CE, RoHS)
- Voltage ratings from 48 Vdc – 600 Vdc, with capabilities in 800 Vdc and up
- Continuous torques from 0.5 Nm – 29,000 Nm
- Proven performance and reliability in a customizable package

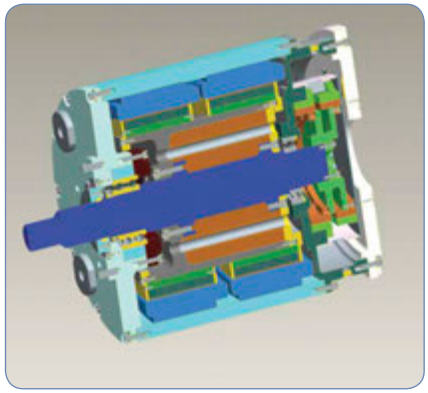
Drive Solutions

- Board-level or packaged solutions supporting single to multi-axis configurations
- Brushed or brushless servo drives, stepper, AC induction control
- Integrated controller and communications options
- Designed for agency approvals (UL 508C, EN 50178, EN 61000-6-6, EN 61800-3, CISPR 14-1, and others available)
- Proprietary technology and software can be embedded into the drive

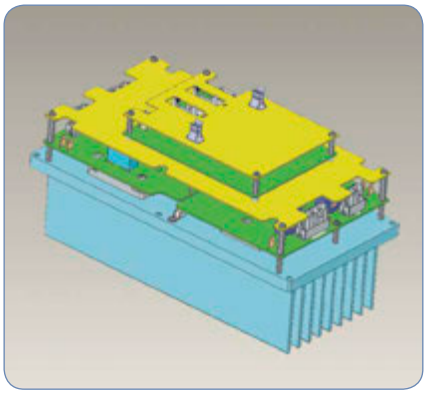
Medical diagnostics drive optimized for form-factor, I/O and EMC



Frameless direct drive rotary motor with water cooling features

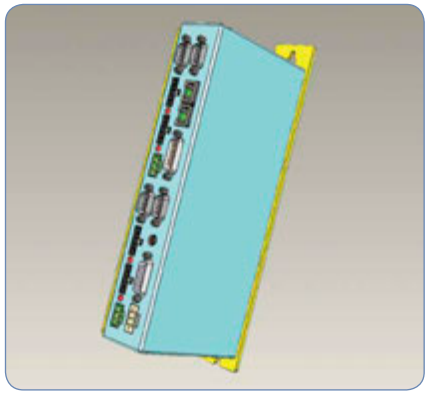


Custom submersible motor



2-axis drive for high-power robotics, optimized for form-factor and communications interface

200 kW electric starter/generator



4-axis stepper drive using SynqNet

Motors and Electronics

Optimized for	Application
Reliability, weight	Implantable heart pumps, military, remote equipment
Precision	Pick and place, satellite tracking, film processing
Package size	Medical imaging, ground based telescopes, aircraft instrumentation, collaborative robotics
Smooth operation	Medical respirators, high precision robotics, printing and textile machines
Harsh environments	Deep sea, outer space, high shock and vibration, extreme temperatures

Kollmorgen Motors for Special Duty

Every day Kollmorgen pushes the boundaries of motion to deliver optimized solutions that satisfy even the most demanding application requirements in the harshest of environments.

We've been working with the biggest names in harsh and hazardous environments in Industry, Automation, Aerospace & Defense, Exploration, Nuclear, Medical and Robotics for nearly 60 years.

We are on Mars and the Moon and at the bottom of the oceans: In fact, Kollmorgen motors powered the legendary ROV Jason Jr. at a depth of 3,784 meters (12,415 feet) to explore the interior of Titanic for the first time since it sank in 1912.

Kollmorgen continues to collaborate with leading innovators with the same enthusiasm and acumen: Kollmorgen knows that motion matters and represents endless possibilities for innovation. Our engineering expertise and engineering capabilities enable us to deliver superior performing solutions for these demanding environments.

Goldline® S Series Submersible Servo Motors

These brushless servo motors incorporate pressure compensation technology to allow underwater operation up to 20,000 ft while withstanding extreme environments. They feature stainless steel and aluminum nickel bronze housings or an anodized aluminum housing for lighter overall weight. All shafts are stainless steel and sealed with an externally serviceable O-ring seal. The S Series is fully tooled for cost-effective volume production.

- Choice of stainless steel and aluminum nickel bronze housings or an anodized aluminum housing for lighter overall weight
- Stainless steel shaft with externally serviceable seal
- SEACON connectors
- Pressure compensated: 10,000 psi
- Designed to withstand severe shock and extreme environments

EKM Series Brushless AC Servo Motors

These enhanced, high-performance motors are Mil-Spec 810E rated and IP67 sealed, and comes standard with a stainless steel and chemical-agent-resistant paint, for duty in harsh environmental conditions.

- 0.43 to 53 Nm continuous stall torque (3.8 to 467 lb-in)
- Speeds up to 8000 RPM meet high speed requirements
- Custom windings, shaft variations, and fail-safe brakes available
- 480 Vac high voltage insulation
- Rugged resolver feedback for extreme environments
- Operating temperature range of -51° C to 54° C
- Shock and vibration tested per MIL-STD-810E, Methods 516.4 & 514.4, Procedure 1
- International standard mount available

MX Series Hazardous Duty Motors

The explosion-proof MX Series provides hazardous-duty stepper motors suitable for use in Class 1, Division 1, Group D locations. They are available in NEMA 34 and 42 frame sizes (90 and 110 mm), and provide minimum holding torques from 1.27 to 9.82 N-m (180 to 1390 oz-in).

- MX09 models: NEMA 34 (90 mm) motors available in three stack lengths with minimum torque ratings from 1.27 to 3.88 N-m (180 to 550 oz-in
- MX11 models: NEMA 42 (110 mm) motors available in 2 stack lengths with minimum torque ratings from 6.0 to 9.82 N-m (850 to 1390 oz-in)
- Speeds up to 3,000 rpm provide for velocity demands of most high torque applications

Hazardous Duty Synchronous Motors

These synchronous motors are available in UL Listed versions suitable for use in Class I, Division 1, Group D hazardous locations. They provide torque up to 1,500 oz-in (1059 N-cm) and are available in NEMA 42 and 66 frame sizes (110 mm and 170 mm).

- Motor torque up to 1,500 oz-in (1059 N-cm)
- 72 rpm at 60 Hz, 60 rpm at 50 Hz
- 120 and 240 volt AC versions
- UL Listed versions meet Class I, Division 1, Group D requirements
- Conduit-style connection

EP Series Explosion-Proof Motors

These permanent magnet DC (PMDC) motors are SCR rated and adhere to NEMA standards. They are available in a variety of DC voltages, from 1/4 to 3/4 HP.

- Patented anti-cog magnets for smooth low speed operation
- Polyester-impregnated armature for electrical and mechanical integrity
- High overcurrent capacity and dynamic braking
- Rugged, fused commutator
- TEFC and TENV configurations
- Long life, constant force brush springs with field-replaceable brushes
- Gasketed conduit box with large wiring compartment
- Large sealed bearings, standard
- Class H insulation

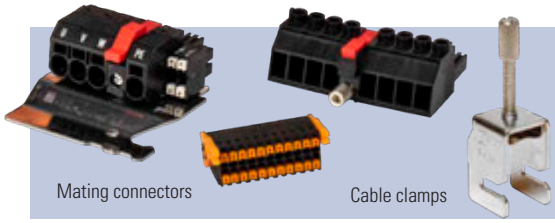
EB Series High-Performance Explosion-Proof Servo Motors

Based on our 230 VAC B and M Series, the Kollmorgen EB Series provides a high-performance explosion-proof servo motor suitable for applications where flammable vapors or gases create a potentially hazardous environment. These motors have been tested and proven capable of withstanding an internal explosion without bursting or allowing ignition to reach outside the motor frame.

- 230 VAC explosion-proof (Class I, Division 1, Groups C and D)
- Tested and proven capable of withstanding an internal explosion without bursting or allowing ignition to reach outside the motor frame

Servo Drive Accessories

For more details on accessories, please see the accessories guide on www.kollmorgen.com



Mating Connectors and Shielding Kit

Kollmorgen's servo drives are equipped with screwable mating connectors. Alternative connectors for common DC, bus, and main ports are also available. We offer shielding kits for our flexible cables for use in environments with strong interference.

Shielding Solutions

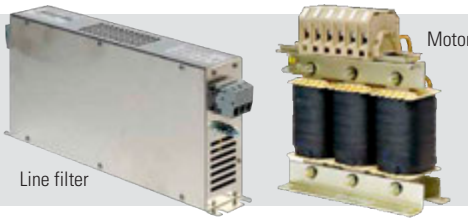
AKD servo drives can be equipped with shielding plates.

Brake Resistors

We offer a full line of brake resistors up to 6000 watts. Brake resistors are impedance matched with AKD and are available in many sizes and form factors.

Chokes and Filters

Line filters are offered to improve reliability and to protect the life of the machine in less stable environments. Motor chokes reduce radiated emissions and are recommended for applications with cable lengths >25 meters.

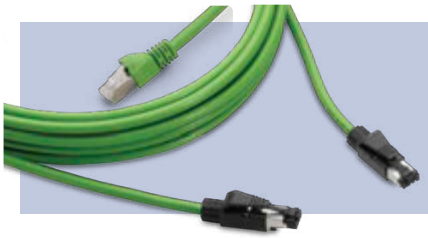


Static Energy Storage

Our Static Energy Storage supplies the drive with power in the event of power outages until the machine reaches a defined state. It generates a power outage signal for evaluation by the machine control system. Simple connection to the DC intermediate circuit with two cables; immediately ready for use; no adjustment; no controls. Cascade for nearly unlimited power range.

Braking Energy Storage

Our Braking Energy Storage saves Energy through Intelligent Energy Feedback. Substantial saving, especially in applications with short cycle times. Simple connection to DC intermediate circuit. Simple start-up – immediately ready for use; no adjustment; no controls. Nearly unlimited power range with expansion modules.

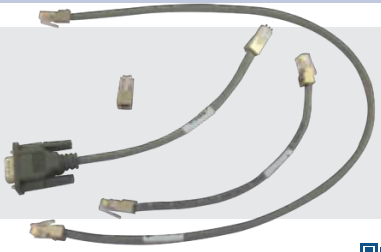


Motion Bus and Service Port Cables

We offer industrial shielded PUR cables with RJ45 connections for demanding industrial environments. These cables outperform office cables in EMC resilience, durability, and life.

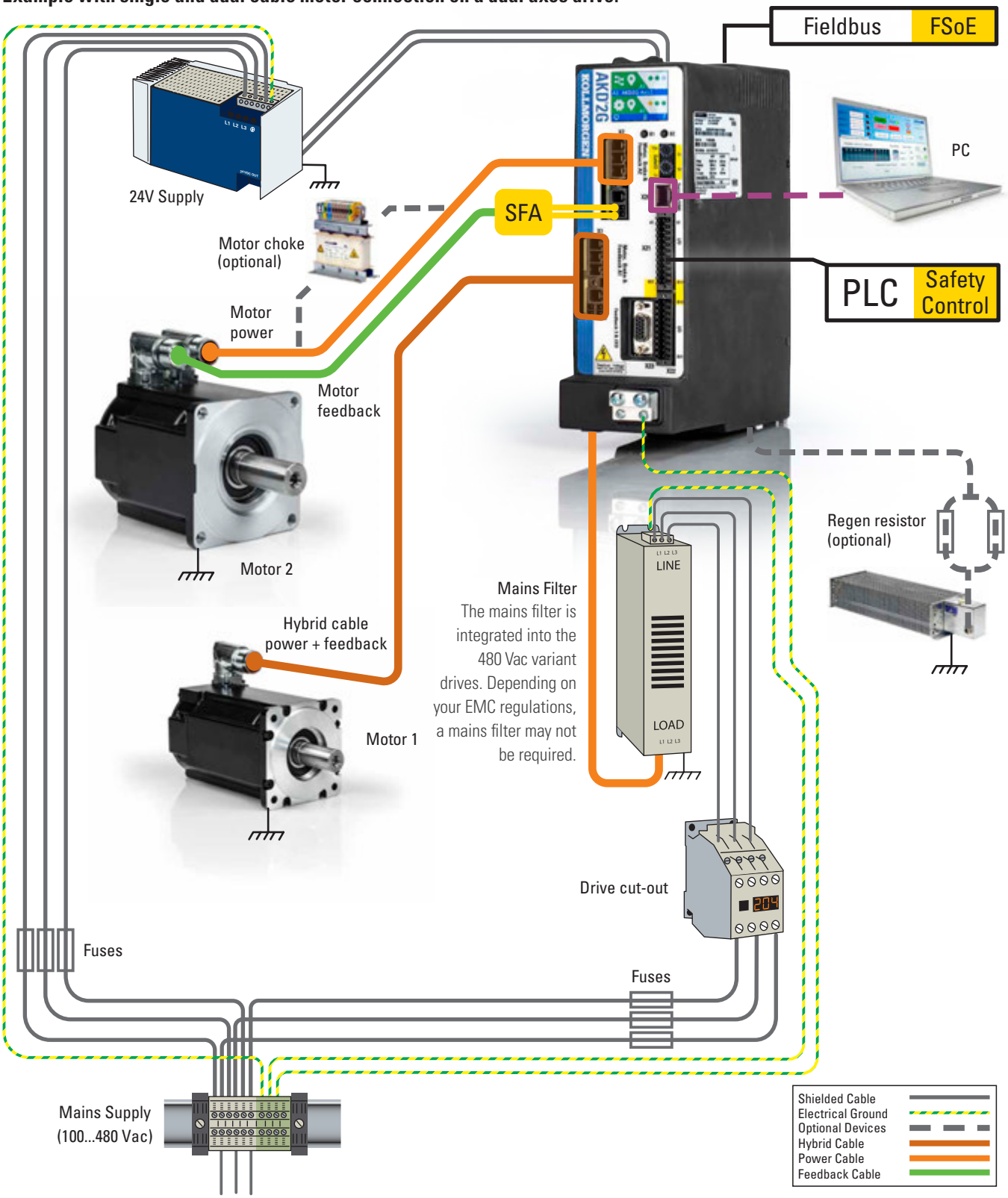
CANopen® Accessories

We offer cables, terminators and adapters for simple integration with CANopen machine networks.



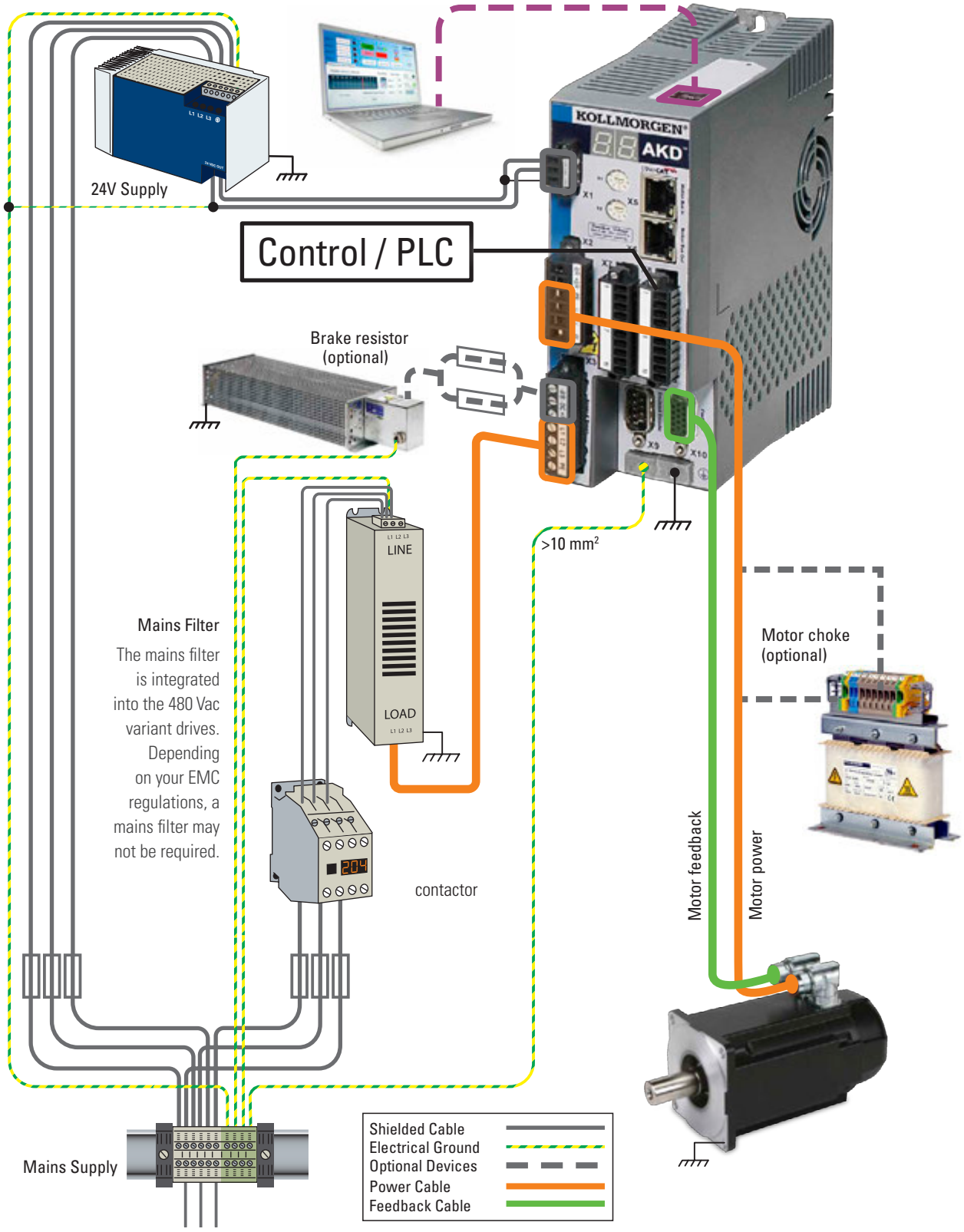
Drive System with AKD2G-Sxx-6VxxD

Example with single and dual cable motor connection on a dual axes drive.

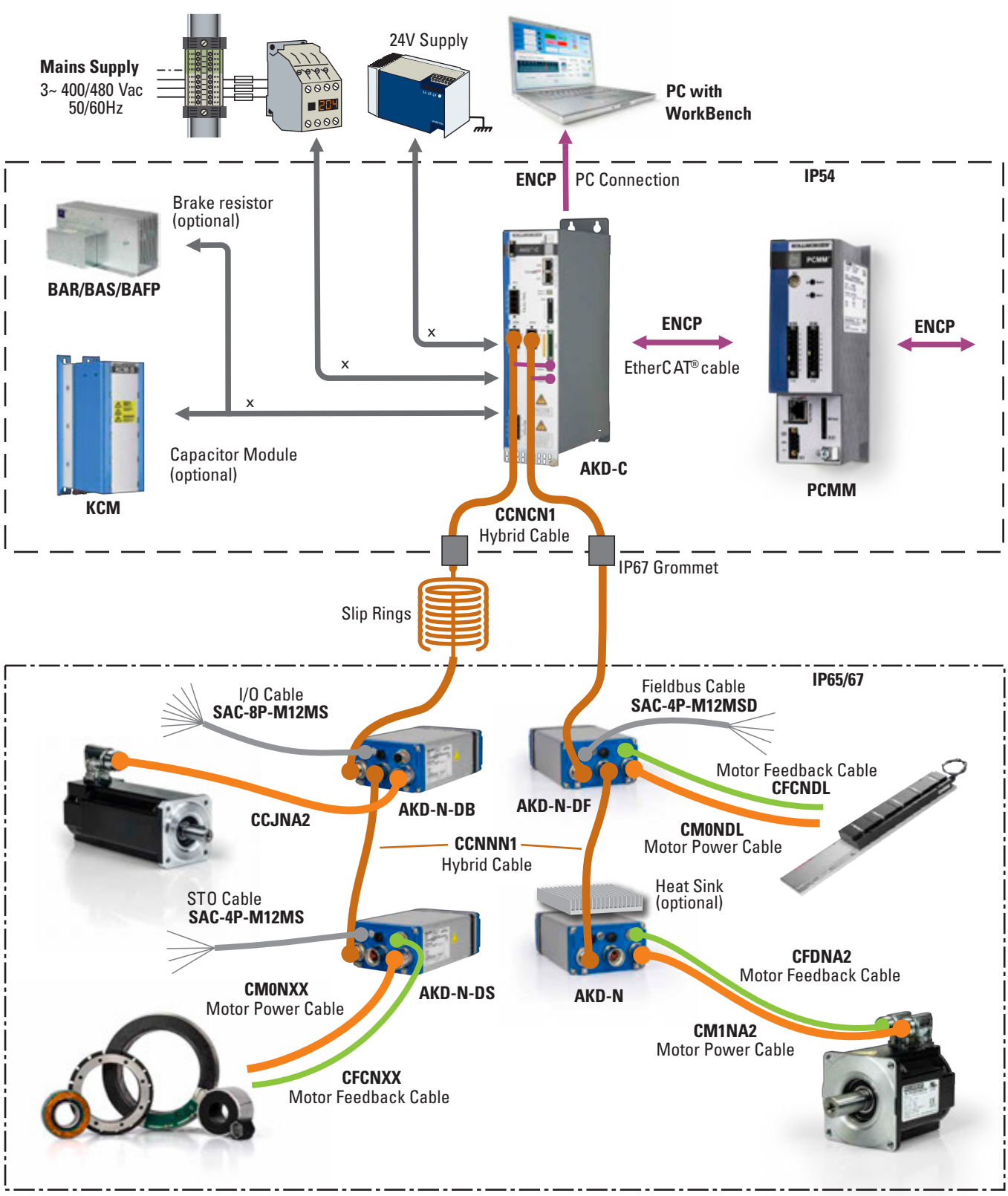


Servo Drive Accessories

Drive System with AKD-x00306...02406



System Featuring AKD®-N



Kollmorgen Servo Drive Cables

High-performance servo systems require high signal integrity. Electrical noise in the system can cause degraded performance or even instability. Therefore, well-designed connectors and cables are as critical to the system as are motors, drives and controls. A system is only as good as its weakest link.

Kollmorgen guarantees the performance and quality of its servo systems only when you use Kollmorgen-supplied motors, drives and cables. Not all cables are created equal.

Kollmorgen has done the hard work for you: The cables in this Selection Guide have been tested with our motors, guaranteeing the highest level of performance. This guide will also provide the detail behind industry standards to assist selecting the right cable for specific application needs.

Kollmorgen Cable Features	Benefits
100% shielded end-to-end with prewired Kollmorgen connectors	Mitigate radiated noise from cable and noise immunity from external sources
Large-diameter power conductors	Able to handle peak currents needed for servo control Minimal impedance in the cables maximizes efficiency and noise immunity
Cable Flex rating	Flexible cables, suitable for trailing, last longer when connected to a moving motor.
Cable bend radius	Tight-bend-radius cables are useful when you have to jam the cables into a tight fit such as a sharp corner or smaller cable track
High-voltage rated	Meets approvals such as UL and CE

Kollmorgen 2G Cable Overview

Kollmorgen offers high performance servo cables to ensure the drive and motor operate at peak performance. Every cable in this Selection Guide has passed Kollmorgen's rigorous tests. Our support team can provide you the optimal cable configuration for any given combination of drive, motor, and environment.

Dual Cables

Dual cable solutions separate power from feedback and typically allow for longer distances between the drive and motor. Dual cables are available for Resolver feedback on AKM®2G motors.

Hybrid Cables

Hybrid cables combine power conductors and feedback-signal conductors in one cable. Less cable means lower cost, reduced weight, and fewer connectors on the motor. Hybrid Cables are available for SFD3, HIPERFACE DSL® and EnDat® feedback on AKM2G motors.

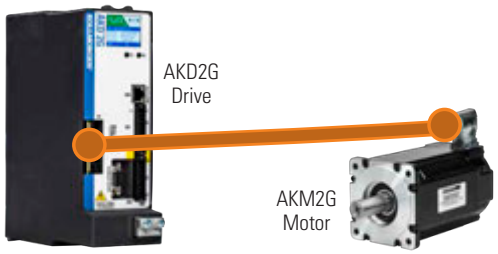
Additional Dual Cable Feedback Options on AKM® motors:

- SFD (Smart Feedback Device)
- Single & Multi-turn EnDat® sine encoders
- Single & Multi-turn BiSS sine encoders
- Single & Multi-turn HIPERFACE® sine encoders
- Up to 5000 lines/rev commutating encoders

Kollmorgen 2G Cable Lookup Tables

AKD®2G Servo Drive Section

Hybrid Single Cable Options



Smart Feedback Device (SFD3) – AKM®2G motor to AKD®2G drive

Motor Feedback	Drive	Motor Connector	Current Rating[1]	Hybrid Cable (PUR)[2]	Hybrid Cable (PVC)[3]
SFD3 (CA)	AKD2G-SPx-6V03x AKD2G-SPx-6V06x AKD2G-SPx-6V12x AKD2G-SPx-7V03x AKD2G-SPx-7V06x AKD2G-SPx-7V12x	SpeedTec® (D)	Rms<15	H2-21-015-A1-00-XXXX00	H6-21-015-A1-00-XXXX00

HIPERFACE DSL® – AKM®2G motor to AKD®2G drive

Motor Feedback	Drive	Motor Connector	Current Rating[1]	Hybrid Cable (PUR)[2]	Hybrid Cable (PVC)[3]
HIPERFACE DSL (GU)	AKD2G-SPx-6V03x AKD2G-SPx-6V06x AKD2G-SPx-6V12x AKD2G-SPx-7V03x AKD2G-SPx-7V06x AKD2G-SPx-7V12x	htec® (D)	Rms<15	H2-21-015-B1-00-XXXX00	H6-21-015-B1-00-XXXX00

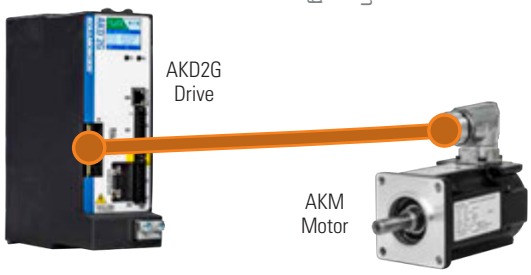
EnDat® 2.2 – AKM®2G motor to AKD®2G drive

Motor Feedback	Drive	Motor Connector	Current Rating[1]	Hybrid Cable (PUR)[2]	Hybrid Cable (PVC)[3]
EnDat 2.2 (LD)[4]	AKD2G-SPx-6V03x AKD2G-SPx-6V06x AKD2G-SPx-6V12x AKD2G-SPx-7V03x AKD2G-SPx-7V06x AKD2G-SPx-7V12x	htec® (D)	Rms<15	H2-21-015-B2-00-XXXX00	NA

Notes:
1. Current ratings used on a IEC 60364-5-52 standard
2. PUR cables have a Polyurethane cable jacket material typically used in Europe
3. PVC cables have a Polyvinyl Chloride cable jacket material typically used in North America
4. Hybrid EnDat 2.2 - 22 cable requires X23 connector on AKD2G drive and only can be used with the X1 connector.

H6 – 21 – 015 – A5 – 00 – XXXX00*

- H6: Cable Version
- 21: Drive Connector
- 015: Wire X-section
- A5: Motor Mating Connector
- 00: Customization
- XXXX00: Length



Smart Feedback Device (SFD3) – AKM® motor to AKD®2G drive

Motor Feedback	Drive	Motor Connector	Current Rating[1]	Hybrid Cable (PUR)[2]	Hybrid Cable (PVC)[3]
SFD3 (CA)	AKD2G-SPx-6V03x AKD2G-SPx-6V06x AKD2G-SPx-6V12x	itec® AKM1 only	Rms<11	H2-21-010-C4-00-XXXX00	H6-21-010-C4-00-XXXX00
	AKD2G-SPx-7V03x AKD2G-SPx-7V06x AKD2G-SPx-7V12x	SpeedTec® (D)	Rms<15	H2-21-015-A5-00-XXXX00	H6-21-015-A5-00-XXXX00

HIPERFACE DSL® – AKM® motor to AKD®2G drive

Motor Feedback	Drive	Motor Connector	Current Rating[1]	Hybrid Cable (PUR)[2]	Hybrid Cable (PVC)[3]
HIPERFACE DSL (GE, GF)	AKD2G-SPx-6V03x AKD2G-SPx-6V06x AKD2G-SPx-6V12x AKD2G-SPx-7V03x AKD2G-SPx-7V06x AKD2G-SPx-7V12x	SpeedTec® (D)	Rms<15	H2-21-015-A5-00-XXXX00	H6-21-015-A5-00-XXXX00

Notes:
1. Current ratings used on a IEC 60364-5-52 standard
2. PUR cables have a Polyurethane cable jacket material typically used in Europe
3. PVC cables have a Polyvinyl Chloride cable jacket material typically used in North America

AKM1 itec Power + SFD3 Mating Connector

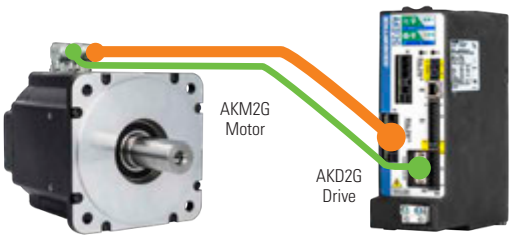
AKD2G Drive Connector

*Complete 2G Cable nomenclature can be found on page 188.

Kollmorgen 2G Cable Lookup Tables

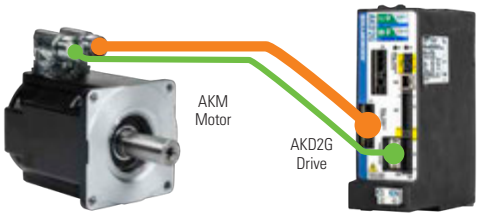
AKD®2G Servo Drive Section

Dual Cable Options – Power and Feedback



Resolver – AKM®2G motor to AKD®2G drive

Motor Feedback	Drive	Motor Connector	Current Rating[1]	Brake Option	Power Cable (PUR)[2] + 00-XXXX00	Power Cable (PVC)[3] + 00-XXXX00	Feedback Cable (PUR)[2] + 00-XXXX00	Feedback Cable (PVC)[3] + 00-XXXX00
Resolver (R-)	AKD2G-SPx-6V03x AKD2G-SPx-6V06x AKD2G-SPx-6V12x AKD2G-SPx-7V03x AKD2G-SPx-7V06x AKD2G-SPx-7V12x	ytec® (Y)	Rms<15	No Brake	P1-21-015-C1-	P5-21-015-C1-	F1-10-FB2-C2-	F5-10-FB2-C2-
				Brake	P2-21-015-C1-	P6-21-015-C1-		
		SpeedTec® (C or G)	Rms<15	No Brake	P1-21-015-A1-	P5-21-015-A1-	F1-10-FB2-A2-	F5-10-FB2-A2-
				Brake	P2-21-015-A1-	P6-21-015-A1-		



Resolver – AKM® motor to AKD®2G drive

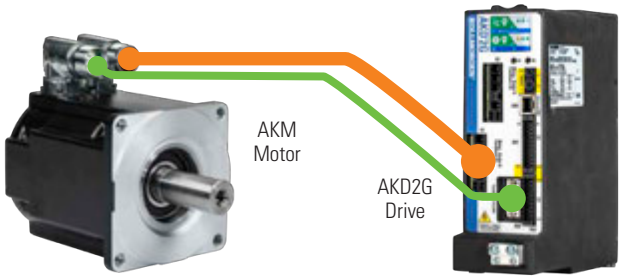
Motor Feedback	Drive	Motor Connector	Current Rating[1]	Brake Option	Power Cable (PUR)[2] + 00-XXXX00	Power Cable (PVC)[3] + 00-XXXX00	Feedback Cable (PUR)[2] + 00-XXXX00	Feedback Cable (PVC)[3] + 00-XXXX00
Resolver (R-)	AKD2G-SPx-6V03x AKD2G-SPx-6V06x AKD2G-SPx-6V12x AKD2G-SPx-7V03x AKD2G-SPx-7V06x AKD2G-SPx-7V12x	ytec (Y)	Rms<15	No Brake	P1-21-015-C1-	P5-21-015-C1-	F1-10-FB2-C2-	F5-10-FB2-C2-
				Brake	P2-21-015-C1-	P6-21-015-C1-		
		SpeedTec (C or G)	Rms<15	No Brake	P1-21-015-A5-	P5-21-015-A5-	F1-10-FB2-A2-	F5-10-FB2-A2-
				Brake	P2-21-015-A5-	P6-21-015-A5-		

Smart Feedback Device – AKM® motor to AKD®2G drive

Motor Feedback	Drive	Motor Connector	Current Rating[1]	Brake Option	Power Cable (PUR)[2] + 00-XXXX00	Power Cable (PVC)[3] + 00-XXXX00	Feedback Cable (PUR)[2] + 00-XXXX00	Feedback Cable (PVC)[3] + 00-XXXX00
Smart Feedback Device (C-)	AKD2G-SPx-6V03x AKD2G-SPx-6V06x AKD2G-SPx-6V12x AKD2G-SPx-7V03x AKD2G-SPx-7V06x AKD2G-SPx-7V12x	ytec (Y)	Rms<15	No Brake	P1-21-015-C1-	P5-21-015-C1-	F1-18-FB3-C2-	F5-18-FB3-C2-
				Brake	P2-21-015-C1-	P6-21-015-C1-		
		SpeedTec (C or G)	Rms<15	No Brake	P1-21-015-A5-	P5-21-015-A5-	F1-18-FB3-A2-	F5-18-FB3-A2-
				Brake	P2-21-015-A5-	P6-21-015-A5-		

Notes:
1. Current ratings used on a IEC 60364-5-52 standard
2. PUR cables have a Polyurethane cable jacket material typically used in Europe
3. PVC cables have a Polyvinyl Chloride cable jacket material typically used in North America
4. Hybrid EnDat 2.2 - 22 cable requires X23 connector on AKD2G drive and only can be used with the X1 connector.

F5 – 10 – FB2 – C2 – 00 – XXXX00*
Cable Version – Drive Connector – Wire X-section – Motor Mating Connector – Customization – Length



Commutating Encoder – AKM® motor to AKD®2G drive

Motor Feedback	Drive	Motor Connector	Current Rating[1]	Brake Option	Power Cable (PUR)[2] + 00-XXXX00	Power Cable (PVC)[3] + 00-XXXX00	Feedback Cable (PUR)[2] + 00-XXXX00	Feedback Cable (PVC)[3] + 00-XXXX00
Sine/Incr. Encoder w/ Halls (Ex, 1-,2-)	AKD2G-SPx-6V03x AKD2G-SPx-6V06x AKD2G-SPx-6V12x AKD2G-SPx-7V03x AKD2G-SPx-7V06x AKD2G-SPx-7V12x	ytec® (Y)	Rms<15	No Brake	P1-21-015-C1-	P5-21-015-C1-	F1-20-FB4-C3-	F5-20-FB4-C3-
				Brake	P2-21-015-C1-	P6-21-015-C1-		
		SpeedTec® (C or G)	Rms<15	No Brake	P1-21-015-A5-	P5-21-015-A5-	F1-20-FB4-A3-	F5-20-FB4-A3-
				Brake	P2-21-015-A5-	P6-21-015-A5-		

EnDat®/BiSS Encoder – AKM® motor to AKD®2G drive

Motor Feedback	Drive	Motor Connector	Current Rating[1]	Brake Option	Power Cable (PUR)[2] + 00-XXXX00	Power Cable (PVC)[3] + 00-XXXX00	Feedback Cable (PUR)[2] + 00-XXXX00	Feedback Cable (PVC)[3] + 00-XXXX00
EnDat/BiSS (Ax, Dx, Lx)	AKD2G-SPx-6V03x AKD2G-SPx-6V06x AKD2G-SPx-6V12x AKD2G-SPx-7V03x AKD2G-SPx-7V06x AKD2G-SPx-7V12x	SpeedTec (C or G)	Rms<15	No Brake	P1-21-015-A5-	P5-21-015-A5-	F1-12-FB4-A3-	F5-12-FB4-A3-
				Brake	P2-21-015-A5-	P6-21-015-A5-		

HIPERFACE® Optical Sine Encoder – AKM® motor to AKD®2G drive

Motor Feedback	Drive	Motor Connector	Current Rating[1]	Brake Option	Power Cable (PUR)[2] + 00-XXXX00	Power Cable (PVC)[3] + 00-XXXX00	Feedback Cable (PUR)[2] + 00-XXXX00	Feedback Cable (PVC)[3] + 00-XXXX00
HIPERFACE (Gx)	AKD2G-SPx-6V03x AKD2G-SPx-6V06x AKD2G-SPx-6V12x AKD2G-SPx-7V03x AKD2G-SPx-7V06x AKD2G-SPx-7V12x	ytec (Y)	Rms<15	No Brake	P1-21-015-C1-	P5-21-015-C1-	F1-14-FB6-C2-	F5-14-FB6-C2-
				Brake	P2-21-015-C1-	P6-21-015-C1-		
		SpeedTec (C or G)	Rms<15	No Brake	P1-21-015-A5-	P5-21-015-A5-	F1-14-FB6-A3-	F5-14-FB6-A3-
				Brake	P2-21-015-A5-	P6-21-015-A5-		

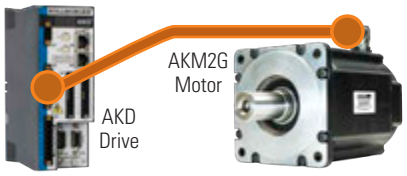
Notes:
1. Current ratings used on a IEC 60364-5-52 standard
2. PUR cables have a Polyurethane cable jacket material typically used in Europe
3. PVC cables have a Polyvinyl Chloride cable jacket material typically used in North America

*Complete 2G Cable nomenclature can be found on page 188.

Kollmorgen 2G Cable Lookup Tables

AKD® Servo Drive Section

Hybrid Single Cable Options



Smart Feedback Device (SFD3) – AKM®2G motor to AKD® drive

Voltage	Motor Feedback	Drive	Motor Connector	Current Rating[1]	Hybrid (PUR)[3]	Hybrid Cable (PVC)[4]
120-240	SFD3 (CA)	AKD-x00306 AKD-x00606	SpeedTec® (D)	Rms<15	H2-11-015-A1-00-XXXX00	H6-11-015-A1-00-XXXX00
		AKD-x01206 AKD-x02406	SpeedTec (D)	Rms<20[2]	H2-12-025-A1-00-XXXX00	H6-12-025-A1-00-XXXX00
			SpeedTec (J)	Rms<27	H2-12-040-A4-00-XXXX00	–
				Rms<34	H2-12-060-A4-00-XXXX00	–
240-480	SFD3 (CA)	AKD-x00307 AKD-x00607 AKD-x01207	SpeedTec (D)	Rms<15	H2-12-015-A1-00-XXXX00	H6-12-015-A1-00-XXXX00
		AKD-x02407	SpeedTec (D)	Rms<20[2]	H2-12-025-A1-00-XXXX00	H6-12-025-A1-00-XXXX00
			SpeedTec (J)	Rms<27	H2-12-040-A4-00-XXXX00	–
				Rms<34	H2-12-060-A4-00-XXXX00	–
		AKD-X04807	SpeedTec (J)	Rms<34	H2-13-060-A4-00-XXXX00	–

HIPERFACE DSL® – AKM®2G motor to AKD® drive

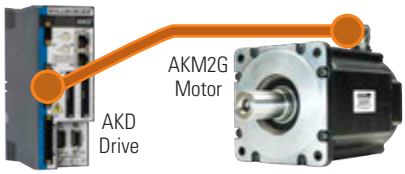
Voltage	Motor Feedback	Drive	Motor Connector	Current Rating[1]	Hybrid (PUR)[3]	Hybrid Cable (PVC)[4]
120-240	HIPERFACE DSL (GU)	AKD-x00306 AKD-x00606	htec® (D)	Rms<15	H2-11-015-B1-00-XXXX00	H6-11-015-B1-00-XXXX00
		AKD-x01206 AKD-x02406	htec (D)	Rms<20[2]	H2-12-025-B1-00-XXXX00	H6-12-025-B1-00-XXXX00
			htec (J)	Rms<27	H2-12-040-B3-00-XXXX00	–
				Rms<34	H2-12-060-B3-00-XXXX00	–
240-480	HIPERFACE DSL (GU)	AKD-x00307 AKD-x00607 AKD-x01207	htec (D)	Rms<15	H2-12-015-B1-00-XXXX00	H6-12-015-B1-00-XXXX00
		AKD-x02407	htec (D)	Rms<20[2]	H2-12-025-B1-00-XXXX00	H6-12-025-B1-00-XXXX00
			htec (J)	Rms<27	H2-12-040-B3-00-XXXX00	–
				Rms<34	H2-12-060-B3-00-XXXX00	–
		AKD-X04807	htec (J)	Rms<34	H2-13-060-B3-00-XXXX00	–

Notes:
1. Current ratings used on a IEC 60364-5-52 standard
2. To utilize full current rating of AKD-x0240x please use the htec M40 motor connector (J)
3. PUR cables have a Polyurethane cable jacket material typically used in Europe
4. PVC cables have a Polyvinyl Chloride cable jacket material typically used in North America

H2 – 12 – 025 – A1 – 00 – XXXX00*
Cable Version | Drive Connector | Wire X-section | Motor Mating Connector | Customization | Length

AKD® Servo Drive Section

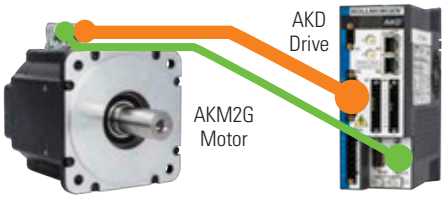
Hybrid Single Cable Options



EnDat® – AKM®2G motor to AKD® drive

Voltage	Motor Feedback	Drive	Motor Connector	Current Rating[1]	Hybrid (PUR)[3]	Hybrid Cable (PVC)[4]
120-240	EnDat 2.2 (LD)	AKD-x00306 AKD-x00606	htec® (D)	Rms<15	H2-14-015-B2-00-XXXX00	–
		AKD-x01206 AKD-x02406	htec (D)	Rms<15[2]	H2-15-015-B2-00-XXXX00	–
				Rms<27	H2-15-040-B2-00-XXXX00	–
240-480	EnDat 2.2 (LD)	AKD-x00307 AKD-x00607 AKD-x01207	htec (D)	Rms<15	H2-15-015-B2-00-XXXX00	–
		AKD-x02407	htec (D)	Rms<15	H2-15-015-B2-00-XXXX00	–
				Rms<27	H2-15-040-B2-00-XXXX00	–

Dual Cable Options – Power and Feedback



Resolver – AKM®2G motor to AKD® drive

Voltage	Motor Feedback	Drive	Motor Connector	Current Rating[1]	Brake Option	Power Cable (PUR)[3] + 00-XXXX00	Power Cable (PVC)[4] + 00-XXXX00	Feedback Cable (PUR)[3] + 00-XXXX00	Feedback Cable (PVC)[4] + 00-XXXX00
120-240	Resolver (R-)	AKD-x00306 AKD-x00606	ytec® (Y)	Rms<15	No Brake	P1-11-015-C1-	P5-11-015-C1-	F1-10-FB2-C2-	F5-10-FB2-C2-
					Brake	P2-11-015-C1-	P6-11-015-C1-		
			SpeedTec® (C or G)		No Brake	P1-11-015-A1-	P5-11-015-A1-	F1-10-FB2-A2-	F5-10-FB2-A2-
					Brake	P2-11-015-A1-	P6-11-015-A1-		
240-480	Resolver (R-)	AKD-x00307 AKD-x00607 AKD-x01207 AKD-x02407	ytec (Y)	Rms<15	No Brake	P1-12-015-C1-	P6-12-015-C1-	F1-10-FB2-C2-	F5-10-FB2-C2-
					Brake	P2-12-015-C1-	P1-12-015-C1-		
			SpeedTec (C or G)	Rms<15	No Brake	P1-12-015-A1-	P5-12-015-A1-	F1-10-FB2-A2-	F5-10-FB2-A2-
					Brake	P2-12-015-A1-	P6-12-015-A1-		
				Rms<20[2]	No Brake	P1-12-025-A1-	P5-12-025-A1-		
					Brake	P2-12-025-A1-	P6-12-025-A1-		
				Rms<27[2]	No Brake	P1-12-040-A1-	P5-12-040-A1-		
					Brake	P2-12-040-A1-	P6-12-040-A1-		
			htec® (H)	Rms<27	No Brake	P1-12-040-A4-	P5-12-040-A4-		
					Brake	P2-12-040-A4-	P6-12-040-A4-		
		AKD-X04807	htec (H)	Rms<34	No Brake	P1-13-060-A4-	P5-13-060-A4-		
					Brake	P2-13-060-A4-	P6-13-060-A4-		

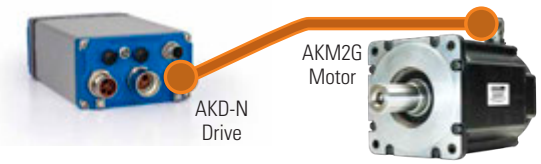
Notes:
1. Current ratings used on a IEC 60364-5-52 standard
2. To utilize full current rating of AKD-x0240x please use the htec M40 motor connector (J)
3. PUR cables have a Polyurethane cable jacket material typically used in Europe
4. PVC cables have a Polyvinyl Chloride cable jacket material typically used in North America

*Complete 2G Cable nomenclature can be found on page 188.

Kollmorgen 2G Cable Lookup Tables

AKD®-N Decentralized Servo Drive Section

Hybrid Single Cable Options



Smart Feedback Device (SFD3) – AKM®2G motor to AKD®-N drive

Drive	Motor Connector	Current Rating[1]	Hybrid (PUR)[3]	Hybrid Cable (PVC)[4]
AKD-N003 AKD-N006 AKD-N012	SpeedTec® (D)	Rms<15	H2-33-015-A1-00-XXXX00	H6-33-015-A1-00-XXXX00
		Rms<20	H2-33-025-A1-00-XXXX00	H6-33-025-A1-00-XXXX00

HIPERFACE DSL® – AKM®2G motor to AKD®-N drive

Drive	Motor Connector	Current Rating[1]	Hybrid (PUR)[3]	Hybrid Cable (PVC)[4]
AKD-N003 AKD-N006 AKD-N012	SpeedTec (D)	Rms<15	H2-33-015-B1-00-XXXX00	H6-33-015-B1-00-XXXX00
		Rms<20	H2-33-025-B1-00-XXXX00	H6-33-025-B1-00-XXXX00

Notes:
1. Current ratings used on a IEC 60364-5-52 standard
2. To utilize full current rating of AKD-x0240x please use the htec M40 motor connector (J)
3. PUR cables have a Polyurethane cable jacket material typically used in Europe
4. PVC cables have a Polyvinyl Chloride cable jacket material typically used in North America

AKD-N – AKM2G Power + HIPERFACE DSL Cable

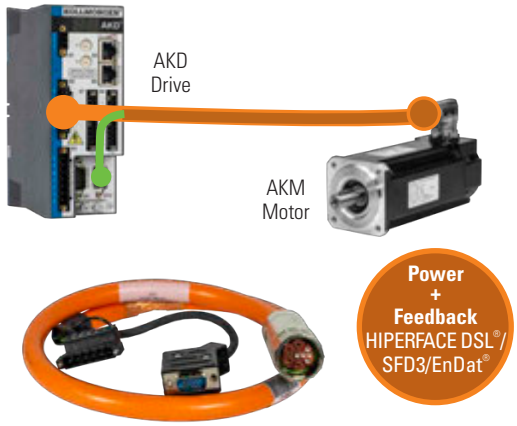
AKD® Performance Cables

Hybrid Cables

Hybrid cables offer a single connection point on the motor for both feedback and power. Feedback options for this connection type are:

- SFD GEN3 (Single-turn absolute, CA option)
- HIPERFACE® DSL (Single-turn absolute, GE option)
- HIPERFACE DSL (Multi-turn option, GF option)

Washdown versions of this cable are also available.



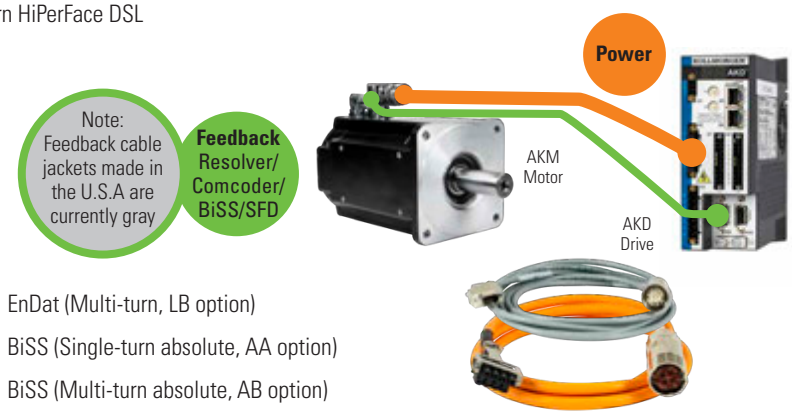
AKD Hybrid Cables by Motor Type

Motor	Hybrid Cable[1] option for 240V drives (AKD-xxxx06xxxx)	Hybrid Cable[1] option for 480V drives (AKD-xxxx07xxxx)
AKM < 12 A	CCJ1A2-015	CCJ2A2-015
12 A ≤ AKM < 20 A	CCJ2A2-025	CCJ2A2-025
Washdown AKM < 12 A	WCJ1A1-015	WCJ2A1-015
12 A ≤ Washdown AKM < 20 A	WCJ2A1-025	WCJ2A1-025

[1] Hybrid cables support SFD GEN 3, Single-turn and Multi-turn HiPerFace DSL

Dual Cables

Dual cables are used to separate power and feedback. Options included in this catalog support:



- HIPERFACE (Single-turn absolute, GJ option)
- HIPERFACE (Multi-turn absolute, GK option)
- EnDat (Single-turn, LA option)
- EnDat (Multi-turn, LB option)
- BiSS (Single-turn absolute, AA option)
- BiSS (Multi-turn absolute, AB option)

Motor	Power Cable	Power Cable with Brake	SFD	EnDat 2.2, 01& BiSS
AKM < 12 A	CP-507CCAN	CP-507CDAN	CF-DA0374N	CF-SB7374N
12 A ≤ AKM < 20 A	CP-507DCAN	CP-507DDAN	CF-DA0374N	CF-SB7374N
20 A ≤ AKM < 24 A	CP-508EDBN	CP-508EDBN	CF-DA0374N	CF-SB7374N
CDDR < 12 A	CP-507CCAN	N/A	N/A	CF-SB7374N
12 A ≤ CDDR < 20 A	CP-508DCAN	N/A	N/A	CF-SB7374N
20 A ≤ CDDR < 48 A	CM-13A4-010	N/A	N/A	CF-SB7374N
DDR < 12 A	CP-507CCAN	N/A	N/A	CF-SB7374N
12 A ≤ DDR < 20 A	CP-508DCAN	N/A	N/A	CF-SB7374N

Complete AKD Performance Cable nomenclature can be found on page 189.

AKD® Performance Cables

AKD Value Line Cables

Value Line Cables are alternative cable options suitable for most applications. These cables separate power and feedback. Options included in this catalog support Single-turn (GJ) and Multi-turn (GK) for AKD.

Motor	Power Cable	Power Cable with Brake	SFD	EnDat 2.2, 01& BiSS
AKM < 6 A	VP-507BEAN	VP-508CFAN	VF-DA0474N	VF-SB7374N
6 A ≤ AKM < 12 A	VP-508CEAN	VP-508CFAN	VF-DA0474N	VF-SB7374N
12 A ≤ AKM < 20 A	VP-508DEAN	VP-508DFAN	VF-DA0474N	VF-SB7374N
CDDR < 12 A	VP-507BEAN	N/A	N/A	VF-SB7374N
12 A ≤ CDDR < 20 A	VP-508CEAN	N/A	N/A	VF-SB7374N
20 A ≤ CDDR < 48 A	VP-508DEAN	N/A	N/A	VF-SB7374N
DDR < 12 A	VP-507BEAN	N/A	N/A	VF-SB7374N
12 A ≤ DDR < 20 A	VP-508CEAN	N/A	N/A	VF-SB7374N
12 A ≤ DDR < 20 A	VP-508DEAN	N/A	N/A	VF-SB7374N

Complete AKD Value Line Cable nomenclature can be found on page 189.

AKD®-N Performance Cables

Digital I/O cable for AKD-N

All AKD-N drives have one 8 poles M12 connector to connect digital control signals.

Drive	Part Number	Description
AKD-N (all)	SAC-8P-M12MS	5 m, M12 mating connector, unconfigured wires

STO Cable for AKD-N-DS

AKD-N-DS drives (devices with local STO input) have an additional 4 poles M12 connectors to connect the local STO signals.

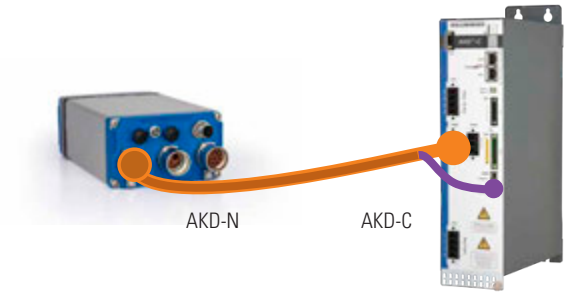
Drive	Part Number	Description
AKD-N-S	SAC-4P-M12MS	5 m, M12 mating connector, unconfigured wires, A- coded

Fieldbus cable for AKD-N-DF

AKD-N-DF drives (devices with local fieldbus input) have an additional 4 poles M12 connectors to connect the local fieldbus signals.

Drive	Part Number	Description
AKD-N-DF	SAC-4P-M12MSD/5.0	5 m, M12 mating connector, unconfigured wires, D- coded

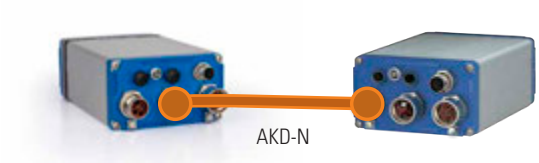
AKD®-N Performance Cables



Hybrid Cable Connecting AKD-C Power Supply to AKD-N Axis Module

Part Number	Description
CCNCN1-025-xxmyy-00	Hybrid cable connecting AKD-C to AKD-N

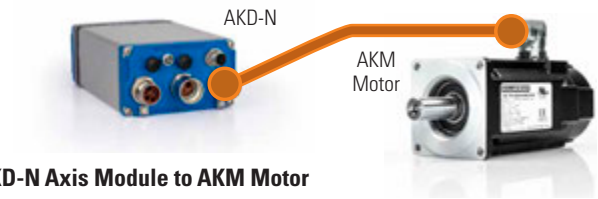
Length definition: xx=meters, yy=centimeters



Hybrid Cable Connecting AKD-N Axis Module to AKD-N Axis Module

Part Number	Description
CCNNN1-025-xxmyy-00	Hybrid cable connecting AKD-N to AKD-N

Length definition: xx=meters, yy=centimeters



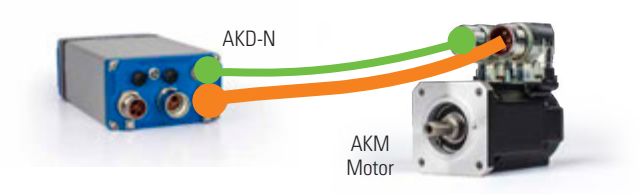
Hybrid Cable Connecting AKD-N Axis Module to AKM Motor

Part Number	Description
CCJNA3-015-xxmyy-00	Hybrid cable connecting AKD-N to AKM1 (SFD GEN3, Single-turn/Multi-turn HiPerFace DSL)
CCJNA2-015-xxmyy-00	Hybrid cable connecting AKD-N to AKM2-8 (SFD GEN3, Single-turn/Multi-turn HiPerFace DSL)

Length definition: xx=meters, yy=centimeters

Complete AKD-N Performance cable nomenclature can be found on page 191.

Performance Cables for AKD®-N-DF/DS to AKM® Motor



Motor	Connector	Power Cable	Power Cable with Brake	SFD
AKM < 6 A	y-tec	CM0NA3	CM1NA3	CFSNA3
	Dual Interconnect	CM0NA2	CM1NA2	CFSNA2

CAN bus cable

Configured CAN bus cables for AKD-xyyyzz-xxCN and AKD-xyyyzz-xxCC.

Part Number	Description
CBP000-002-m15-00	CAN bus cable 0.15 m
CBP000-002-m30-00	CAN bus cable 0.30 m
CBP000-002-001-00	CAN bus cable 1.00 m
CBP000-002-003-00	CAN bus cable 3.00 m

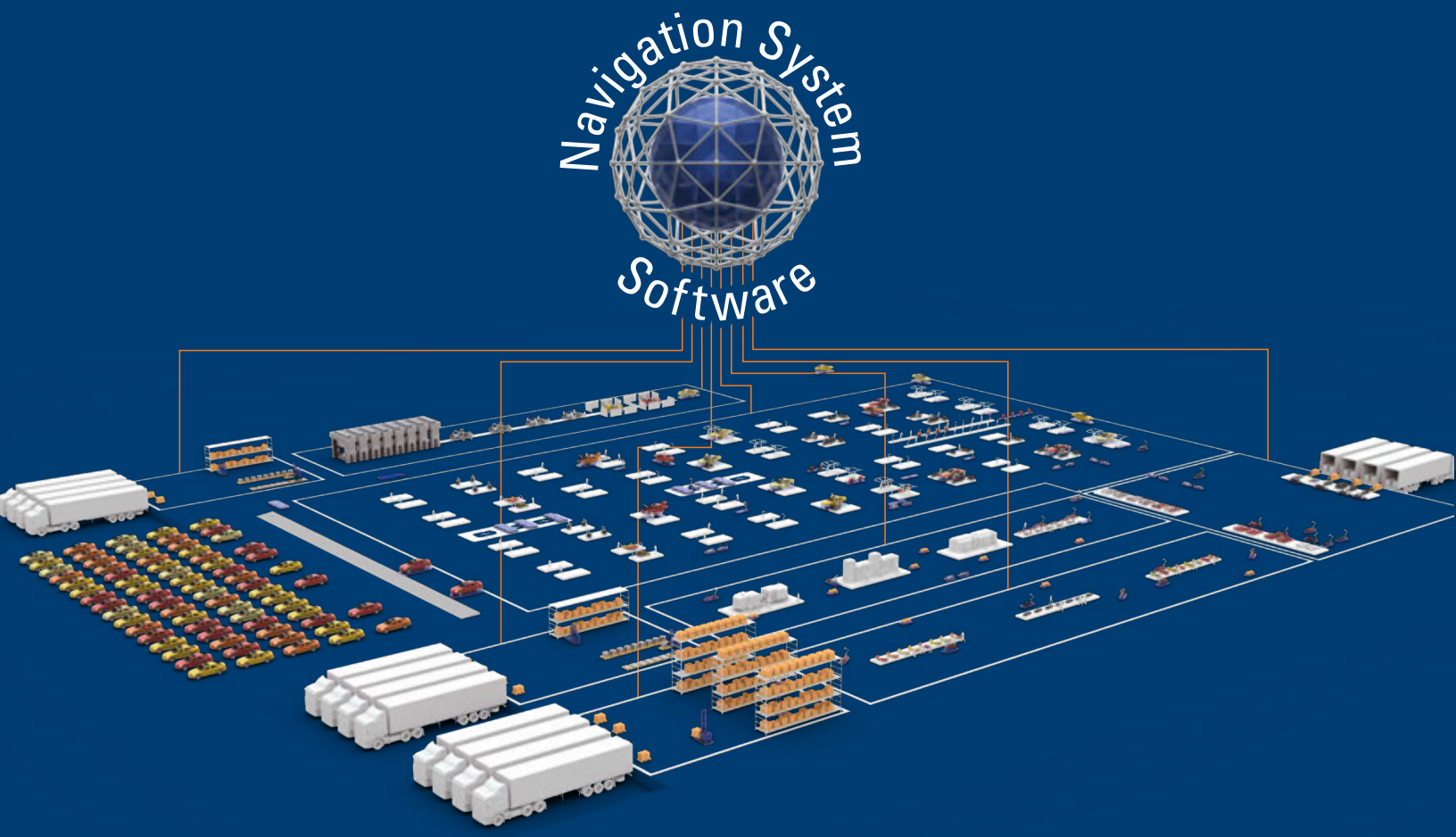
The CAN Termination connector is required for bus termination of the last AKD connected to the CAN bus. For connecting an AKD to a CAN device with SubD9 connector the CAN RJ12-SubD9 adapter can be used.

Part Number	Description
AKD-CAN-Termination	CAN Termination connector
AKD-CAN-RJ12-SubD9	CAN RJ12->SubD9 adapter

Vehicle Automation

Kollmorgen is a world-leading provider of vehicle automation kits. We combine a complete range of hardware, software and navigation technologies with vast knowledge and experience. We have a long and successful history in this field and can provide you with everything you need for excellent vehicle control independent of application. The result is lower total costs – for you and your customers.

Turn to us when you want to create vehicle solutions that give you a competitive advantage in the marketplace.



Benefits	Features
• Lowest total cost for partners	• No need to develop your own controls • More time to focus on end-user application • Proven and flexible concept • Works for all applications in all segments • Support in the sales process • Access to value-adding services
• Lowest total cost for end-users	• Customized application • Easy to integrate with other systems • Easy to operate, maintain and update • High availability – 24/7 operation

NDC AGV Navigation Solutions

Powerful Software Solutions for Efficient Design and Service

NDC8 gives you access to a set of efficient design and service tools. The design tools help you outline a wide variety of layouts as well as system and vehicle applications. Service tools include vehicle maintenance (e.g. fault-tracing, statistics and software downloads) and automatic surveying of the environment.

Service tools

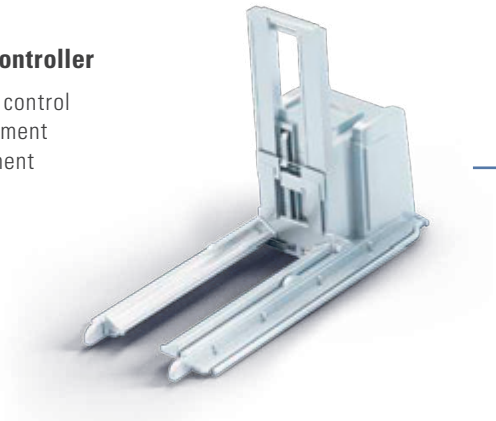
Vehicle maintenance
Vehicle diagnostics

Host

(ERP/MES/WMS)
Not offered by Kollmorgen

Vehicle system controller

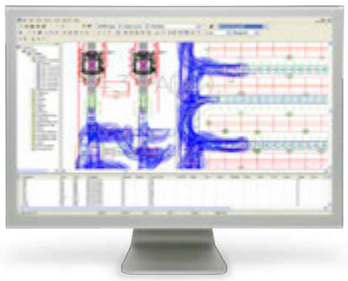
Transport flow control
Traffic management
Fleet management



Vehicles

Navigation
Steer/drive control
Load handling

Operator interfaces



Design tools

Layout
Applications

Robust and Reliable Vehicle Hardware

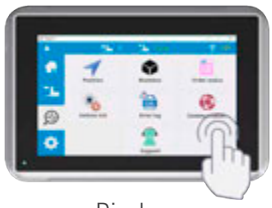
The different platforms in NDC8 use the same vehicle hardware. The hardware consists of powerful and reliable components in a number of areas. All components are designed for tough environments where vibrations, dust, moisture and temperature variations are all part of daily life.

Safety sensors*

Navigation sensors

Vehicle I/O*

Vehicle controllers



Displays

Drives

Encoders*

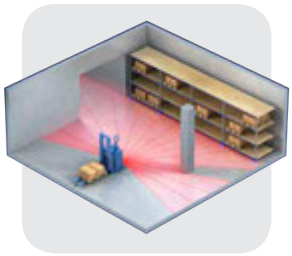
Manual control device

* Encoders, Vehicle I/O and Safety sensors are not offered by Kollmorgen.

NDC AGV Navigation Solutions

Navigation Technologies

NDC8 works with all established navigation technologies. What's more, there is also support for a combination of technologies, such as multi-navigation. Multi-navigation allows you to serve a storage space using one type of navigation and a production area using another.



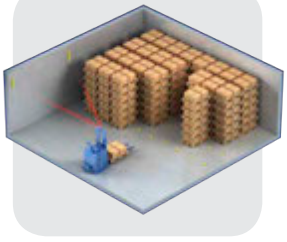
Natural

Reflector

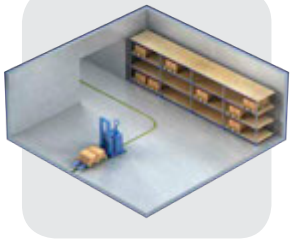
Spot

Magnetic tape

Bar Code



Multi-navigation



Inductive wire

Kollmorgen - A Partner You Can Trust

With an installed base of 25,000 vehicles, Kollmorgen is the number one provider of vehicle automation kits.

World's first automobile production plant with driverless vehicles
Volvo, Sweden, 1972

World's first laser-guided vehicle
Tetra Pak, Singapore, 1990

World's first Pick-n-Go system
Marktkauf, Germany, 2007

World's first driverless vehicle with 16 controlled wheels,
Posco Steel, South Korea, 2009

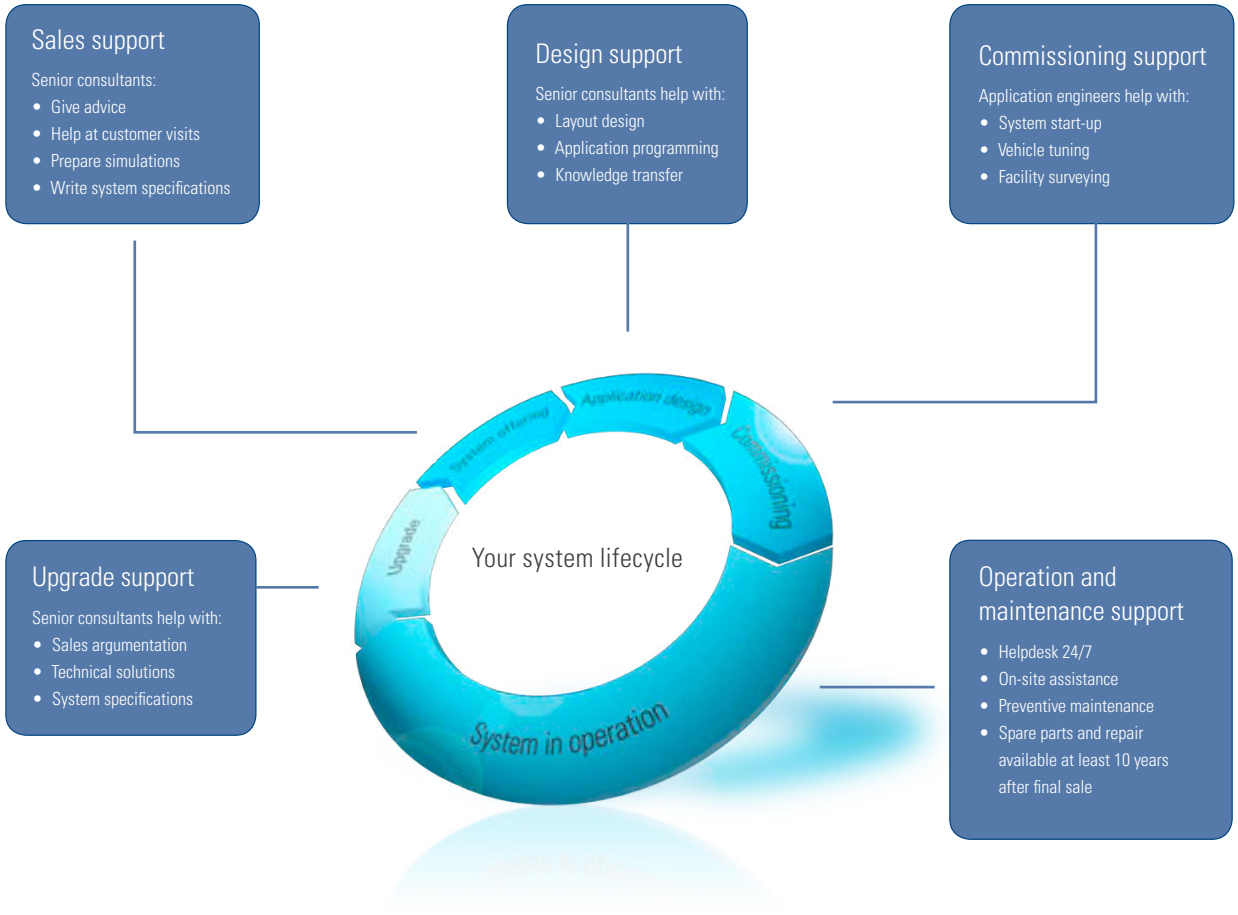
Services that Last a Lifetime

The end-users require high uptime, efficient daily operations and applications that are easy to change. We help you meet these demands with both technology and services.

Our services portfolio consists of:

- Training services that quickly make you an NDC8 expert. We offer basic, advanced and tailor-made courses, either at our training facilities or at your site. Internet-based training is also available.
- Support services where we give answers and solutions to your requests.
- Consulting services where our senior consultants help you in the sales and design process.

The illustration shows how we support you throughout the lifecycle of your system.



Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

Kollmorgen 2G Cables

H2 – 12 – 015 – A1 – 00 – XXXX00

Cable Version

Cable Jacket Material – PUR

F1	Mid-flex Feedback Cable PUR
H2	Mid-flex Hybrid PUR with brake
P1	Power Cable PUR
P2	Power Cable PUR with brake

Cable Jacket Material – PVC

F5	MId-flex Feedback Cable PVC
H6	Mid-flex Hybrid PVC with brake
P5	Mid-flex Power Cable PVC
P6	Mid-flex Power Cable PVC with brake

Length (no less than 100 mm increments)

xxxx00	Length in mm
	Standard lengths: 1 - 25 m
	Example: 6 m cable = 006000
	25 m cable = 025000

Options

00	Standard Option Set
XX	Specials (excluding standard option set)

Connector Type

If Feedback, connector type [connector type and pinout]

10	AKD, AKD2G, 15 Pin D-Sub, 45° angle, Resolver
12	AKD, AKD2G, 15 Pin D-Sub, 45 degree angle, EnDat® 2.1, BiSS B
14	AKD, AKD2G, 15 Pin D-sub, 45 degree angle, HIPERFACE®
18	AKD, AKD2G, 15 Pin D-sub, 45 degree angle, SFDG2
20	AKD, AKD2G, 15 Pin D-sub, 45 degree angle, Comcoder, Sine Enc. w/ Halls
41	S300/S700 Resolver 9 pin D-sub
42	S300/S700 Encoder 15 pin D-sub (EnDat® 2.2, Biss C)
43	S300/S700 Encoder 15 pin D-sub (Sine Encoder w Halls)
91	Flying leads, Resolver
92	Flying leads, EnDat, Biss
93	Flying leads, HIPERFACE
94	Flying leads, SFD2G
95	Flying leads, Comcoder

If Power or Hybrid drive connector type

11	AKD-x00306, -x00606 (Power and Hybrids with HDSL, SFD3)
12	AKD-x01206, -x02406 (Power and Hybrids with HDSL, SFD3)
	AKD-x00307, -x00607, -x01207, -x02407 (Power and Hybrids with HDSL, SFD3)
13	AKD-x04807 (Power and Hybrids with HDSL, SFD3)
14	AKD-x00306, -x00606 (Hybrids with EnDat 2.2)
15	AKD-x01206, -x02406 (Hybrids with EnDat 2.2)
	AKD-x00307, -x00607, -x01207, -x02407 (Hybrids with EnDat 2.2)
21	AKD2G-x00306, -x00606, -x01206
	AKD2G-x00307, -x00607, -x01207, -x02406, -x02407
33	AKD-N DB (Hybrid cable)
34	AKD-N DF/DS (Power cable)
41	S300 MV (Power or Hybrid w/ SFDG3, DSL)
42	S300 HV (Power or Hybrid w/ SFDG3, DSL)
43	S300 MV (Hybrid with EnDat 2.2-22)
44	S300 HV (Hybrid with EnDat 2.2-22)
46	S701-S724 connector (Power or Hybrid w/ SFDG3, HDSL)
47	S701-S724 connector (Hybrid with EnDat 2.2-22)
48	S748/S772 flying leads
01	Unterminated flying leads
SP	Special

Motor Mating Connector Type

Hybrid / Power Connectors

A1	AKM2G, M23 SpeedTec® (9)
A4	AKM2G, M40 SpeedTec (9)
A5	AKM1G, M23 SpeedTec (8)
A6	AKM1G, M23 Screw-type (8)
A7	AKM1G, M40 SpeedTec (6)
B1	AKM2G, M23 htec (9) standard keying, DSL)
B2	AKM2G, M23 htec (13) (rotated keying, EnDat 2.2)
B3	AKM2G, M40 htec (11) (standard keying, DSL)
C1	AKM/AKM2G, M15 ytec® (9)
C4	AKM, M15 itec (9) (SFD3)
UB	Unterminated (Blunt Cut)
UF	Unterminated (Flying leads)
W5	AKM, M23 Hummel Washdown (8)

Feedback Connectors

A2	AKM/AKM2G, M23 SpeedTec (12)
A3	AKM/AKM2G, M23 SpeedTec (17)
C2	AKM/AKM2G, M15 ytec (12)
C3	AKM/AKM2G, M15 ytec (15)
UB	Unterminated (Blunt cut)
UF	Unterminated (flying leads)

Cable Type

If Feedback, type [cable construction, not pinout]

FB1	4 Conductor
FB2	8 Conductor
FB3	6 Conductor
FB4	16 Conductor
FB5	14 Conductor
FB6	10 Conductor
FB7	12 Conductor

If Power or Hybrid drive connector type

005	0.5 mm^2
007	0.75 mm^2
010	1.0 mm^2
015	1.5 mm^2
025	2.5 mm^2
040	4.0 mm^2
060	6.0 mm^2
100	10.0 mm^2

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

AKD® Drive Performance and Value Line Cables

Feedback Cables

CF – D A 03 74N – XXX

Cable Type

CF = Performance Line
VF = Value Line

Feedback Type

D = SFD
H = HIPERFACE®
S = Sine Encoder

Feedback Drive Connector

A = Size 1.0, 12-pin (SFD or Resolver)
B = Size 1.0, 17-pin (Encoder)

Cable Length

Length in meters

Feedback Motor Connector

03 = 4 conductor (SFD) (Performance Line)
04 = 4 conductor (SFD) (Value Line)

Power Cables

CP – 5 07 CD A N – XXX

Cable Type

CP = Performance Line
VP = Value Line Feedback

Drive Power Connector Type

07 = AKD, 1-12A (230V)
08 = AKD, 24A (230V) & 1-24A (480V)

Cable Length

Length in meters

Motor Power Connector Type

A = Size 1.0, 8 pin
B = Size 1.5, 8 pin

Power Cable Material Type

BE = 16 AWG, 4 conductor, Value Line
CD = 14/18 AWG, 6 conductor, brake, Performance
CE = 14 AWG, 4 conductor, Value Line
CF = 14/18 AWG, 6 conductor, brake, Value Line
DE = 12 AWG, 4 conductor, Value Line
DD = 12/18 AWG, 6 conductor, brake, Performance
DF = 12/18 AWG, 6 conductor, brake, Value Line
ED = 10/18 AWG, 6 conductor, brake, Value Line

Hybrid (Power + Feedback) Cables

Refer to the AKD Drive Cables (Centralized) nomenclature page

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

AKD® Drive Cables (Centralized)

CC J 1 A2 – 015 – 003 – 00

Cable Version

Power
- CM Motor power
- WM Washdown motor power

Feedback
- CF Motor Feedback
- WF Washdown motor feedback

Hybrid (Power + Feedback)
- CC Motor hybrid
- WC Washdown motor hybrid

Fieldbus
- CB Motor hybrid
- WB Washdown motor hybrid

Cable Type

Power
- 0 No Brake
- 1 Brake

Feedback
- C Commutating Encoder
- D EnDat/BiSS digital
- E EnDat®/BiSS
- H HIPERFACE®
- R Resolver
- S SFD

Hybrid (Power + Feedback)
- S SDF + power
- J SDF3/DSL + power and brake

Fieldbus
- P CANopen®

Drive Connector Type

- X No connector (cut off)

Power / Hybrid (Power + Feedback)
- 1 AKD-x00306, -x00606
- 2 AKD-x01206, -x02406, -x00307, -x02407
- 3 AKD-x04807

Feedback
- 0 AKD X10
- 1 AKD X9

Fieldbus
- 0 AKD

Motor Connector Type

- XX No connector (cut off)
- 00 Special connector

Power
- A1 AKM & C/CH connector 1.0
- A2 AKM SpeedTec® 1.0
- A3 AKM itec connector
- A4 AKM molex, 10 pin
- A5 AKM connector 1.5, 8 pin
- A6 AKM molex, 5 pins
- A7 AKM molex, 8 pins
- AK AKM terminal box
- DL Linear motors

Feedback
- A1 AKM & C/CH connector 1.0
- A2 AKM SpeedTec® 1.0
- A3 AKM ytec® connector
- A4 AKM molex, 10 pins
- A5 AKM molex 18 pins
- DL Linear motors
- E1 EnDat ext.
- E2 HIPERFACE ext.

Hybrid (Power + Feedback)
- A1 AKM & C/CH connector 1.0
- A2 AKM SpeedTec® 1.0
- A3 AKM itec connector
- A4 AKM molex, 10 pin
- A5 AKM connector 1.5, 8 pin

Fieldbus
- 00 Specific for fieldbus

Cable Length

Length in meters
Standard lengths:

m25	0.25 m
m50	0.50 m
001	1 m
003	3 m
006	6 m
012	12 m
024	24 m

Wire Cross Section

Power

010	1.0 mm^2
015	1.5 mm^2
025	2.5 mm^2
040	4.0 mm^2
060	6.0 mm^2
100	10.0 mm^2
160	16.0 mm^2
250	25.0 mm^2

Feedback
- 002 0.25 mm^2

Fieldbus
- 002 0.25 mm^2

Specials

- 00 = Cardboard packing
- 01 = Foil packing

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

AKD®-N Cables (Decentralized)

CC N C N1 – 025 – 05M00 – 00

Cable Version

Power
- CM Motor power
- WM Washdown motor power

Feedback
- CF Motor Feedback
- WF Washdown motor feedback

Hybrid (Power + Feedback)
- CC Motor hybrid
- WC Washdown motor hybrid

Cable Type

Power
- 0 No Brake
- 1 Brake

Feedback
- C Commutating Encoder
- D EnDat/BiSS digital
- E EnDat®/BiSS
- H HIPERFACE®
- S SFD

Hybrid (Power + Feedback)
- S SDF + power
- J SDF3/DSL + power and brake
- N EtherCAT® + power

Drive Connector Type

Power
- N AKD-N (DF/DS)

Feedback
- N AKD-N (DF/DS)

Hybrid (Power + Feedback)
- C AKD-C
- N AKD-N

Motor Connector Type

- XX No connector (cut off)
- 00 Special connector

Power
- A1 AKM & C/CH connector 1.0
- A2 AKM SpeedTec® 1.0
- A3 AKM ytec® connector
- DL Linear motors

Feedback
- A1 AKM & C/CH connector 1.0
- D AKM SpeedTec® 1.0
- E AKM ytec® connector
- DL Linear motors
- E1 EnDat ext.
- E2 HIPERFACE ext.

Hybrid (Power + Feedback)
- A1 AKM & C/CH connector 1.0
- A2 AKM SpeedTec® 1.0
- A3 AKM itec connector
- N1 AKD-N

Wire Cross Section

Power
- 010 1.0 mm^2
- 015 1.5 mm^2
- 025 2.5 mm^2

Feedback
- 002 0.25 mm^2

Hybrid (Power + Feedback)
- 010 1.0 mm^2
- 015 1.5 mm^2
- 025 2.5 mm^2

Cable Length

XXMYY where:
- XX meters
- YY centimeters

according to allowed steps (see accessories manual)

Specials

00 = Cardboard packing
01 = Foil packing

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

AKD® Servo Drive Family

AKD – B 003 06 – NB AN – 0000

AKD Series

Version

B = Base drive
P = Position indexer (motion tasking)
T = AKD BASIC Language Programmable drive (Requires IC or NB Extention)
M = Multi-axis Master Drive (Requires MC Extension option, and EC Connectivity option)

Current Rating

003 = 3 Amp
006 = 6 Amp
012 = 12 Amp
024 = 24 Amp
048 = 48 Amp

Voltage

06 = 120/240 Vac 1Ø/3Ø (24 Amp Drive: 240 Vac 3Ø only)
07 = 240/480 Vac 3Ø

Variants

0000 = Standard

Connectivity*

	Drive Version Availability
AN = Analog command	B, P, T
CN = CANopen®	P
EC = EtherCAT®	M, P
EI = EtherNet/IP™	P
PN - PROFINET®	P
SQ = SynqNet®	B

*Motion Tasking is included as a free upgrade with CN, EC, EI and PN

Extension

IC = Expanded I/O version and SD card slot (AKD-T version only)
NB = Without extensions

AKD – C 010 07 – CB EC – E000

AKD Series

Version

C Central Power Supply IP20

Power Class

010 10 kW (17 kW @ 570 V DC)

Voltage Class

07 400 to 480 V AC, 3-ph

Customization

x000 Standard (x = language)

Connection Option

EC EtherCAT

Expansions

CB No expansion

AKD – N 003 07 – DB EC – E000

AKD Series

Version

N Near servo drive IP65/67

Current Class

003 3 Arms
006 6 Arms
012 12 Arms

Voltage Class

07 700 V DC

Customization

x000 Standard (x = language)

Connection Option

EC EtherCAT

Expansions

DB Hybrid motor cable
DF Feedback connector and tertiary fieldbus
DG Hybrid motor cable and tertiary fieldbus
DS Feedback connector and individual STO
DT Hybrid motor cable and individual STO

Note: Options in blue type refer to standard products.

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

AKD®2G Servo Drive

AKD2G – S P E – 7V 06 S – A 1 F3 – 0000 – A

AKD2G Series
AKD 2nd Generation

Format
S = Servo IP20

Drive Version
P = Position Indexer with motion tasks

Connectivity Options
N = Analog
E = EtherCAT®
C = CANopen

Voltage
6V = 120/240 Vac 1Ø/3Ø
7V = 240/480 Vac 3Ø

Current Rating
003 = 3 Amp
006 = 6 Amp
012 = 12 Amp

Axis Count
S = Single Axis
D = Dual Axis

Platform Revision
A = MAP Revision A

Functional Safety*
1 = STO, dual channel (SIL2, PLd)
2 = STO, SS1, SDB, SBC/SBT, FSoE (SIL3/PLe)

Options
00 = Standard
F3 = X23 (Feedback 3)
IO = X22 (I/O)
DX = X22+X23

Customization
0000 = Standard

Connectors
A = with connectors
(except X1/X2 and X23)

*Functional Safety certifications are planned to be completed by March 2020. Consult factory on certification status.

Note: Options shown in blue text are considered standard.

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

AKM® Brushless Servo Motor

AKM 6 2 P – A N C N DA 00

AKM Series

Flange Size

1	40 mm
2	58 mm
3	70 mm
4	84 mm
5	108 mm
6	138 mm
7	188 mm
8	260 mm

Rotor Length

1
2
3
4
5

Winding Type

A to Z

S	Special

Flange

A	IEC with tolerance N
B	NEMA
C	Alternative IEC standard
D	Other standard
G	Alternative IEC standard
H	Alternative IEC standard
R	IEC with tolerance R
M, T	Reinforced bearing AKM8
W	Flange coating for Washdown, IEC
S	Special

Version

00	Standard motor without shaft seal
01	With shaft seal
0W	Washdown
0F	Washdown Food
FAN	Fan Option for AKM7 only
xx	Special

Feedback Device

For all options see following page

S	Special

Brake

2	24 V holding brake
N	Without brake
S	Special

Connections

For all options see following page

S	Special

Shaft

C	Keyway
K	Open keyway
N	Smooth shaft
S	Special

Note: Options shown in blue text are considered standard.

Note: Options in blue type refer to standard products.

Feedback Unit Options

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

Code	Designation	Model	Can be used with	Connection Option	Comment
1-	Comcoder		AKM1 - AKM8	1, 2, 7, B, C, G, H, T	1024 incr./rev
2-	Comcoder		AKM1 -AKM8	1, 2, 7, B, C, G, H, T	2048 incr./rev
AA	BiSS B encoder	AD36	AKM2 - AKM4	1, 7, B, C, M	Single-turn, optical
AA	BiSS B encoder	AD58	AKM5 - AKM8	1, 2, C, G, H, M, T	Single-turn, optical
AB	BiSS B encoder	AD36	AKM2 - AKM4	1,7,B, C, M	Multi-turn, optical
AB	BiSS B encoder	AD58	AKM5 - AKM8	1, 2, C, G, H, M, T	Multi-turn, optical
C-	Smart Feedback Device SFD	Size 10	AKM1	1, D, Y, M, P	Single-turn 4-wire
C-	Smart Feedback Device SFD	Size 15	AKM2 - AKM4	1, D, Y, M, P	Single-turn 4-wire
C-	Smart Feedback Device SFD	Size 21	AKM5- AKM8	1, D, Y, M, P	Single-turn 4-wire
CA	Smart Feedback Device SFD3		AKM1 - AKM6	D	Single-turn 2-wire
DA	EnDAT® 2.1 encoder	ECN 1113	AKM2 - AKM4	1, 7, B, C, M	Single-turn. optical
DA	EnDAT 2.1 encoder	ECN 1313	AKM5 - AKM8	1, 2, C, G, H, M, T	Single-turn, optical
DB	EnDAT 2.1 encoder	EQN 1125	AKM2 - AKM4	1, 7, B, C, M	Multi-turn, optical
DB	EnDAT 2.1 encoder	EQN 1325	AKM5 - AKM8	1, 2, C, G, H, M, T	Multi-turn, optical
EF	Comcoder		AKM2 - AKM8	B,C,G,H,M,T	2000 incr./rev
EG	Comcoder		AKM2 - AKM8	B,C,G,H,M,T	2500 incr./rev
EH	Comcoder		AKM2 - AKM8	B,C,G,H,M,T	5000 incr./rev
EJ	Comcoder		AKM3 - AKM8	B,C,G,H,M,T	10,000 incr./rev
EM	Comcoder		AKM2 - AKM8	B,C,G,H,M,T	4096 incr./rev
EN	Comcoder		AKM3 - AKM8	B,C,G,H,M,T	8192 incr./rev
LA	EnDAT 2.1 encoder	ECI 1118	AKM2 - AKM3	1, 7, B , C, M	Single-turn, inductive
LA	EnDAT 2.1 encoder	ECI 1319	AKM4 - AKM8	1, 2, C, G, H, M, T	Single-turn, inductive
LB	EnDAT 2.1 encoder	ECI 1130	AKM2 - AKM3	1,7, B, C, M	Multi-turn, inductive
LB	EnDAT 2.1 encoder	ECI 1331	AKM4 - AKM8	1, 2, C, G, H, M, T	Multi-turn, inductive
GA	HIPERFACE® encoder	SKS36	AKM2 - AKM8	B,C,G	Single-turn, optical
GB	HIPERFACE encoder	SKS36	AKM2 - AKM8	B,C,G	Multi-turn, optical
GJ	HIPERFACE encoder	SKS36	AKM2 - AKM8	1,2,7, B, C, G, H, M, T	Single-turn, optical
GK	HIPERFACE encoder	SKM36	AKM2 - AKM8	1,2,7, B, C, G, H, M, T	Multi-turn, optical
GP	HIPERFACE encoder	SEK34	AKM1	1, Y, M	Single-turn, capacitive
GR	HIPERFACE encoder	SEL34	AKM1	1, Y, M	Multi-turn, capacitive
GE	HIPERFACE DSL® encoder	EKS36	AKM2 - AKM8	D	Single-turn, optical
GF	HIPERFACE DSL encoder	EKM36	AKM2 - AKM8	D	Multi-turn, optical
GM	Safety HIPERFACE	SKS36S	AKM2 - AKM8	1, 2, 7, B, C, G, H, M, T	Single-turn, optical
GN	Safety HIPERFACE	SKM36S	AKM2 - AKM8	1, 2, 7, B, C, G, H, M, T	Multi-turn, optical
MA	Drive Cliq	ECN1324S	AKM4 - AKM8		Single-turn, optical
MB	Drive Cliq	EQN1336S	AKM4 - AKM8	tba	Multi-turn, optical
R-	Resolvers	Size 10	AKM1	1,2,7, B, C, G, H, M, T, Y	2-pin, hollow shaft
R-	Resolvers	Size 15	AKM2 - AKM4	1,2,7, B, C, G, H, M, T, Y	2-pin, hollow shaft
R-	Resolvers	Size 21	AKM5 - AKM8	1,2,7, B, C, G, H, M, T, Y	2-pin, hollow shaft

* not available for AKM2 with connection option C (cable with IP65 connector)

Connector Options

Code		Can be used with	Protection class	Connection type	Description
With PTC	With KTY 84-130				
B	1	AKM2	IP65	2 threaded connectors, size 1.0	Angled, rotatable, mounted on motor
C	7	AKM1 - AKM2	IP65	2 threaded connectors, size 1.0	On 0.5 m cable
C	1	AKM3	IP65	2 threaded connectors, size 1.0	Angled, rotatable, mounted on motor
C	1	AKM4 - AKM7	IP65	2 SpeedTec® Ready connectors, size 1.0	Angled, rotatable, mounted on motor
–	D	AKM1	IP65	1 hybrid itec® connector	Mounted on motor
–	D	AKM2 - AKM6	IP65	1 hybrid threaded connector, size 1.0	Angled, rotatable, mounted on motor
G	–	AKM2 - AKM3	IP67	2 threaded connectors, size 1.0	Straight, mounted on motor
G	–	AKM4 - AKM6	IP67	2 SpeedTec Ready connectors, size 1.0	Straight, mounted on motor
H	1	AKM74Q and AKM82T	IP65	1 feedback threaded connector, size 1.0 1 power threaded connector, size 1.5	Angled, rotatable, mounted on motor
M	–	AKM1 - AKM4	IP20	2 Molex connectors, $I_0 < 6$ A	On 0.5 m cable
P	–	AKM1 - AKM4	IP20	1 Molex connector, $I_0 < 6$ A	On 0.5 m cable
R	–	AKM4 - AKM7	IP65	1 feedback threaded connector M12 1 power connector SpeedTec-Ready M23	Straight, mounted on motor Angled, mounted on motor
T	2	AKM8	IP65	1 terminal box IP65 for power 1 Feedback threaded connector, size 1.0	Mounted on motor
Y	1	AKM1	IP65	1 ytec® connector	Mounted on motor

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

AKM®2G Brushless Servo Motor

AKM2G – 6 2 A – A N C N DA 0 0

AKM2G Series

Flange Size

2	58mm
3	72 mm
4	88 mm
5	114 mm
6	142 mm
7	192 mm

Rotor Length

1
2
3
4
5

Winding Type

A to Z

ML, PL	Low-voltage options
S	Special

Mount

A	IEC with accuracy N

Shaft

C	Keyway
N	Smooth shaft
S	Special

Customization

0	Standard
T	Mineral filled PTFE seal (Teflon®)
V	Viton® shaft seal
x	Special

Thermal Sensor

0	PT-1000 + PTC
1	PT-1000
2	PTC
3	KTY84-130 Equivalent
S	Special

Feedback Device

For all options see following page

S	Special

Brake

2	24 V holding brake
N	Without brake
S	Special

Connections

For all options see following page

S	Special

Note: Options shown in blue text are considered standard.

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

Feedback Unit Options

Code	Description	Connector Type	Compatible AKM2Gx	Size	Motor ID Support[3]	Accuracy[1,2] (arc-sec)	RMS Noise[1] (arc-sec)	Resolution	Absolute revs.	Compatible Drives
2-	Commutating Encoder	C,G	AKM2G3 LV	15	No	±218.2"	N/A	12 bits	None	AKD/AKD2G
CA	SFD3	D	AKM2G2-4	15	Yes	±585"	±9.9"	24 bits	1	AKD/AKD2G
		D	AKM2G5-7 > 20A	21						
		J	AKM2G7 > 20A	21						
GU	HIPERFACE DSL®	C,G	AKM2G3 LV	EEM37	Yes	±240"	±20"	17 bits	4096	AKD/AKD2G
		D	AKM2G2-7 ≤ 20A							
		J	AKM2G7 > 20A							
LD	EnDat® 2.2	C,G	AKM2G3 LV	EQI 1131	Yes	±120"	See Note 4	19 bits	4096	AKD/AKD2G
		D	AKM2G2-4							
		H	AKM2G7 ≤ 20A			±65"				
R-	Resolver	Y	AKM2G2	15	No	±540"	N/A	24 bits for AKD/AKD2G	1	All
		C/G	AKM2G3-4							
		C/G	AKM2G5-7 ≤ 20A	21						
		H	AKM2G7 > 20A							

Note 1: AKD/AKD2G drives have a resolver measurement accuracy of ±45", for a drive w/ motor accuracy of ±585" and RMS Noise of ±9.9".
Note 2: Accuracy refers to overall system accuracy once installed in the motor. Noise refers to the RMS position noise when at stand-still.
Note 3: Motor ID support means electronic motor nameplate data is included, allowing for plug-and-play commissioning.
Note 4: At the time of printing, this information was not available. Please contact Kollmorgen Customer Support for the latest update.
With AKD and AKD2G drives, all received positions are interpolated to a 32-bit resolution per revolution.

Connector Options

Model Designation	Connection	Compatible AKM2Gx	Position of connection
C	2 SpeedTec® M23	AKM2G3 - AKM2G7 ≤ 20 Amps	Angular, rotatable, motor mounted
D*	1 htec® M23	AKM2G2 - AKM2G7 ≤ 20 Amps	Angular, rotatable, motor mounted
G	2 SpeedTec® M23	AKM2G3 - AKM2G7 ≤ 20 Amps	Straight, motor mounted
H	1 M40 Power, 1 M23 Feedback	AKM2G7 > 20 Amps	Angular, rotatable, motor mounted
J*	1 htec® Connector M40	AKM2G7 > 20 Amps	Angular, rotatable, motor mounted
Y	1 ytec® Connector	AKM2G2	Rotatable, motor mounted

* Hybrid connectors valid for SFD3, DSL, and EnDat Feedback only.

Connector Description

Connector	Usage	Contacts - Pins Power/Signal	Max. Current [A] Power/Signal	Max. Cross Section [mm²] Power/Signal	Protection Class
M23 SpeedTec® right angle connectors (Size 1)	Power & Brake	4 / 5	20 / 10	4 / 1.5	IP65
	Resolver	- / 12	- / 10	- / 0.5	IP65
	DSL	5 / 2 / 2	20 / 10	4 / 1.5	IP65
	SFD3	4 / 5	20 / 10	4 / 1.5	IP65
	EnDat	5 / 4 / 6	20 / 10	4 / 1.5	IP65
M40 (Size 1.5)	Power & Brake	4 / 5	75 / 30	16 / 4	IP65
	SFD3	4 / 5	75 / 30	16 / 4	IP65
	DSL	5 / 4 / 2	75 / 30	16 / 4	IP65
ytec®	Power & Brake	4 / 5	14 / 3.6	1.5 / 0.75	IP65
	Resolver	- / 12	- / 5	- / 0.75	IP65

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

AKMH™ Brushless Servo Motor

AKMH 4 2 E – AN K N CA 1 K

AKMH Series
AKMH Hygienic Stainless Steel Washdown Motor

Motor Frame Size
2, 3, 4, 5, 6

Rotor Stack Length
1, 2, 3, 4, 5

Winding Type
A, B, C, D, etc.
S = Special

Mount
A = Flange mounting IEC
B, E = Flange mounting NEMA
C = Face mounting IEC
D = Face mounting NEMA
L = NEMA 56 face mount

Shaft
C = Closed keyway
K = Open keyway
N = Smooth shaft

Seal
K = IP69K shaft seal

Cable Length
1 to F (1 to 15 meters)

Brake ❶
2 = 24 V DC holding brake
N = No brake
S = Special

Feedback Device ❶ ❷
2- = Comcoder 2048 incr./rev
C- = SFD2
CA = Smart Feedback Device (SFD3)
DA = EnDAT 2.1 single-turn, optical
DB = EnDAT 2.1 multi-turn, optical
GA = Hiperface SKS36 single-turn
GB = Hiperface SKM36 multi-turn
GE = Hiperface DSL encoder single-turn
GF = Hiperface DSL encoder multi-turn
LA = EnDAT 2.1 single-turn, inductive
LB = EnDAT 2.1 multi-turn, inductive
R = Resolver
RA = Single-turn absolute HIPERFACE SRS50-S21 encoder
RB = Multi-turn absolute HIPERFACE SRM-S21 encoder)
RC = single-turn absolute HIPERFACE SRS50-K21 encoder
RD = multi-turn absolute HIPERFACE SRM50-K21 encoder
RE = HIPERFACE DSL Absolute Encoder
RF = HIPERFACE DSL Absolute Encoder
RG = HIPERFACE DSL Absolute Encoder
RH = HIPERFACE DSL Absolute Encoder

Mount-Shaft Availability

Base Model	Mount-Shaft									
	AC	AN	BK	BN	CC	CN	DK	DN	EK	EN	LK
AKMH2x	•	•		•	•	•		•			
AKMH3x	•	•		•	•						
AKMH4x	•	•	•	•	•	•	•	•	•	•	
AKMH5x	•	•	•	•	•	•	•	•	•	•	
AKMH6x	•	•			•	•	•	•	•	•	

Note: LK mount requires 2 weeks additional lead time for the first product order.
Note: Ex mounts are only available if Rx feedback devices are selected.

Cable Connection
B = Cable with IP67 SpeedTec connector
C = Cable for connection to third-party drives
G = Cable with IP67 SpeedTec connector in silicone tube
K = Pre-assembled cable for connection to AKD
L = Dual-cable version with open cable ends
M = Dual-cable version with open cable ends in silicone tube
R = Dual cable with IP67 non-stainless steel, non-hygienic, vented connector with air pressure compensation
T = Pre-assembled cable in silicone tube for connection to AKD
V = Cable with IP69 SpeedTec connector
W = Cable with IP69 SpeedTec connector in silicone tube

Feedback and Connection Availability

Feedback Device	Cable Connection									
	K	T	B	G	V	W	L	M	R	C
C-, CA	•	•	•	•	•	•				
GE, GF	•	•	•	•	•	•				
2-, R-			•	•	•	•	•	•		
DA, DB			•	•	•	•	•	•		
GA, GB			•	•	•	•	•	•		
LA, LB			•	•	•	•	•	•		
RA, RB							•		•	
RC, RD							•		•	
RE, RF, RG, RH			•	•	•	•			•	•

❶ C- feedback is not available with brake.
❷ Rx feedback device options are mapped for connection to third-party servo drives

Note: Options in blue type refer to standard products.

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

Cartridge DDR Motor

C 09 1 A - 1 1 - 1 1 0 5 - xxx

Product Family
C = 230 Volt
CH = 400/480 Volt

Frame Size Field
04 = 4.25" Sq. Housing
05 = 5.43" Sq. Housing
06 = 7.40" Sq. Housing
09 = 9.68" Sq. Housing
13 = 13.78" Sq. Housing

Stack Length Field
1 = Short Stack
2 = Mid Stack
3 = Long Stack
4 = Extra Long Stack
(04 and 05 frame sizes only)

Winding Letter Field
A = Standard Winding
B = High-Speed Winding (C04x, C05x, C06x, C13x)
C = Standard Winding (C052, C062, C063, C092, C093, C13x)
D = High-Speed Winding (C052 only)

Mounting Option Field
1 = Std. Flange Mount

Connector Option Field
1 = Side Connector Option (09 and 13 frame sizes only)
2 = Rear Connector Option (09 and 13 frame sizes only)
3 = 90° Rotatable Connectors (04, 05 and 06 frame sizes only)

Sequential number for specials
(Unique description within a frame size)

Unit Seal Option Field
5 = Sealed
(Shaft Option "1" - IP64 Rating when customer seals interface side)
(Shaft Option "2" or "3" - IP65 Rating when customer seals interface side)

Bearing Option Field
0 = No Bearing Design
(Standard - Integral Shipping Clamp Provided)

Feedback Option Field
1 = EnDat single turn absolute sine encoder (2048 line)
3 = BiSS single turn absolute since encoder (2048 line)
4 = BiSS multi-turn absolute since encoder (2048 line)
5 = EnDat Multi-turn absolute since encoder (2048 line)

Shaft Field
1 = Hollow with Compression Coupling and Key
(09 and 13 frame sizes only)
2 = Solid with Compression Coupling and Key
(09 and 13 frame sizes only)
3 = Solid with Split Ring Coupling and no Key
(04, 05, and 06 frame sizes only)

Note: Options in blue type refer to standard products.

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

Housed DDR Motor

DH 08 1 M - 1 2 - 1 3 1 0 - xxx

Direct Drive Series
D = 115/230 VAC winding
DH = 400/480 VAC winding

Motor Frame Size
06 = 6.93" O.D.
08 = 8.60" O.D.
10 = 11.19" O.D.
14 = 14.25" O.D.

Rotor Stack Length
1 = Short stack
2 = Mid stack
3 = Long stack

Winding Type
A = Std. w/ resolver[1]
M = Std. w/ sine encoder

Mounting Option
1 = Face mount
2 = Flange mount

Designated for Specials

Unit Seal
0 = Non-sealed unit
5 = IP65[2] - length increase
7 = IP67[2] - length increase

Bearing Option
1 = Single bearing design
2 = Dual bearing design[3]

Feedback Device
2 = Resolver ("A" Winding Type)[1]
3 = Sine Encoder ("M" Winding Type)

Shaft Option
1= Straight thru bore w/ face coupling

Connector Type
2 = Straight
3 = 90°, rotatable

Notes:
1. Not available on D14x & DH14x.
2. Encoder sealed motors have increased length. See outline drawing.
3. Standard on D143 & DH143 models.
4. Options shown in blue text are considered standard.

Note: Options in type refer to standard products.

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

KBM Frameless Motor

KBM(S) - 25 H 01 - A XX

Product Family

KBM = Frameless motor
KBMS = Frameless motor with sensors

Motor Frame Size (Armature I.D.)

10	57
14	60
17	79
25	88
35	118
43	163
45	260

Insulation Ratings

H = High voltage insulation (>240 Vac), S = Low-Voltage insulation (≤ 240 Vac)
Note: H insulation is standard option for frame sizes 10, 14, 17, 25, 35 and 45.

Stack Length Specifier

00 = 0
01 = 1
02 = 2
03 = 3
04 = 4
05 = 5

Winding Options

(A, B, C, etc...)

Sequential Number for Available Modifications

TBM Frameless Motor

TBM(S) - 6013 - A00

Product Family

TBM = Frameless motor
TBMS = Frameless motor with Hall sensors

Motor Frame Size (Armature Outer Diameter)

60
76
129

Stack Length Specifier

Winding Options

A, B

Sequential Number for Available Modifications

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

Direct-Drive Linear Motor Coil Model Number Description

IL 06 030 A1 AC TR XX

Coil Type
IL = Ironless
ICD = Low Profile Ironcore
IC = Ironcore
ICH = Ironcore High Voltage

Coil Series
06 = 06 Series Ironless
12 = 12 Series Ironless
18 = 18 Series Ironless
24 = 24 Series Ironless
05 = 05 Series ICD
10 = 10 Series ICD
11 = 11 Series Ironcore
22 = 22 Series Ironcore
33 = 33 Series Ironcore
44 = 44 Series Ironcore

Magnetic Way Width (mm)
030 = 30 mm
050 = 50 mm
075 = 75 mm
100 = 100 mm
150 = 150 mm (IC/ICH only)
200 = 200 mm (IC/ICH only)
250 = 250 mm (ICH only)

Winding Code
A1
A2
A3
A4 — "Y" Windings
see performance specifications
A5
A6
A7
A8 — "Δ" Windings

Termination Option Px or Cx
Px = Cable with Connector:
Configuration (P1) includes 400 mm (16") shielded cable with connector.
P1 = 400 mm (16")
P2 = 200 mm (8")
P3 = 100 mm (4")
P4 = 1200 mm (48")
Cx = Motor cable and thermal cable with flying leads:
C1 = 400 mm (16")
C2 = 200 mm (8")
C3 = 100 mm (4")
C4 = 1200 mm (48")

Thermal Protection Option
TS = Thermostat (IC only)
TR = Thermistor
TY = Standard (both PTC and KTY84-130) (ICH only)

Cooling Option (IC Only)
AC - Integral Cooling
If No Cooling, leave blank

Ironless 6 Series motor coil, 30 mm width, A1 winding designation terminated with 16" cable with connector.

Direct-Drive Linear Motor Magnetic Way Model Number Description

MW 030 L 0128 001

Magnet Way Type
MW = Ironless
MCD = ICD
MC = Ironcore

Magnet Way Width (mm)
030 = 30mm
050 = 50mm
075 = 75mm
100 = 100mm
150 = 150mm (IC only)
200 = 200mm (IC only)

L = Low Profile
(30 & 50 mm Ironless only)
For standard Assemblies or Ironcore, leave blank.

Magnet Assembly Way Length (mm)
0064 = 64 mm
0128 = 128 mm
0256 = 256 mm
0512 = 512 mm

Magnet Way Cover (Ironcore only)
(Leave blank for Ironless or no cover)

Example: MW0300128
Ironless magnet way, 30 mm magnet width, 128 mm assembly length.

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

Direct-Drive Linear Motor Hall Effect Assembly Model Number Description

HDIL 100 XX

Hall Effect
HD = Digital for Ironcore High Voltage (NA)
HDIC = Digital for Ironcore (Microswitch SS461A)
HDIL = Digital for Ironless (Microswitch SS461A)

Winding Code
100 (A1, A2, A3, A4)
200 (A5, A6, A7, A8)
D = Delta Winding ICH in NA
Y = Y winding ICH in NA

Termination Option
Px - Cable with Connector:
Configuration (P1) includes 400 mm (16") shielded cable with connector.
(lengths as above)
Cx - flying leads (lengths as above)

Example: HDIL-100-P1
Hall effect assembly with digital outputs for Ironless motor terminated with 16" cable with connector.

Example: HD-Y-P1
Hall effect assembly with digital outputs for ironcore motor terminated with 16" cable with connector.

Direct-Drive Linear Motor High Flex Cable Numbering System

M1C – 01

High Flex Motor Cable
M = Motor

Wire Size
1C = 18 AWG for AKD 3/6 Amp amplifiers
2C = 14 AWG for AKD 12 Amp amplifiers *
3C = 12 AWG for AKD 24 Amp amplifiers *

Example: M1C - 06
High flex motor cable, terminated with connectors at motor and amplifier ends, 18 AWG, for 3 or 6 Amp AKD.

Length in meters
01 = 1 meter
03 = 3 meters
06 = 6 meters
09 = 9 meters
12 = 12 meters
15 = 15 meters

H1C – 01

High Flex Hall Effect Cable
H1C = Hall Effect

Example: H1C - 06
High flex Hall Effect cable, terminated with connectors at motor and amplifier ends.

Length in meters
01 = 1 meter
03 = 3 meters
06 = 6 meters
09 = 9 meters
12 = 12 meters
15 = 15 meters

T1C – 01

High Flex Thermal Cable
T1C = Thermal
T2C = Thermal (S300, S600)

Example: T1C - 06
High flex Thermal cable, terminated with connectors at motor and amplifier ends.

Length in meters
01 = 1 meter
03 = 3 meters
06 = 6 meters
09 = 9 meters
12 = 12 meters
15 = 15 meters

* For application assistance regarding cable selection for these and other higher current rated amplifiers, contact a Kollmorgen Customer Support representative.

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

P-Series Stepper Drive

P7 03 6 0 – SD N _

P-Series
P5 = P5000 Series
P6 = P6000 Series
P7 = P7000 Series

Current Rating
03 = 2.5 Arms continuous, 3.5 Arms peak (AC models only)
05 = 5 Arms continuous, 7.2 Arms peak (DC models only)
06 = 5.7 Arms Continuous, 8.0 Amps peak*

Voltage Range
3 = 20 - 75 Vdc
6 = 120/240 Vac (160/320 Vdc)

Electrical Options
0 = None

Customization
Omit field for standard configurations
000 = Optimized for Standard POWERPAC
001 = Optimized for Enhanced POWERPAC
PMX = Optimized Powermax Settings

Feedback Device
N = No feedback, with mating connectors (P6000)
O = No feedback, no connectors

Fuctionality
PN = Motion node indexing
SD = Step/direction base drive, Internal VCO (P5000)
R4 = RS485 (P70360 only)

PMX™ Series Stepper Motor

PMX 11 2 0 – A 1 O – B N 0 – 00

Motor Series

NEMA Motor Frame Size
08, 11, 14, 17, 23, 34

Rotor Stack Length

1 = 1 stack	All PMX series motors
2 = 2 stacks	All PMX series motors
3 = 3 stacks	PMX11, -17, -23, -34
4 = 4 stacks	PMX17, -23, -34
5 = 5 stacks	PMX17

Motor Winding

A, B, C, D	Bipolar windings
G, H, J	Unipolar or Bipolar windings

Step Angle

1 = 1.8°	All PMX series motors
9 = 0.9°	PMX17, PMX23

Rear Shaft Option

O = No rear shaft	All PMX series motors
R = Rear shaft	All PMX series motors
H = Rear shaft + encoder mounting holes	PMX14, -17, -23

Front Shaft Option

N = Normal/Smooth front shaft	All PMX
F = Flat front shaft	All PMX
K = Open keyway	PMX34

Connection/Hookup Option

B = 4 lead Bipolar	All PMX
U = 6 lead Unipolar	PMX17, -23
X = Integrated Connector	PMX17, -23

Note: Options in blue type refer to standard products.

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

CT Series Stepper Motor

CTM 2 1 N L F 10 N AA 00

CT Series
CTM = Cool torque maximum series
CTP = Cool torque performance series

Frame Size
1 = Size 17 / 4.2 cm (CTP only)
2 = Size 23 / 5.7 cm
3 = Size 34 / 8.5 cm

Length
0 = Short Stack (CTP only)
1 = 1 stack
2 = 2 stacks
3 = 3 stacks

Mounting
N = NEMA through holes (size 23 & 34 only)
E = English tapped holes (size 17 only)
M = Metric tapped holes (size 17 only)

Construction/Connection Style
L = Leads
S = Special

Number of Connections
F = Four
S = six

Customization
00 = Standard motor
Other numbers serially assigned for special motors

Rear Options
AA = None
EE = English rear shaft & encoder mouting holes (size 23 & 34 only)
MA = Metric rear shaft (size 17 only)
SS = Special

Front Shaft Options
N = Round smooth shaft (size 23 only)
F = Flat (size 23 only)
K = Straight keyway (size 34 only)
M = Metric (size 17 only)
S = Special

Winding Current
For 4 lead motors = Bipolar current x10
For 6 lead motors = Unipolar current x10
Examples:
05 = 0.5 Amps
10 = 1 Amp
50 = 5 Amps
00 = Special

Note: Options in blue type refer to standard products.

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

E & H Series Stepper Motor

E 3 3 H C H P – L E K – M2 – 01

Basic series
H = Standard construction
E = SIGMAX construction (n/a half stack)

Size
2 = NEMA 23
frame size (2.25" dia,)
3 = NEMA 34
frame size (3.38"dia.)
4 = NEMA 42
frame size (4.28" dia.)

Number of Rotor Stacks
H = Half stack (H series only)
1 = 1 stack
2 = 2 stacks
3 = 3 stacks (size 3,4 only)
4 = 4 stacks (size 3 only)

Mounting
N = NEMA (n/a 4 stacks)
H = Heavy duty NEMA
(opt. on 3 stacks, std. on 4 stacks)
S = Special, contact customer support

Construction/Connection Style
R = Regular/leadwire
C = System MS connector
L = Splashproof/to terminal board via conduit connector: 1/2" NPS pipe thread (size 3,4 only)
M = Splashproof/to terminal board via conduit connect: metric PG11 pipe thread (size 3,4 only)
S = Special, contact customer support

Number of Connections
F = 8 lead
L = 4 lead series
H = 4 lead parallel
E = 6 lead

Winding Type
T = Max, torque at low speed
P = Max. torque torque at high speed
A, B and C = Additional standards
S = Special, contact customer support

Special Sequence
00 = Standard motor without shaft seal
01 = Standard motor with shaft seal (size 3 and 4 only)
Other numbers will be assigned for special motors

Encoder Option
NS = No feedback
All options below require construction R or C
M1 = Encoder mounting provision (size 2 only). Requires shaft configuration E
HD = 500 LPR encoder (size 2 only)
HJ = 512 LPR encoder (size 2 only)
M2 = HP encoder mounting provision (size 3,4 only). Requires shaft configuration E
M3 = BEI encoder mounting provision (size 3,4 only). Requires shaft configuration D
SS = Special, contact customer support

Shaft Modifications
N = Smooth (size 2,3 only)
(mounting config. N only)
F = Flat (size 2,3 only)
(mounting config. N only)
K = Straight key (size 3,4 only)
(mounting config. H only)
W = #303 Woodruff key (size 3 only)
(mounting config. N only)
S = Special

Shaft Configuration (Diameter & Length)
N = Single
D = Double (R or C construction only)
E = Double ended for encoder (R or C construction only, size 3,4 only)
S = Special, contact customer support

Rotor Type
L = Laminated
J = Low inertia (size 2 only, n/a with half stack motors)

Note: Options shown in blue text are considered standard.

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

NEMA 34 K & N Series Stepper Motor

N 3 3 H C H J – L E K – M2 – 01

K and N series
N = Standard construction
K = Sigmax construction

Size
3 = NEMA 34 frame size;
3.38" width/height, square frame

Length
1 = 1 stack
2 = 2 stacks
3 = 3 stacks
4 = 4 stacks

Mounting
H = Heavy duty NEMA
S = Special, contact customer support

Construction/Connection Style
R = Regular/leadwire
C = System MS connector
L = splashproof/to terminal board via conduit connector: 1/2" NPSC pipe thread
M = Splashproof/to terminal board via conduit connect: metric PG11 pipe thread
S = Special, contact customer support

Number of Connections
F = 8 lead (n/a C construction)
L = 4 lead series
H = 4 lead parallel
E = 6 lead (n/a C construction)

Special Sequence
00 = Standard motor without shaft seal
01 = Standard motor with shaft seal
Other numbers will be assigned for special motors

Encoder Option
NS = No feedback
M2 = Encoder mounting provision (must use construction C or R and shaft configuration E)
PD = 500 LPR encoder
PF = 1000 LPR encoder
SS = Special, contact customer support

Shaft Modifications
K = Straight key
S = Special, contact customer support

Shaft Configuration (Diameter & Length)
N = Single
D = Double (R or C construction only)
E = Double ended for encoder (R or C construction only)

Rotor Type
L = Laminated

Winding Type
H = Standard, 1 stack only
D, E, G, J, K, L = Standard
M = Standard, N/A on 1 stack
S = Special, contact customer support

Note: Options shown in blue text are considered standard.

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

NEMA 42 K & N Series Stepper Motor

N 4 3 H C H J – L E K – M2 – 01

K and N series
N = Standard construction
K = Sigmax construction

Size
4 = NEMA 42 frame size;
4.325" width/height, square frame

Length
1 = 1 stack
2 = 2 stacks
3 = 3 stacks

Mounting
H = Heavy duty NEMA
S = Special, contact customer support

Construction/Connection Style
R = Regular/leadwire
C = System MS connector
L = splashproof/to terminal board via conduit connector: 1/2" NPSC pipe thread
M = Splashproof/to terminal board via conduit connect: metric PG13.5 pipe thread
S = Special, contact customer support

Number of Connections
F = 8 lead (n/a C construction)
L = 4 lead series
H = 4 lead parallel
E = 6 lead (n/a C construction)

Special Sequence
00 = Standard motor without shaft seal
01 = Standard motor with shaft seal
Other numbers will be assigned for special motors

Encoder Option
NS = No feedback
M2 = Encoder mounting provision (must use construction C or R and shaft configuration E)
PD = 500 LPR encoder
PF = 1000 LPR encoder
SS = Special, contact customer support

Shaft Modifications
K = Straight key
S = Special, contact customer support

Shaft Configuration (Diameter & Length)
N = Single
D = Double (R or C construction only)
E = Double ended for encoder (R or C construction only)
S = Special, contact customer support

Rotor Type
L = Laminated

Winding Type
J = Standard, 1 stack only
K, N = Standard, N/A on 1 stack
L = N/A on 1 stack
F, M, G = Standard
S = Special, contact customer support

Note: Options shown in blue text are considered standard.

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

M & P Series Stepper Motor

P 2 1 N R X A – L N N – N S – 00

Series
P = Standard
M = Enhanced (n/a half stack)

Size
2 = NEMA 23
(2.25" across flat)

Number of Stacks
H = Half stack
1 = 1 stack
2 = 2 stacks

Mounting
N = NEMA
S = Special, contact customer support

Construction
R = Regular
S = Special, contact customer support

Termination
X = Receptacle
F = 8 flying leads
S = Special, contact customer support
For X (receptacle) designation, Mating leaded connectors may be ordered seperately. Optional GRN/YEL ground wire available.

Winding Type
A, B, C, D
S = Special, contact customer support

Rotor Type
L = Standard
J = Low inertia (n/a half stack)

Shaft Configuration (Diameter & Length)
N = Single
D = Double
S = Special, contact customer support

Shaft Modifications
N = Smooth
F = Flat
S = Special, contact customer support

Encoder Option
NS = No Feedback
Use encoders below. You must specify shaft configuration D (double ended)
Caution: An encoder with line driver output may be required for use with some stepper motor controls.
M1 = Encoder mounting provisions
HD = Encoder 500 LPR
HJ = Encoder 512 LPR
SS = Special, contact customer support

Sequence Number
Insert 00 if all parts are standard.
Other numbers will be assigned for special motors.

Note: Options shown in blue text are considered standard.

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

MH172 Stepper Motor

MH 17 2 FD 8030 - _

MH Series

Frame Size
17 = 170 mm

Stack length
2 = double stack

Options
Omit for no options
E = Rear shaft extension
C2 = 200 line six output encoder
C2 = 200 line six output encoder
C4 = 400 line six output encoder
C5 = 500 line six output encoder

Identification Suffix

Lead Configuration/Mount
FD = 8 connections, round flange

MX Series Hazardous Duty Stepper Motor

MX 9 1 – F F – 206 U

MX Series
Meets UL Class1, Division1,
Group D requirements

Frame Size
9 = 90 mm
11 = 110mm

Number of Stacks
1 = 1 Stack
2 = 2 Stacks
3 = 3 Stacks

Rear Options
U = No shaft extension
EU = Shaft extension

Identification Suffix

Connection/Mount
FD
FF
FJ
See outline drawing for details

Note: Options shown in blue text are considered standard.

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

T2 Series Stepper Motor

T 2 3 N R H J – L N N – N – 00

T Series

Motor Frame Size
2 = NEMA 23 (2.25" square)

Rotor Stack Length
H = Half stack
1 = 1 stack
2 = 2 stacks
3 = 3 stacks

Mounting Configuration
N = NEMA 23
S = Special, contact factory

Construction / Hookup
C = MS connector
L = Terminal box via 1/2" NPT pipe thread
M = Terminal box via metric PG11 pipe thread
R = Regular - leadwire
S = Special, contact factory

Windings / Leads
E = 6 leads (Unipolar)[1]
H = 4 leads (Parallel connected)
L = 4 leads (Series connected)
S = Special, contact factory

Winding Type
D, E, F, G, H, J, K
S = Special, contact factory

Rotor Type
L = Laminated

Shaft Configuration
D = Rear shaf extension[2]
N = No rear shaft extension
S = Special, contact factory

Shaft Modifications
F = Flat
N = Smooth
S = Special, contact factory

Ecoder Option
C2 = Encoder 200 LPR w/line driver[3]
C4 = Encoder 400 LPR w/line driver[3]
C5 = Encoder 500 LPR w/line driver[3]
M4 = Encoder mtg. provisions[3]
NS = No Feedback
SS = Special, contact factory

Special Sequence
Insert 00 if all parts are standard. Any other numbers are factory assigned

Notes:
1. N/A with "C" Construction / Hookup option
2. "R" Construction / Hookup only, required for motors with encoders
3. Requires "R" Construction / Hookup option and "D" Shaft Configuration option

Note: Options in blue type refer to standard products.

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

KS Series AC Synchronous Motor

KS L 06 2 T1 Y _

KS Series

Termination
L = leaded
T = Terminal box

Frame Size
06 = NEMA size 23

Number of Stacks
1 = 1 stack
2 = 2 stacks
3 = 3 stacks

Options
E = Rear shaft
(omit for no options)

Frequency
W = 60 Hz
X = 50 Hz
Y = 50/60 Hz

Voltage
T1 = 120 Vac
T2 = 240 Vac

X Series AC Synchronous Motor

X 25 2 _

X Series
X = Meets UL Class 1, Group D requirements
X = Exd IIC T5 Gb requirements

Minimum Running Torque (oz-in)
24x = 240 oz-in
25x = 250 oz-in
45x = 450 oz-in
70x = 700 oz-in
110x = 1100 oz-in
150x = 1500 oz-in
180x = 1800 oz-in

Options
Contact customer support for option availability
Omit for no options

Voltage
0 or 1 = 120 Vac (model dependent)
2 = 240 Vac

Note: Options shown in blue text are considered standard.

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

SS Series AC Synchronous Motor

SS 24 1 L G60

SS Series

Minimum Running Torque (oz-in)

NEMA Size 23

25 = 25 oz-in
9x = 90 oz-in
13x = 130 oz-in

NEMA Size 24

5x = 50 oz-in
8x = 80 oz-in
24x = 240 oz-in
45x = 450 oz-in

NEMA Size 42

15xB = 150 oz-in
25xB = 250 oz-in
40xB = 400 oz-in
70xB = 700 oz-in

NEMA Size 66

180x = 1800 oz-in

Gearbox

GXX where XX = reducer ratio

Options

L = Leads
T = Terminal box
(blank) = connector on leads
C = Covered capacitor
CT = Capacitor in terminal box
E = Rear shaft extension

Voltage

0 or 1 = 120 Vac (model dependent)
Omit for 25 oz-in models (25 oz-in models are 120 Vac)
2 = 240 Vac

Note: Options shown in blue text are considered standard.

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

Micron™ TRUE Planetary™ Gearbox

NTR 115 – 005 – 0 – ( )

Gearbox Series

NT = NemaTRUE™
NTP = NemaTRUE PLUS™
NTR = NemaTRUE 90™
XT = XTRUE™
ET = EverTRUE™
DT = DuraTRUE™
DTR = DuraTRUE 90™
DTRS = DuraTRUE™ slimline
DTRH = DuraTRUE™ hollow shaft
DTRD = DuraTRUE™ dual shaft
VT = ValueTRUE™
VTR = ValueTRUE 90™
UT = UltraTRUE™
UTR = UltraTRUE 90™

Motor Model Number

RediMount number (if available)
or motor manufacturer and model number

Customer Options

0 = None
S = Special
H = High precision
(for NemaTRUE™ product line only)

Gearbox Ratio

See ratio availability in corresponding gearbox section (pp 109-113)

Gearbox Size

NemaTRUE™
NemaTRUE PLUS™
NemaTRUE 90™
17 = Size 17
23 = Size 23
34 = Size 34
42 = Size 42
60 = Size 60
90 = Size 90
115 = Size 115

XTRUE™
040 = Size 40
060 = Size 60
080 = Size 80
120 = Size 120
160 = Size 160

EverTRUE™
10 = Size 10
14 = Size 14
18 = Size 18

DuraTRUE™
DuraTRUE 90™
DuraTRUE™ Slimline
DuraTRUE™ Hollow Shaft
DuraTRUE™ Dual Shaft
60 = Size 60
90 = Size 90
115 = Size 115
142 = Size 142

ValueTRUE™
ValueTRUE 90™
006 = Size 60
075 = Size 75
090 = Size 90
010 = Size 10
115 = Size 115
014 = Size 14
018 = Size 18
022 = Size 22

UltraTRUE™
UltraTRUE 90™
006 = Size 60
075 = Size 75
090 = Size 90
010 = Size 10
115 = Size 115
014 = Size 14
018 = Size 18
022 = Size 22 (UltraTRUE™ only)

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

EC Series Electric Cylinder with AKM Servo Motors

EC Series	Motor Type	Motor Options	Drive Ratio	Screw Lead	Stroke Length	Cylinder Mounting	Rod Ends	Options	Cable Option
EC2	– AKM23D	– BNC	– 10	– 05B	– 300	– MP2	– FT1M	– ( )	– CO

EC Series

EC1
EC2
EC3
EC4
EC5

Motor Type

	Available
AKM11B = AKM11B-ANCNx-00 brushless servo	EC1
AKM13C = AKM13C-ANCNx-00 brushless servo	EC1
AKM23D = AKM23D-EFxxx-00 brushless servo	EC2, EC3
AKM23C = AKM23C-EFxxx-00 brushless servo	EC2, EC3
AKM42G = AKM42G-EKxxx-00 brushless servo	EC3, EC4, EC5
AKM42E = AKM42E-EKxxx-00 brushless servo	EC3, EC4, EC5
AKM52G = AKM52G-EKxxx-00 brushless servo	EC4, EC5
AKM52H = AKM52H-EKxxx-00 brushless servo	EC4, EC5
AKM52L = AKM52L-EKxxx-00 brushless servo	EC4, EC5

Motor Options

	Available
B xx = Rotatable IP65 connectors	AKM2
C xx = 0.5 m shielded cables w/ IP65 connectors	AKM1, AKM2
C xx = Rotatable IP65 connectors	AKM4, AKM5
x N x = No brake	AKM1, AKM2, AKM4, AKM5
x 2 x = 24 Vdc power-off holding brake	AKM2, AKM4, AKM5
xx R = Resolver	AKM1, AKM2, AKM4, AKM5
xx 2 = 2048 LPR incremental comm. encoder	AKM1, AKM2, AKM4, AKM5
xx C = Smart Feedback Device (SFD)	AKM1, AKM2, AKM4, AKM5

Drive Ratio

	Available
10 = 1.0:1 drive belt/pulley (EC1 – helical)	All
10L = 1.0:1 inline coupling (direct 1:1 coupling is the only ratio available for inline models)	All
15 = 1.5:1 drive belt/pulley	EC2, EC3, EC4, EC5
20 = 2.0:1 drive belt/pulley (EC1 – helical)	Not valid for EC3-AKM42
40 = 4.0:1 helical gears	EC1 only
50 = 5.0:1 helical gears	EC2, EC3, EC4, EC5
70 = 7.1:1 helical gears	EC3 only
100 = 10.0:1 helical gears	EC2, EC4, EC5

Screw Lead

	Available
03M = 3 mm/rev ballscrew	EC1
05B = 5 mm/rev ballscrew	EC2, EC3
10B = 10 mm/rev ballscrew	EC3, EC4, EC5
16B = 16 mm/rev ballscrew	EC2, EC3
25B = 25 mm/rev ballscrew	EC4
32B = 32 mm/rev ballscrew	EC5
04A = 4 mm/rev lead screw	EC2, EC3

Stroke Length

	Available
50 = 50 mm total stroke	All
100 = 100 mm total stroke	All
150 = 150 mm total stroke	All
200 = 200 mm total stroke	All
250 = 250 mm total stroke	EC2, EC3, EC4, EC5
300 = 300 mm total stroke	EC2, EC3, EC4, EC5
450 = 450 mm total stroke	EC2, EC3, EC4, EC5
600 = 600 mm total stroke	EC2, EC3, EC4, EC5
750 = 700 mm total stroke	EC2, EC3, EC4, EC5
1000 = 1,000 mm total stroke	EC3, EC4, EC5
1250 = 1,250 mm total stroke	EC4, EC5
1500 = 1,500 mm total stroke	EC4, EC5
nnn = Custom stroke lengths available in 10 mm increments	

Cylinder Mounting

	Available
MF1 = Front rectangular flange	EC1, EC2, EC3, EC5
MF1E = Front rectangular flange (English)	EC4 only
MF1M = Front rectangular flange (metric)	EC4 only
MF2 = Rear rectangular flange	EC2, EC3, EC5
MF2E = Rear rectangular flange (English)	EC4 only
MF2M = Rear rectangular flange (metric)	EC4 only
MF3 = Front & rear rectangular flange	EC2, EC3, EC5
MF3E = Front & rear rectangular flange	EC4 only
MF3M = Front & rear rectangular flange	EC4 only
MP2 = Rear double clevis without pivot base	All
MP3 = Rear double clevis with pivot base	All
MS1 = Side end angle	EC2, EC3
MS2 = Side lugs	All
MS6M = Side tapped holes (metric)	All
MS6E = Side tapped holes (English)	EC2, EC3, EC4, EC5
MT4 = Trunnion	EC2, EC3, EC4, EC5

Rod Ends

	Available
FC2 = Clevis (includes MT1M)	All
FS2 = Spherical joint (includes FT1M)	All
FT1M = Female thread (metric)	All
FT1E = Female thread (English)	EC2, EC3, EC4, EC5
MT1M = Male thread (metric)	All
MT1E = Male thread (English)	EC2, EC3, EC4, EC5

Options

(add multiple in the following sequence, omit if no options)

BA24 = 24 Vdc brake on actuator (EC1 only, not available with 10L ratio or MS1 mounting options)
BS24 = 24 Vdc brake on ballscrew (not available with EC1 or 10L ratio, or with MF2(x), MF3(x), MS1, MP2(x), MP3(x) mounting options)
BS115 = 115 Vac brake on ballscrew (not available with EC1 or 10L ratio, or with MF2(x), MF3(x), MS1, MP2(x), MP3(x) mounting options)
PB = Protective boot*
L = Linear potentiometer (only valid through 600 mm stroke, standard lengths)*
17X = NEMA 17 mountless motor (EC1 only)

Cable

CO = No cable supplies, motor includes connectors.
Default for all AKM Servo Motors; select cable as an accessory.
*Contact customer service for EC1

Note: Options shown in blue text are considered standard.

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

N2 Series Electric Cylinder with AKM Servo Motors

N2 – AKM23D – BNC – 15 – 5B – 8 – MP2 – FT1M – ( ) – CO

N2 Series

Motor Type*

AKM23D = AKM23D-EFxxx-00 brushless servo
AKM23C = AKM23C-EFxxx-00 brushless servo

Motor Options

B xx = Rotatable IP65 connectors
C xx = 0.5 m shielded cables w/ IP65 connectors
x N x = No brake
x 2 x = 24 Vdc power-off holding brake
xx R = Resolver
xx 2 = 2048 LPR incremental comm. encoder
xx C = Smart Feedback Device (SFD)

Drive Ratio

10 = 1.0:1 drive belt/pulley
10L = 1.0:1 inline coupling (direct 1:1 coupling is the only ratio available for inline models)
15 = 1.5:1 drive belt/pulley
20 = 2.0:1 drive belt/pulley
25 = 2.5:1 helical gears

Screw Pitch, Type

2B = 2 rev/inch ballscrew
5B = 5 rev/inch ballscrew
5A = 5 rev/inch lead screw
8A = 8 rev/inch lead screw

Stroke Length**

2 = 2 inch total stroke
4 = 4 inch total stroke
6 = 6 inch total stroke
8 = 8 inch total stroke
12 = 12 inch total stroke
18 = 18 inch total stroke (requires -DB option, effective stroke is 16.5")
24 = 24 inch total stroke (requires -DB option, effective stroke is 22.5")
nn.n = Custom stroke lengths available in 0.1 inch increments

Cylinder Mounting

MF1 = Front rectangular flange
MF2 = Rear rectangular flange
MF3 = Front & rear rectangular flange
MP2 = Rear double clevis without pivot base
MP3 = Rear double clevis with pivot base
MS1 = Side end angle
MS2 = Side lugs
MS6M = Side tapped holes (metric)
MS6E = Side tapped holes (English)
MT4 = Trunion

Rod Ends

FC2 = Clevis (includes MT1M)
FE2 = Female eye rod end
FS2 = Spherical joint (includes FT1M)
FT1M = Female thread (metric)
FT1E = Female thread (English)
MT1M = Male thread (metric)
MT1E = Male thread (English)

Options***

(add multiple in the following sequence, omit if no option required)

BS24 = 24 Vdc brake on lead screw (not available with 10L ratio, or with MF2, MF3, MS2, MP2, MP3 mounting options)
DB = Dual rod end bearing
PB = Protective boot
W = Water resistant
F = Sub-freezing temperature
H = High temperature prep
L = Linear potentiometer (only for valid std. lengths)

Cable

CO = No cable supplied, motor includes connectors. Default for all AKM servo motors; select Kollmorgen cables based on motor/drive pairings.

* Contact customer support for AKM combinations outside of those listed.
** For custom lengths round up to next standard incremental plus add standard cut fee.
*** Contact customer support for non-standard pricing and lead times.
Note: Options shown in blue text are considered standard.

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

Rodless Actuators R-Series with AKM Servo Motors

R Series	Motor Type*	Motor Options	Drive Ratio	Linear Drive Type	Stroke Length	Motor Orientation	Mounting Style	Carriage	English/ Metric	Cable Option
R3	– AKM42G	CNC	– 10	5B	– 12	– P	– A	S	E	– C0

R Series

R2A, R3, R4

Motor Type*

	Available
AKM23C = AKM23C-EFxxx-00 brushless servo	R2A, R3
AKM23D = AKM23D-EFxxx-00 brushless servo	R2A, R3
AKM42E = AKM42E-EKxxx-00 brushless servo	R3, R4
AKM42G = AKM42G-EKxxx-00 brushless servo	R3, R4
AKM52G = AKM52G-EKxxx-00 brushless servo	R4
AKM52H = AKM52H-EKxxx-00 brushless servo	R4

Motor Options

	Available
B■■ = Rotatable IP65 connectors	AKM2
C■■ = 0.5 m shielded cables w/ IP65 connectors	AKM2
C■■ = Rotatable IP65 connectors	AKM4, AKM5
■N■ = No brake	AKM2, AKM4, AKM5
■2■ = 24 Vdc power-off holding brake	AKM2, AKM4, AKM5
■■R = Resolver	AKM2, AKM4, AKM5
■■2 = 2048 LPR incremental comm. encoder	AKM2, AKM4, AKM5
■■C = Smart Feedback Device (SFD)	AKM2, AKM4, AKM5

Drive Ratio

	Available
10 = 1.0:1 drive belt/pulley	R2A, R3, R4
15 = 1.5:1 drive belt/pulley	R2A, R3, R4
20 = 2.0:1 drive belt/pulley	R2A, R3, R4
30 = 3.0:1 drive belt/pulley	R4
50 = 5:1 helical gear	R3, R4
70 = 7:1 helical gear	R3
100 = 10:1 helical gear	R3

Linear Drive Type

	Available
5A = 5 pitch (0.2" lead) lead screw	R2A, R3
8A = 8 pitch (0.125" lead) lead screw	R2A, R3
1B = 1 pitch (1" lead) ball screw	R4
2B = 2 pitch (0.5" lead) ball screw	R2A, R3
4B = 4 pitch (0.25" lead) ball screw	R4
5B = 5 pitch (0.2" lead) ball screw	R2A, R3
T = Tangential drive belt	R2A, R3, R4

Stroke Length**

	Available
6 = 6" of total stroke	R2A, R3, R4
12 = 12" of total stroke	R2A, R3, R4
18 = 18" of total stroke	R2A, R3, R4
24 = 24" of total stroke	R2A, R3, R4
30 = 30" of total stroke	R2A, R3, R4
36 = 36" of total stroke	R2A, R3, R4
42 = 42" of total stroke	R2A, R3, R4
48 = 48" of total stroke	R2A, R3, R4
54 = 54" of total stroke	R2A, R3, R4
60 = 60" of total stroke	R2A, R3, R4
66 = 66" of total stroke	R2A, R3, R4
72 = 72" of total stroke	R2A, R3, R4
84 = 84" of total stroke	R3, R4
96 = 96" of total stroke	R3, R4
108 = 108" of total stroke	R3, R4

Custom lengths available in the increment of 1"

Options***

	Available
BS24 = 24 Vdc brake on lead screw (Screw option only, n/a with inline models, MF3 or "C" options)	R2A, R3, R4
BS115 = 115 Vdc brake on lead screw (Screw option only, n/a with inline models, MF3 or "C" options)	R2A, R3, R4
BS230 = 230 Vdc brake on lead screw (Screw option only, n/a with inline models, MF3 or "C" options)	R2A, R3, R4
WR = Water resistant seal option right	R2A
WL = Water resistant seal option left	R2A
GR = Lube port, right side	R3, R4
GL = Lube port, left side	R3, R4
DC1 = Idler carriage between driven carriage and non-motor end	R2A
DC2 = Idler carriage between driven carriage and motor end	R2A
VR = Breather vent, fitting, tubing, right side	R4
VL = Breather vent, fitting, tubing, left side	R4
C0 = No motor cable	R2A, R3, R4
S = Stub shaft	R2A

English/Metric (carriage/mounting)

	Available
E = English carriage & mounting dimensions	R2A, R3, R4
M = Metric carriage & mounting dimensions	R2A, R3, R4

Carriage (omit this field for R2A models)

	Available
S = Single carriage	R3, R4
Dxx = Dual carriage (xx = center distance between dual carriages in inches – contact customer support for lengths)	R3, R4

Mounting Style

	Available
MF3 = Front & rear rectangular flanges	R2A
MS1 = Side end angles	R2A
MS5 = Adjustable feet	R2A
MS6 = Side tapped mounting holes	R2A
A = Side angle brackets	R3, R4
B = Adjustable T-nuts	R3, R4
C = Front & rear rectangular flanges	R3, R4

Motor Orientation

	Available
Belt options	
AR = Motor housing rotated above/right	R2A, R3, R4
BR = Motor housing rotated behind/right	R2A, R3, R4
CR = Motor housing rotated under/right	R2A, R3, R4
AL = Motor housing rotated above/left	R2A, R3, R4
BL = Motor housing rotated behind/left	R2A, R3, R4
CL = Motor housing rotated under/left	R2A, R3, R4
Screw options	
I = Motor mounted inline	R2A, R3, R4
P = Motor mounted parallel	R2A, R3, R4
PR = Motor mounted parallel/right	R2A, R3, R4
PL = Motor mounted parallel/left	R2A, R3, R4

* Contact customer support for AKM combinations outside of those listed.
** For custom lengths round up to next standard incremental plus add standard cut fee.
*** Contact customer support if C0 is not selected.

Note: Options shown in blue text are considered standard.

Model Nomenclature

Please use the part scheme for product identification only and not ordering.
Not all combnations of features are always possible.

DS Series Precision Table

DS Series	Stroke Length	Grade	Ballscrew Lead	Motor Type*	Motor Options	Motor Mounts	Couplings	Motor Orient.	Limit Sensors	Home Switch	Shaft End Opt.	Linear Encoder	Options
DS4	– 250	– C	– 5G	– AKM23D	– BNC	(-)	– OE6	– PR6E	– LN1	– H0	(-)	– E0	– CLN

DS Series

DS4
DS6

Stroke Length

50 = 50 mm total stroke	DS4 only
100 = 100 mm total stroke	
150 = 150 mm total stroke	DS4 only
200 = 200 mm total stroke	
250 = 250 mm total stroke	DS4 only
300 = 300 mm total stroke	
350 = 350 mm total stroke	DS4 only
400 = 400 mm total stroke	
450 = 450 mm total stroke	DS4 only
500 = 500 mm total stroke	
550 = 550 mm total stroke	DS4 only
600 = 600 mm total stroke	
700 = 700 mm total stroke	DS6 only
800 = 800 mm total stroke	DS6 only
900 = 900 mm total stroke	DS6 only
1000 = 1000 mm total stroke	DS6 only
1250 = 1250 mm total stroke	DS6 only
1500 = 1500 mm total stroke	DS6 only
1750 = 1750 mm total stroke	DS6 only
2000 = 2000 mm total stroke	DS6 only

Grade

C = Commercial grade
P = Precision grade**

Ballscrew Lead

5G = 5 mm/rev	
10G = 10 mm/rev	
25G = 25 mm/rev (≥ 700 mm)	DS6 only

Motor Type*

AKM23C = AKM23C-EFxxx-00 brushless servo	
AKM23D = AKM23D-EFxxx-00 brushless servo	
AKM42E = AKM42E-EKxxx-00 brushless servo	DS6 only
AKM42G = AKM42G-EKxxx-00 brushless servo	DS6 only

Motor Options*

B■■ = Rotatable IP65 connectors	
C■■ = 0.5 m shielded cables w/ IP65 connectors	AKM2 only
C■■ = Rotatable IP65 connectors	AKM2 only
■N■ = No brake	AKM4, AKM5 only
■2■ = 24 Vdc power-off holding brake	
■■R = Resolver	
■■2 = 2048 LPR incremental comm. encoder	
■■C = Smart Feedback Device (SFD)	
■■DA = Single-turn absolute sine encoder, EnDat2.2, 01	
■■DB = Multi-turn absolute sine encoder, EnDat2.2, 01	

Additional Options

P1 = Standard pinning of x-axis carriage
CLN = Cleanroom prep – class 100
Omit for no additional options

Linear Encoder

E0 = No linear encoder
E1 = 1.0 micron resolution
E2 = 0.5 micron resolution
E3 = 0.1 micron resolution

Shaft End Options

BS = Brake on ballscrew, 24 Vdc power-off
ES = Rotary encoder on ballscrew, 1250 line
Omit for no additional options

Home Switch

H0 = No home sensor
HN1 = Home, NPN type normal open
HN2 = Home, NPN type normal closed
HP1 = Home, PNP type normal open
HP2 = Home, PNP type normal closed

Limit Sensors

L0 = No end-of-travel limits
LN1 = Limits, NPN type normal open
LN2 = Limits, NPN type normal closed
LP1 = Limits, PNP type normal open
LP2 = Limits, PNP type normal closed

Motor Orientation & Pulley Bore (Parallel Models)

PR6E = Parallel right
PL6E = Parallel left
PU6E = Parallel under
Omit if parallel model is not preffered

Couplings (Inline Models)

OE6 = Oldham style, 3/8" bore (AKM2X)	
OE8 = Oldham style, 1/2" bore (AKM4X)	DS6 only
BE6 = Bellows style, 3/8" bore (AKM2X)	
BE8 = Bellows style, 1/2" bore (AKM4X)	DS6 only

Omit for parallel models

Motor Mounts

X23 = NEMA 23 mount	
X34 = NEMA 34 mount	DS6 only

Omit if motor option is used

* Contact customer support for AKM combinations outside of those listed.
** Extended lead time required.
Note 1: Options shown in blue text are considered standard.
Note 2: Contact customer support for price and lead time on all non-standard features.

Kollmorgen Solutions

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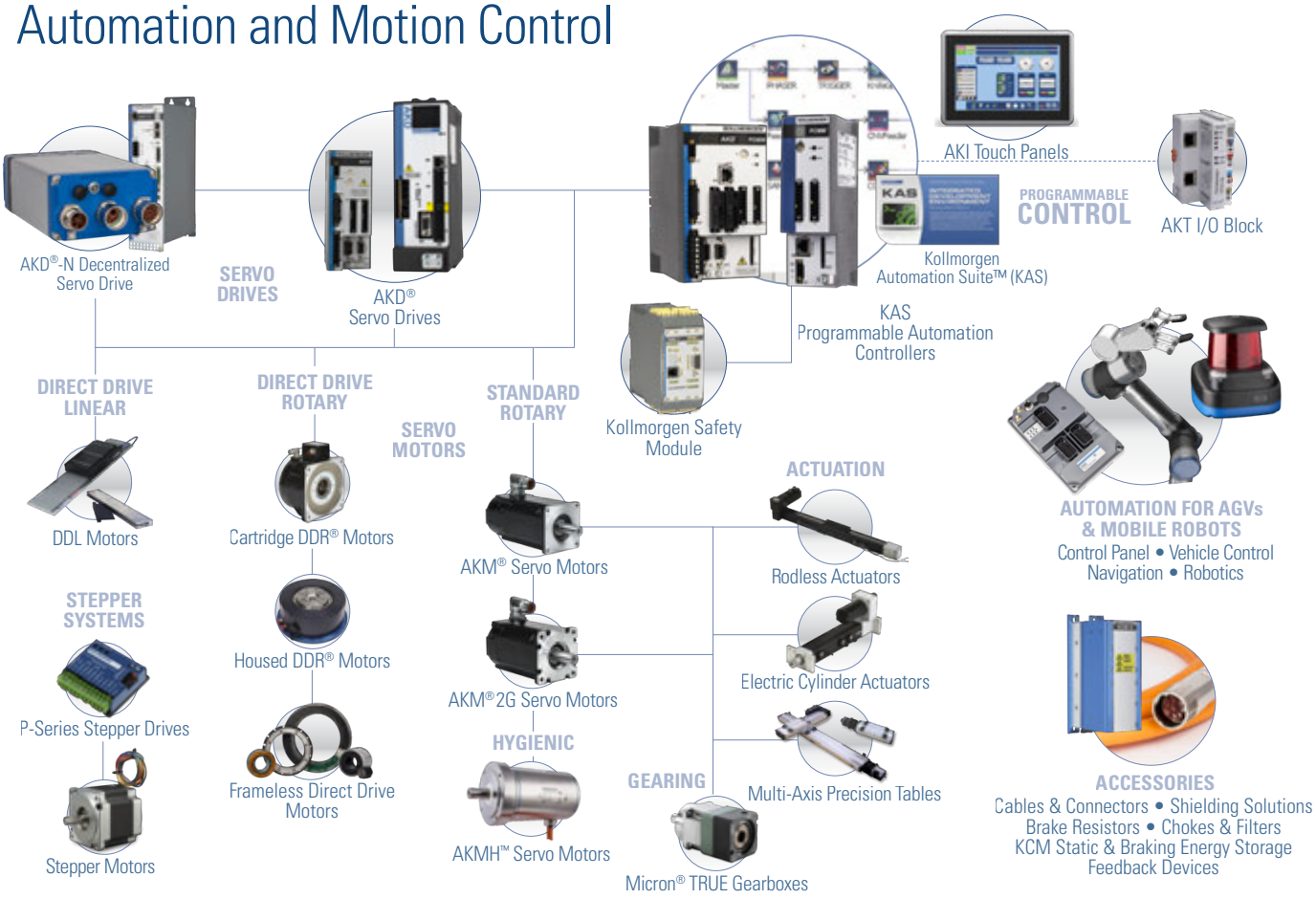

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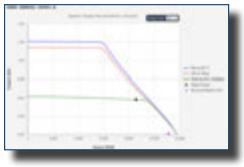

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Since its founding in 1916, Kollmorgen's innovative solutions have brought big ideas to life, kept the world safer, and improved peoples' lives. Today, its world-class knowledge of motion systems and components, industry-leading quality, and deep expertise in linking and integrating standard and custom products continually delivers breakthrough motion solutions that are unmatched in performance, reliability, and ease-of-use. This gives machine builders around the world an irrefutable marketplace advantage and provides their customers with ultimate peace-of-mind.

For assistance with your application needs in North America, contact us at: 540-633-3545, support@kollmorgen.com or visit www.kollmorgen.com for a global contact list.

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